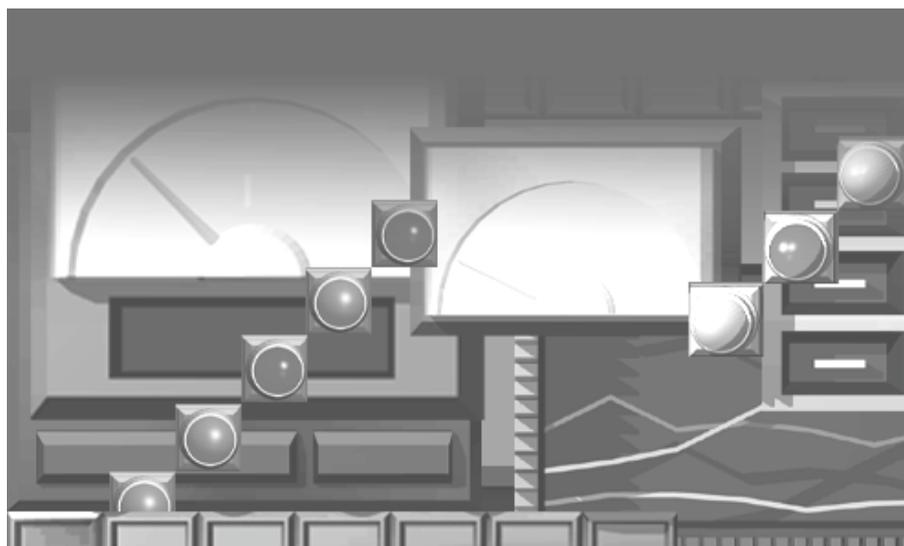


GOT-A900 Series User's Manual

(SW4D5C-GOTR-PACKE compatible Connection System Manual)



Graphic Operation Terminal
900
series



• SAFETY PRECAUTIONS •

(Always read these instructions before using this equipment.)

Before using this product, please read this manual and the relevant manuals introduced in this manual carefully and pay full attention to safety to handle the product correctly.

The instructions given in this manual are concerned with this product. For the safety instructions of the programmable controller system, please read the CPU module user's manual.

In this manual, the safety instructions are ranked as "DANGER" and "CAUTION".



DANGER

Indicates that incorrect handling may cause hazardous conditions, resulting in death or severe injury.



CAUTION

Indicates that incorrect handling may cause hazardous conditions, resulting in medium or slight personal injury or physical damage.

Note that the  CAUTION level may lead to a serious consequence according to the circumstances. Always follow the instructions of both levels because they are important to personal safety.

Please save this manual to make it accessible when required and always forward it to the end user.

[Design Instructions]



DANGER

- Some failures of the GOT main unit, communication module, communication board or cable may keep the outputs on or off.
An external monitoring circuit should be provided to check for output signals which may lead to a serious accident.
Not doing so can cause an accident due to false output or malfunction.
- If a communication fault (including cable disconnection) occurs during monitoring on the GOT, communication between the GOT and PLC CPU is suspended and the GOT becomes inoperative.
For bus connection : The CPU becomes faulty and the GOT inoperative.
For other than bus connection : The GOT becomes inoperative.
A system where the GOT is used should be configured to perform any significant operation to the system by using the switches of a device other than the GOT on the assumption that a GOT communication fault will occur.
Not doing so can cause an accident due to false output or malfunction.



CAUTION

- Do not bundle the control and communication cables with main-circuit, power or other wiring.
Run the above cables separately from such wiring and keep them a minimum of 100mm apart.
Not doing so noise can cause a malfunction.

[Mounting Instructions]

DANGER

- Before installing or removing the GOT main unit to or from an enclosure, always switch off the GOT power externally in all phases.
Not doing so can cause a module failure or malfunction.
- Before installing or removing the communication board, communication module, memory board, external I/O interface unit, or memory card interface unit, be sure to switch off the GOT power externally in all phases.
Not doing so can cause a module failure or malfunction.

CAUTION

- The GOT should be used in the environment given in the general specifications of the GOT user's manual.
Not doing so can cause an electric shock, fire, malfunction or product damage or deterioration.
- When mounting the GOT main unit to an enclosure, tighten the mounting screws in the specified torque range.
Undertightening can cause a drop, short circuit or malfunction.
Overtightening can cause a drop, short circuit or malfunction due to the damage of the screws or module.
- When loading the communication board or communication module to the GOT main unit, fit it to the connection interface of the GOT and tighten the mounting screws in the specified torque range.
Undertightening can cause a drop, failure or malfunction.
Overtightening can cause a drop, failure or malfunction due to the damage of the screws or module.
- When loading the memory board into the GOT main unit, load it into its corresponding GOT slot and tighten the mounting screws in the specified torque range.
Undertightening can cause a malfunction due to a contact fault.
Overtightening can cause a malfunction due to the damage of the screws or module.
- When loading the PC card into the GOT main unit, insert and push it into its corresponding GOT slot until the PC card eject button comes up.
Not doing so can cause a malfunction due to a contact fault.
- Before loading or unloading the PC card to or from the GOT, set the memory card access switch to the OFF position.
Not doing so can cause the PC card data to be corrupted.

[Wiring Instructions]

DANGER

- Before starting wiring, always switch off the GOT power externally in all phases.
Not doing so may cause an electric shock, product damage or malfunction.

CAUTION

- Always earth the FG, LG and earth terminals of the GOT power supply section to the protective earth conductor.
Not doing so may cause an electric shock or malfunction.
- Correctly wire the power supply module on the GOT after confirming the rated voltage and terminal arrangement of the product.
Not doing so can cause a fire or failure.
- Tighten the terminal screws of the GOT power supply section in the specified torque range.
Undertightening can cause a short circuit or malfunction.
Overtightening can cause a short circuit or malfunction due to the damage of the screws or module.
- Exercise care to avoid foreign matter such as chips and wire offcuts entering the module.
Not doing so can cause a fire, failure or malfunction.
- Plug the bus connection cable by inserting it into the connector of the connected module until it "clicks".
After plugging, check that it has been inserted snugly.
Not doing so can cause a malfunction due to a contact fault.
- Plug the communication cable into the connector of the connected module and tighten the mounting and terminal screws in the specified torque range.
Undertightening can cause a short circuit or malfunction.
Overtightening can cause a short circuit or malfunction due to the damage of the screws or module.

[Test Operation Instructions]

DANGER

- Before performing test operation (bit device on/off, word device's present value changing, timer/counter's set value and present value changing, buffer memory's present value changing) for a user-created monitor screen, system monitoring, special module monitoring or ladder monitoring, read the manual carefully to fully understand how to operate the equipment.
During test operation, never change the data of the devices which are used to perform significant operation for the system.
False output or malfunction can cause an accident.

[Startup/Maintenance Instructions]

 DANGER

- When power is on, do not touch the terminals.
Doing so can cause an electric shock or malfunction.
- Do not change the extension stage setting switch or the I/O slot setting switch.
Doing so can cause malfunction.
- Before starting cleaning or terminal screw retightening, always switch off the power externally in all phases.
Not switching the power off in all phases can cause a module failure or malfunction.
Undertightening can cause a short circuit or malfunction.
Overtightening can cause a short circuit or malfunction due to the damage of the screws or module.

 CAUTION

- Do not disassemble or modify the module.
Doing so can cause a failure, malfunction, injury or fire.
- Do not touch the conductive and electronic parts of the module directly.
Doing so can cause a module malfunction or failure.
- The cables connected to the module must be run in ducts or clamped.
Not doing so can cause the module or cable to be damaged due to the dangling, motion or accidental pulling of the cables or can cause a malfunction due to a cable connection fault.
- When unplugging the cable connected to the module, do not hold and pull the cable portion.
Doing so can cause the module or cable to be damaged or can cause a malfunction due to a cable connection fault.

[Disposal Instructions]

 CAUTION

- When disposing of the product, handle it as industrial waste.

Revisions

*The manual number is given on the bottom left of the back cover.

Print Date	*Manual Number	Revision
Jan.,2000	SH(NA)-080070-A	First edition
May.,2000	SH(NA)-080070-B	Partial additions Section 3.1, 4.1.3, 14.4, 15.1.1, 15.1.2, 15.1.3, 15.1.4, 15.1.6

This manual confers no industrial property rights or any rights of any other kind, nor does it confer any patent licenses. Mitsubishi Electric Corporation cannot be held responsible for any problems involving industrial property rights which may occur as a result of using the contents noted in this manual.

INTRODUCTION

Thank you for choosing the Mitsubishi Graphic Operation Terminal.

Before using the equipment, please read this manual carefully to use the equipment to its optimum.

Please forward a copy of this manual to the end user.

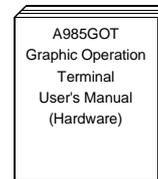
Whereabouts and Usage of This Manual

The manuals relating to SW4D5C-GOTR-PACKE are available in the following types.

The manuals are classified according to their purposes. Please read the proper manuals to understand the handling, operation and functions of the GOT unit and SW4D5C-GOTR-PACKE.

[A985GOT Graphic Operation Terminal User's Manual(Hardware)]

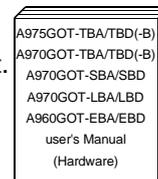
- To know the features of A985GOT unit.
- To confirm the specifications of A985GOT unit.
- To know the part names of A985GOT unit.
- To know how to install and wire A985GOT unit.
- To know the outline dimension drawing of A985GOT unit.



Found in the packing of the A985GOT unit.

[A975GOT-TBA/TBD(-B), A970GOT-TBA/TBD(-B), A970GOT-SBA/SBD, A970GOT-LBA/LBD, A960GOT-EBA/EBD User's Manual(Hardware)]

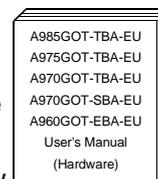
- To know the features of A975GOT/A970GOT/A960GOT unit.
- To confirm the specifications of A975GOT/A970GOT/A960GOT unit.
- To know the part names of A975GOT/A970GOT/A960GOT unit.
- To know how to install and wire A975GOT/A970GOT/A960GOT unit.
- To know the outline dimension drawing of A975GOT/A970GOT/A960GOT unit.



Found in the packing of the A975GOT/A970GOT/A960GOT unit.

[A985GOT-TBA-EU, A975GOT-TBA-EU, A970GOT-TBA-EU, A970GOT-SBA-EU, A960GOT-EBA-EU User's Manual(Hardware)]

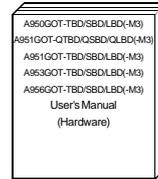
- To know the features of the GOT-A900 series EMC directive Low voltage directive compliant unit.
- To confirm the specifications of the GOT-A900 series EMC directive Low voltage directive compliant unit.
- To know the part names of the GOT-A900 series EMC directive Low voltage directive compliant unit.
- To know how to install and wire the GOT-A900 series EMC directive Low voltage directive compliant unit.
- To know the outline dimension drawing of the GOT-A900 series EMC directive Low voltage directive compliant unit.



Found in the packing of the A985GOT-TBA-EU, A975GOT-TBA-EU, A970GOT-TBA-EU, A970GOT-SBA-EU, A960GOT-EBA-EU unit.

[A950GOT-TBD/SBD/LBD (-M3), A951GOT-QTBD/QSBD/QLBD (-M3), A951GOT-TBD/SBD/LBD (-M3), A953GOT-TBD/SBD/LBD (-M3), A956GOT-TBD/SBD/LBD (-M3) User's Manual(Hardware)]

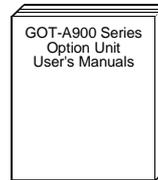
- To know the features of A950GOT/A951GOT/A953GOT/A956GOT unit.
- To confirm the specifications of A950GOT/A951GOT/A953GOT/A956GOT unit.
- To know the part names of A950GOT/A951GOT/A953GOT/A956GOT unit.
- To know how to install and wire A950GOT/A951GOT/A953GOT/A956GOT unit.
- To know the outline dimension drawing of A950GOT/A951GOT/A953GOT/A956GOT unit.



Found in the packing of the A950GOT/A951GOT/A953GOT/A956GOT unit.

[GOT-A900 Series Option Unit User's Manuals]

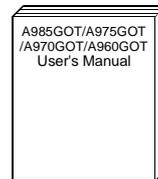
- To know the features of the corresponding GOT-A900 series option unit.
- To confirm the specifications of the corresponding GOT-A900 series option unit.
- To know the part names of the corresponding GOT-A900 series option unit.
- To know the outline dimension drawing of the corresponding GOT-A900 series option unit.



Found in the packing of the corresponding GOT-A900 series option unit.

[A985GOT/ A975GOT/ A970GOT/ A960GOT User's Manual]

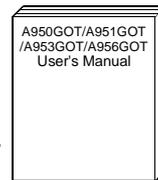
- To know the features of A985GOT/ A975GOT/ A970GOT/ A960GOT unit.
- To confirm the component devices of A985GOT/ A975GOT/ A970GOT/ A960GOT unit.
- To confirm the specifications of A985GOT/ A975GOT/ A970GOT/ A960GOT unit.
- To know the part names of A985GOT/ A975GOT/ A970GOT/ A960GOT unit.
- To fit various units to A985GOT/ A975GOT/ A970GOT/ A960GOT unit.
- To know how to install and wire A985GOT/ A975GOT/ A970GOT/ A960GOT unit.
- To know how to maintain and inspect A985GOT/ A975GOT/ A970GOT/ A960GOT unit.
- To confirm the error codes of A985GOT/ A975GOT/ A970GOT/ A960GOT unit.
- To know the outline dimension drawing of A985GOT/ A975GOT/ A970GOT/ A960GOT unit.



Available as an option.

[A950GOT/ A951GOT/ A953GOT/ A956GOT User's Manual]

- To know the features of A950GOT/ A951GOT/ 953GOT/ A956GOT unit.
- To confirm the component devices of A950GOT/ A951GOT/ 953GOT/ A956GOT unit.
- To confirm the specifications of A950GOT/ A951GOT/ 953GOT/ A956GOT unit.
- To know the part names of A950GOT/ A951GOT/ 953GOT/ A956GOT unit.
- To fit various units to A950GOT/ A951GOT/ 953GOT/ A956GOT unit.
- To know how to install and wire A950GOT/ A951GOT/ 953GOT/ A956GOT unit.
- To know how to maintain and inspect A950GOT/ A951GOT/ 953GOT/ A956GOT unit.
- To confirm the error codes of A950GOT/ A951GOT/ 953GOT/ A956GOT unit.
- To know the outline dimension drawing of A950GOT/ A951GOT/ 953GOT/ A956GOT unit.



Available as an option.

[GOT-A900 Series User's Manual(SW4D5C-GOTR-PACKE compatible Connection System Manual)]

- To know the connection forms available for the GOT-A900 series.
- To confirm the specifications of each connection form.
- To know the system configuration of each connection form.
- To know how to set the unit used.
- To confirm the connection diagrams of the connection cables.

SW4D5C-GOTR-PACKE



Contained in the SW4D5C-GOTR-PACKE as PDF data.

* The printed matter is also available as an option.

[SW4D5C-GOTR-PACKE(V) Operating Manual]

- To install the software into the personal computer.
- To start each software.
- To know how to connect the personal computer and GOT.
- To know the screen makeup of the software.
- To grasp the outline of various monitoring functions.
- To know the procedure of displaying the monitor screen.
- To know how to use the help function.



Found in the packing of SW4D5C-GOTR-PACKE.

* Contained also in the SW4D5C-GOTR-PACKE as PDF data.

[SW4D5C-GOTR-PACKE Help Functions]

- To confirm how to operate each software of SW4D5C-GOTR-PACKE.
- To confirm how to set various object functions.

SW4D5C-GOTR-PACKE



Incorporated in each software of SW4D5C-GOTR-PACKE

[GOT-A900 Series Operating Manual (SW4D5C-GOTR-PACKE compatible Extended • Option Functions Manual)]

- To perform the utility function.
- To perform the system monitoring function.
- To perform the ladder monitoring function.
- To perform the special function unit monitoring function.
- To perform the network monitoring function.
- To perform the list editor function.

SW4D5C-GOTR-PACKE



Contained in the SW4D5C-GOTR-PACKE as PDF data.

* The printed matter is also available as an option.

[GOT Operations Guide]

- To learn the sequence of operations by creating a simple screen using the drawing software (the screen displays of the drawing software introduced in the GOT Operations Guide are partly different from those of SW4D5C-GOTR-PACKE).

GOT Operations Guide



Contained in the GOT Operations Guide.

Abbreviations, generic terms and special terms used in this manual

Abbreviations, generic terms and special terms used in this manual are described as follows:

Abbreviations, generic terms and special terms	Description
A985GOT	Generic term of A985GOT-TBA, A985GOT-TBD and A985GOT-TBA-EU
A975GOT	Generic term of A975GOT-TBA-B, A975GOT-TBD-B, A975GOT-TBA, A975GOT-TBD and A975GOT-TBA-EU
A970GOT	Generic term of A970GOT-TBA-B A970GOT-TBD-B, A970GOT-TBA, A970GOT-TBD, A970GOT-SBA, A970GOT-SBD, A970GOT-LBA, A970GOT-LBD, A970GOT-TBA-EU and A970GOT-SBA-EU
A97*GOT	Generic term of A975GOT and A970GOT
A960GOT	Generic term of A960GOT-EBA, A960GOT-EBD and A960GOT-EBA-EU
A956GOT	Generic term of A956GOT-TBD, A956GOT-SBD, A956GOT-LBD, A956GOT-TBD-M3, A956GOT-SBD-M3 and A956GOT-LBD-M3
A953GOT	Generic term of A953GOT-TBD, A953GOT-SBD, A953GOT-LBD, A953GOT-TBD-M3, A953GOT-SBD-M3 and A953GOT-LBD-M3
A951GOT	Generic term of A951GOT-TBD, A951GOT-SBD, A951GOT-LBD, A951GOT-TBD-M3, A951GOT-SBD-M3 and A951GOT-LBD-M3
A951GOT-Q	Generic term of A951GOT-QTBD, A951GOT-QSBD, A951GOT-QLBD, A951GOT-QTBD-M3, A951GOT-QSBD-M3 and A951GOT-QLBD-M3
A950GOT	Generic term of A950GOT-TBD, A950GOT-SBD, A950GOT-LBD, A950GOT-TBD-M3, A950GOT-SBD-M3 and A950GOT-LBD-M3
A950 handy GOT	Generic term of A953GOT-SBD-M3-H and A953GOT-LBD-M3-H
A95*GOT	Generic term of A956GOT, A953GOT, A951GOT, A951GOT-Q, A950GOT and A950 handy GOT
GOT	Generic term of A985GOT, A97*GOT, A960GOT and A95*GOT
Memory	Abbreviation of memory (flash memory) in the GOT
OS	Abbreviation of GOT system software
A9GT-QBUSS	Abbreviation of A9GT-QBUSS type bus connection board
A9GT-QBUS2S	Abbreviation of A9GT-QBUS2S type multi-drop bus connection board
A9GT-BUSS	Abbreviation of A9GT-BUSS type bus connection board
A9GT-BUS2S	Abbreviation of A9GT-BUS2S type multi-drop bus connection board
Bus connection board	Generic term of A9GT-QBUSS, A9GT-QBUS2S, A9GT-BUSS and A9GT-BUS2S
A9GT-RS4	Abbreviation of A9GT-RS4 type serial communication board
A9GT-RS2	Abbreviation of A9GT-RS2 type serial communication board
A9GT-RS2T	Abbreviation of A9GT-RS2T type serial communication board
Serial communication board	Generic term of A9GT-RS4, A9GT-RS2 and A9GT-RS2T
Communication board	Generic term of bus connection board and serial communication board
A9GT-QBUS2SU	Abbreviation of A9GT-QBUS2SU type multi-drop bus connection unit
A9GT-BUSSU	Abbreviation of A9GT-BUSSU type bus connection unit
A9GT-BUS2SU	Abbreviation of A9GT-BUS2SU type multi-drop bus connection unit
A7GT-BUSS	Abbreviation of A7GT-BUSS type bus connection unit
A7GT-BUS2S	Abbreviation of A7GT-BUS2S multi-drop bus connection unit
Bus connection unit	Generic term of A9GT-QBUS2SU, A9GT-BUS2SU, A9GT-BUS2SU, A7GT-BUSS and A7GT-BUS2S
A7GT-J71AP23	Abbreviation of A7GT-J71AP23 type data link unit
A7GT-J71AR23	Abbreviation of A7GT-J71AR23 type data link unit
A7GT-J71AT23B	Abbreviation of A7GT-J71AT23B type data link unit
Data link unit	Generic term of A7GT-J71AP23, A7GT-J71AR23 and A7GT-J71AT23B
A7GT-J71LP23	Abbreviation of A7GT-J71LP23 type network unit
A7GT-J71BR13	Abbreviation of A7GT-J71BR13 type network unit
Network unit	Generic term of A7GT-J71LP23 and A7GT-J71BR13
A8GT-J61BT13	Abbreviation of A8GT-J61B13 CC-Link communication unit
A8GT-J61BT15	Abbreviation of A8GT-J61B15 CC-Link communication unit
CC-Link communication unit	Generic term of A8GT-J61BT13 and A8GT-J61BT15
Communication unit	Generic term of bus connection unit, data link unit, network unit and CC-Link communication unit
Protection sheet	Abbreviation of A9GT-80PSC, A9GT-70PSC, A9GT-60PSC and A9GT-50PSC type transparent protection sheets
Backlight	Abbreviation of A9GT-80LTT, A9GT-70LTTB, A9GT-70LTT, A9GT-70LTS and A9GT-50LT type backlights
Debug stand	Abbreviation of A9GT-80STAND, A9GT-70STAND and A9GT-50STAND type debug stand
PC card (memory card)	Abbreviation of PC card with PCMCIA Ver.2.1
Memory board	Abbreviation of A9GT-FNB, A9GT-FNB1M, A9GT-FNB2M, A9GT-FNB4M, A9GT-FNB8M, A9GT-QFNB, A9GT-QFNB4M, A9GT-QFNB8M type option function memory board

Abbreviations, generic terms and special terms	Description
External I/O unit	Abbreviation of A9GT-70KBF and A8GT-50KBF type external I/O interface unit
Printer interface unit	Abbreviation of A9GT-50PRF type printer interface unit
Memory card interface unit	Abbreviation of A1SD59J-MIF memory card interface unit
Attachment	Generic term of A77GT-96ATT/A85GT-95ATT/A87GT-96ATT/A87GT-97ATT attachments
QCPU (Q Mode)	Generic term of Q02CPU, Q02HCPU, Q06HCPU, Q12HCPU and Q25HCPU CPU units
QCPU (A Mode)	Generic term of Q02CPU-A, Q02HCPU-A and Q06HCPU-A CPU units
QCPU	Generic term of QCPU (Q Mode) and QCPU (A Mode)
QnACPU (Large Type)	Generic term of Q2ACPU, Q2ACPU-S1, Q3ACPU, Q4ACPU and Q4ARCPU CPU units
QnACPU (Small Type)	Generic term of Q2ASCPU, Q2ASCPU-S1, Q2ASHCPU and Q2ASHCPU-S1 CPU units
QnACPU	Generic term of QnACPU (Large Type) and QnACPU (Small Type)
AnUCPU	Generic term of A2UCPU, A2UCPU-S1, A3UCPU and A4UCPU CPU units
AnACPU	Generic term of A2ACPU, A2ACPU-S1 and A3ACPU CPU units
AnNCPU	Generic term of A1NCPU, A2NCPU, A2NCPU-S1 and A3NCPU CPU units
ACPU (Large Type)	Generic term of AnUCPU, AnACPU and AnNCPU CPU units
A2US(H)CPU	Generic term of A2USCPU, A2USCPU-S1 and A2USHCPU-S1 CPU units
AnS(H)CPU	Generic term of A1SCPU, A1SHCPU, A2SCPU and A2SHCPU CPU units
A1SJ(H)CPU	Generic term of A1SJCPU-S3 and A1SJHCPU CPU units
ACPU (Small Type)	Generic term of A2US(H)CPU, AnS(H)CPU and A1SJ(H)CPU CPU units
ACPU	Generic term of ACPU (Large Type), ACPU (Small Type) and A1FXCPU CPU units
FX0 series	Generic term of FX0 series CPU unit
FX0N series	Generic term of FX0N series CPU unit
FX0S series	Generic term of FX0S series CPU unit
FX1 series	Generic term of FX1 series CPU unit
FX1S series	Generic term of FX1S series CPU unit
FX2 series	Generic term of FX2 series CPU unit
FX2C series	Generic term of FX2C series CPU unit
FX2N series	Generic term of FX2N series CPU unit
FX2NC series	Generic term of FX2NC series CPU unit
FXCPU	Generic term of FX0 series, FX0N series, FX0S series, FX1 series, FX1S series, FX2 series, FX2C series, FX2N series, FX2NC series CPU unit
Motion controller CPU	Generic term of A373UCPU, A373UCPU-S3, A273UCPU, A273UHCPU, A273UHCPU-S3, A171SCPU-S3, A171SHCPU, A172SHCPU CPU unit
FA controller	Generic term of LM610, LM7600, LM8000 CPU unit
Omron PLC	Generic term of C200HS, C200H, C200HX, C200HG, C200HE, CQM1, C1000H, C2000H, CV1000 CPU unit
Yasukawa PLC	Generic term of GL60S, GL60H, GL70H, GL120, GL130, CP-9200SH, CP-9300MS, MP-920, MP-930, CP-9200(H) and PROGIC-8 CPU unit
Allen-Bradley PLC	Generic term of SLC 5/03, SLC 5/04 CPU unit
Sharp PLC	Generic term of JW-21CU, JW-22CU, JW-31CUH, JW-32CUH, JW-33CUH, JW-50CUH, JW-70CUH, JW-100CUH CPU unit
Toshiba PLC	Generic term of T3, T3H CPU unit
SIEMENS PLC	Generic term of SIMATIC S7-300 Series and SIMATIC S7-400 Series CPU unit
Other PLC	Generic term of Omron PLC, Yasukawa PLC, Allen-Bradley PLC, Sharp PLC, Toshiba PLC and SIEMENS PLC CPU unit
SW4D5C-GOTR-PACKE	Generic term of SW4D5C-GOTR-PACKE software package and SW4D5C-GOTR-PACKEV software package
Drawing software	Abbreviation of image creation software GOT Screen Designer for GOT900
Data conversion software	Abbreviation of data conversion software GOT Converter for GOT900
Debug software	Abbreviation of debugging software GOT Debugger
Object	Setting data for dynamic image
Windows95	Abbreviation of Microsoft Windows95 ^{*1}
Windows98	Abbreviation of Microsoft Windows98 ^{*1}
Windows NT4.0	Abbreviation of Microsoft Windows NT Workstation 4.0 ^{*1}
Windows	Generic term of Windows95, Windows98 and Windows NT4.0
Acrobat Reader	Abbreviation of Adobe Acrobat Reader3.0 ^{*2}
Personal Computer	Windows compatible Personal Computer that can install SW4D5C-GOTR-PACKE

*1 Microsoft Windows95, Microsoft Windows98 and Microsoft Windows NT Workstation 4.0 are the trademarks of Microsoft Corporation, U.S.

*2 Adobe and Adobe Acrobat are the trademarks of Adobe Systems Incorporated. (C)1998 Adobe Systems Incorporated. All right reserved.

Manual

The following manuals related to this product are available. Obtain the manuals as required the according to this table.

- Related manual

Manual name	Manual number (Model code)
A985GOT/A975GOT/A970GOT/A960GOT User's Manual Explains the specifications, general system configuration, component devices, part names, option unit loading methods, installation and wiring methods, maintenance and inspection methods, and error codes of A985GOT/A975GOT/A970GOT/A960GOT unit. (Available as option)	SH-4005 (13JL70)
A950GOT/A951GOT/A953GOT/A956GOT User's Manual Explains the specifications, general system configuration, component devices, part names, option unit loading methods, installation and wiring methods, maintenance and inspection methods, and error codes of A950GOT/A951GOT/A953GOT/A956GOT unit. (Available as option)	SH-080018 (13JL92)
GOT-A900 Series User's Manual (SW4D5C-GOTR-PACKE compatible Connection System Manual) Gives the specifications, system configuration, setting method and connection diagram of each connection form available for the GOT-A900 series. (Available as option)	SH-080070 (13JR11)
GOT-A900 Series Operating Manual (SW4D5C-GOTR-PACKE compatible Extended • Option Functions Manual) Provides the specifications of the utility, system monitoring, ladder monitoring, special function unit monitoring, network monitoring functions and list editor functions available for the GOT-A900 series and how to operate the dedicated monitor screen. (Available as option)	SH-080069 (13J979)
SW4D5C-GOTR-PACKE(V) Operating Manual Deals with how to install and start the SW4D5C-GOTR-PACKE, its system configuration, the screen makeup of the software package, the general description of various monitoring functions, the procedure for displaying the monitor screen on the GOT, and how to use the help function. (Found in the packing of the SW4D5C-GOTR-PACKE)	IB-0800094 (13J978)
A9GT-QBUSS Type Bus Connection Board User's Manual Describes specifications, part names and installation of A9GT-QBUSS. (with A9GT-QBUSS)	IB-0800073 (13JQ75)
A9GT-QBUS2S Type Multi-Drop Bus Connection Board User's Manual Describes specifications, part names and installation of A9GT-QBUS2S. (with A9GT-QBUS2S)	IB-0800074 (13JQ76)
A9GT-QBUS2SU Type Multi-Drop Bus connection unit User's Manual Describes specifications, part names and installation of A9GT- QBUS2SU. (with A9GT- QBUS2SU)	IB-0800083 (13JQ83)
A9GT-BUSSU Type Bus connection unit User's Manual Describes specifications, part names and installation of A9GT-BUSSU. (with A9GT-BUSSU)	IB-0800076 (13JQ78)
A9GT-BUS2SU Type Multi-Drop Bus connection unit User's Manual Describes specifications, part names and installation of A9GT-BUS2SU. (with A9GT-BUS2SU)	IB-0800077 (13JQ79)
A9GT-BUSS Type Bus Connection Board User's Manual Describes specifications, part names and installation of A9GT-BUSS. (with A9GT-BUSS)	IB-68953 (13JM87)
A9GT-BUS2S Type Multi-Drop Bus Connection Board User's Manual Describes specifications, part names and installation of A9GT-BUS2S. (with A9GT-BUS2S)	IB-68954 (13JM88)
A7GT-BUSS Type bus connection unit User's Manual Describes specifications, part names and operation of A7GT-BUSS. (with A7GT-BUSS)	IB-66760 (13JL07)

Manual name	Manual number (Model code)
A7GT-BUS2S Type multi-drop bus connection unit User's Manual Describes specifications, part names and operation of A7GT-BUS2S. (with A7GT-BUS2S)	IB-66761 (13JL08)
A9GT-RS4 Type Serial Communication Board User's Manual Describes specifications, part names and installation of A9GT-RS4. (with A9GT-RS4)	IB-68955 (13JM89)
A9GT-RS2 Type Serial Communication Board User's Manual Describes specifications, part names and installation of A9GT-RS2. (with A9GT-RS2)	IB-68956 (13JM90)
A9GT-RS2T Type Serial Communication Board User's Manual Describes specifications, part names and installation of A9GT-RS2T. (with A9GT-RS2T)	IB-0800022 (13JQ38)
A7GT-J71AP23/R23 Type Data Link Unit User's Manual Describes specifications, part names and installation of A7GT-J71AP23/R23. (with A7GT-J71AP23/R23)	IB-66438 (13JE26)
A7GT-J71AT23B Type Data Link Unit User's Manual Describes specifications, part names and installation of A7GT-J71AT23B. (with A7GT-J71AT23B)	IB-66439 (13JA81)
A7GT-J71LP23/BR13 Type Network Unit User's Manual Describes specifications, part names and installation of A7GT-J71LP23/BR13. (with A7GT-J71LP23/BR13)	IB-66558 (13JE94)
A8GT-J61BT13 Type CC-Link Communication Unit User's Manual Describes specifications, part names and installation of A8GT-J61BT13. (with A8GT-J61BT13)	IB-66838 (13JL56)
A8GT-J61BT15 Type CC-Link Communication Unit User's Manual Describes specifications, part names and installation of A8GT-J61BT15. (with A8GT-J61BT15)	IB-66788 (13JL29)
A9GT-80LTT Type Back light Unit User's Manual Describes specifications, part names and installation of A9GT-80LTT. (with A9GT-80LTT)	IB-80027 (13JQ21)
A9GT-70LTT Type Back light Unit User's Manual Describes specifications, part names and installation of A9GT-70LTT. (with A9GT-70LTT)	IB-68982 (13JM97)
A9GT-70LTS Type Back light Unit User's Manual Describes specifications, part names and installation of A9GT-70LTS. (with A9GT-70LTS)	IB-68984 (13JM99)
A9GT-70LTTB Type Back light Unit User's Manual Describes specifications, part names and installation of A9GT-70LTTB. (with A9GT-70LTTB)	IB-80033 (13JQ25)
A9GT-50LT type backlight User's Manual Describes specifications and operation of A9GT-50LT. (with A9GT-50LT)	IB-0800020 (13JQ29)
A9GT-80STAND User's Manual Describes specifications, part names and installation of A9GT-80STAND. (with A9GT-80STAND)	IB-80028 (13JQ22)
A9GT-70STAND User's Manual Describes specifications, part names and installation of A9GT-70STAND. (with A9GT-70STAND)	IB-68981 (13JM96)
A9GT-50STAND User's Manual Describes specifications and operation of A9GT-50STAND. (with A9GT-50STAND)	IB-0800021 (13JQ30)

Manual name	Manual number (Model code)
Add-on memory board for A9GT-FNB, A9GT-FNB1M, A9GT-FNB2M, A9GT-FNB4M and A9GT-FNB8M type option function Describes specifications, part names and installation of A9GT-FNB (1M/2M/4M/8M). (with A9GT-FNB (1M/2M/4M/8M))	IB-68975 (13JM91)
Add-on memory board for A9GT-QFNB, A9GT-QFNB4M and A9GT-QFNB8M type option function Describes specifications, part names and installation of A9GT-QFNB (4M/8M). (with A9GT- QFNB (4M/8M))	IB-0800051 (13JQ62)
A9GT-70KBF Type External I/O Interface Unit User's Manual Describes specifications, system configurations, part names and installation/wiring methods of A9GT-70KBF. (with A9GT-70KBF)	IB-80018 (13JQ14)
A8GT-50KBF Type External I/O Interface Unit User's Manual Describes specifications, system configurations, part names and installation/wiring methods of A8GT-50KBF. (with A8GT-50KBF)	IB-66787 (13JL28)
A9GT-50PRF type printer interface unit user's manual Describes specifications, system configuration, part names, installation method and external dimensions of A9GT-50PRF. (with A9GT-50PRF)	IB-0800019 (13JQ28)
A8GT-TK Type Numerical Keypad Panel User's Manual Describes specifications, part names and installation of A8GT-TK. (with A8GT-TK)	IB-66832 (13JL51)
A9GT-QCNB Type bus connector conversion box User's Manual Describes specifications, part names and installation of A9GT-QCNB. (with A9GT-QCNB)	IB-0800082 (13JQ82)
A7GT-CNB Type bus connector conversion box User's Manual Describes specifications, part names and installation of A7GT-CNB. (with A7GT-CNB)	BCN-P5138

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Chapter1 Overview

This manual describes the specifications, system configurations, setting method, connection cables and other information of each connection supported by the GOT.

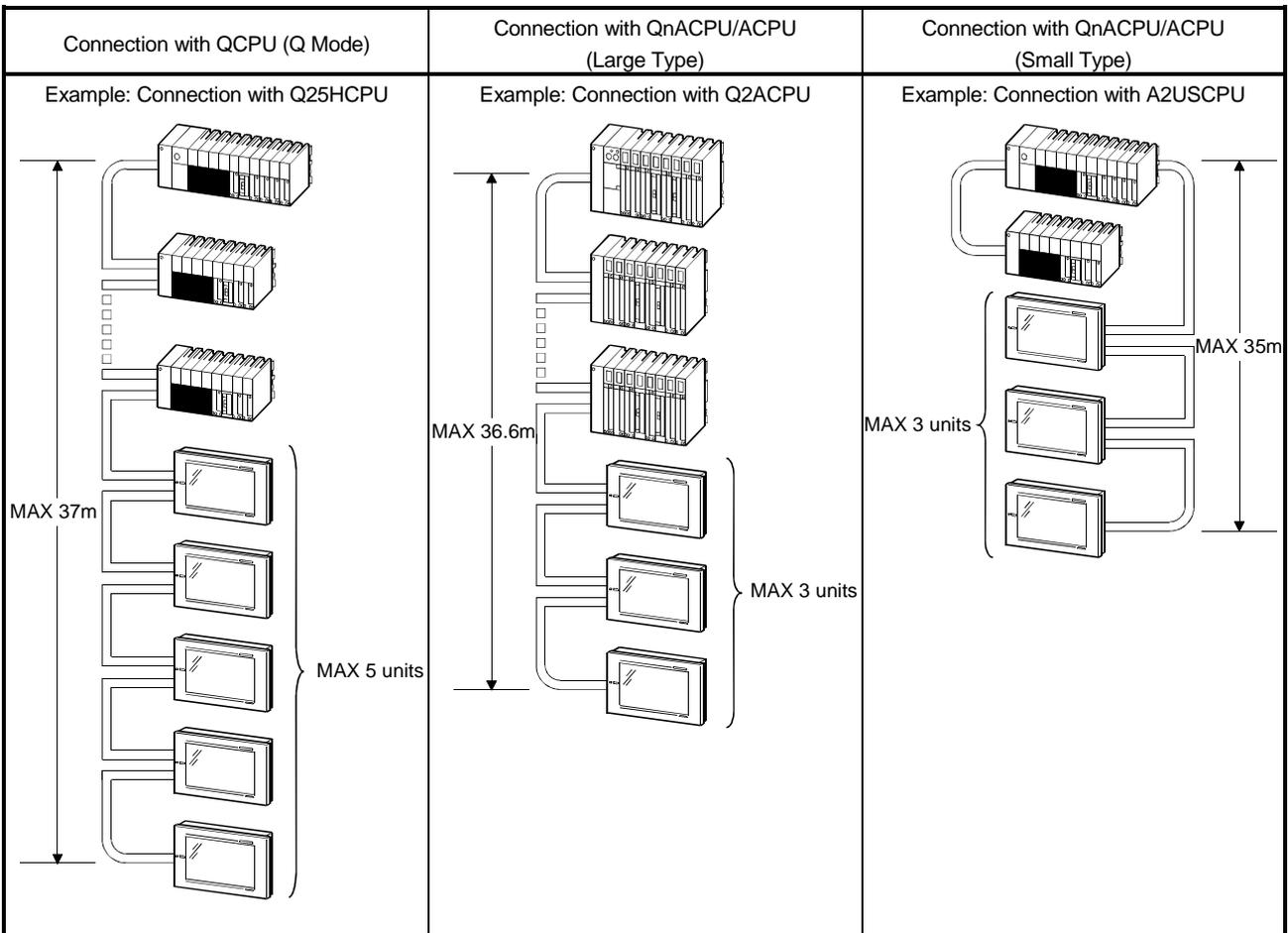
1.1 Connection supported by GOT

(1) Bus connection

Bus connection is a way of using the extension connector of a base unit for connection of the GOT (connection by I/O bus) and this connection form has the fastest response to a PLC CPU among the GOT connection forms.

Multiple GOTs can be connected in a position away from the PLC CPU to be connected to.

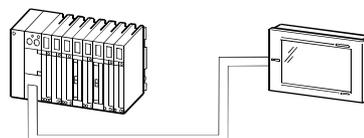
However, only one GOT may be connected depending on the PLC CPU to be connected to.



*There are various precautions for bus connection according to the system selected. For details, refer to Chapter 3.

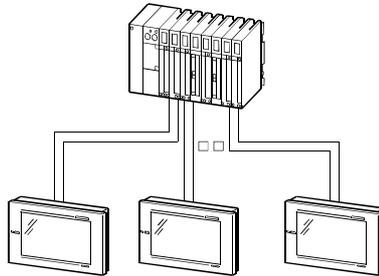
(2) Direct connection to CPU

You can connect the GOT with the PLC CPU by an RS-422/RS-232C cable and this is the most economical way of connection.



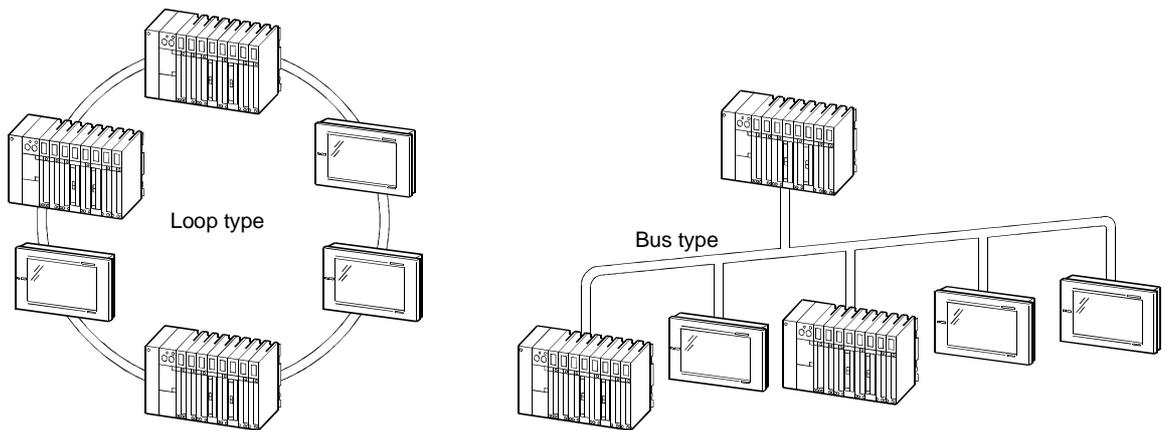
(3) Computer link connection

Since the GOT can be connected with a computer link unit on a 1:1 basis, several GOTs can be connected.



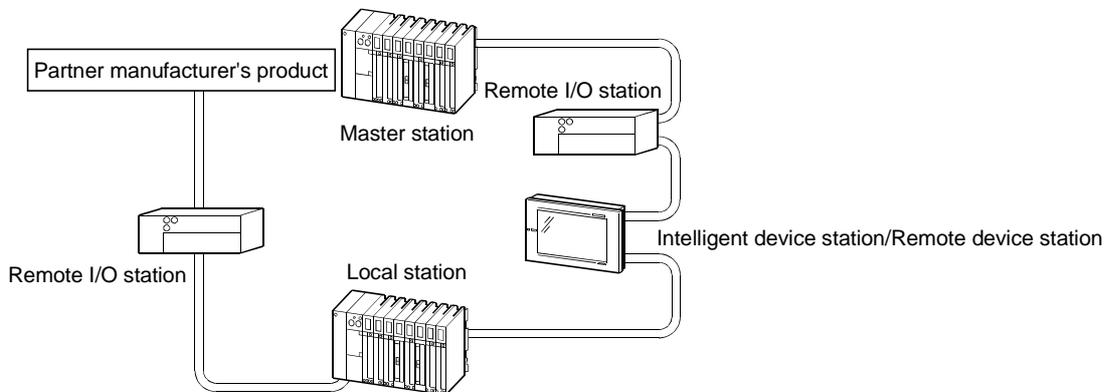
(4) MELSECNET connection

The GOT is used as a local station of the data link system or a normal station of the network system and allows remote control via network.



(5) CC-Link connection

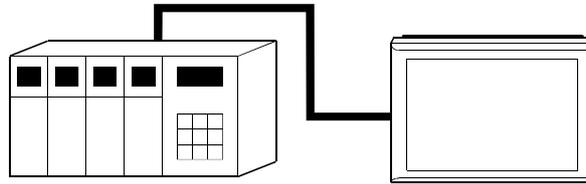
The GOT is used as an intelligent device station or a remote device station of the CC-Link system and allows remote control via network.



(6) Omron PLC connection

Allows monitoring by connecting to an Omron PLC.

- CPUs that allow monitoring
C200H, C200HS, C200H, CQM1, C1000H, C2000H, CV1000

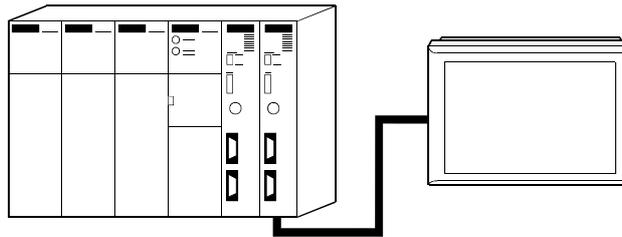


RS-422 communication/RS232C communication enables monitoring.

(7) Yasukawa PLC connection

Allows monitoring by connecting to a Yasukawa PLC.

- CPUs that allow monitoring
GL60S, GL60H, GL70H, GL120, GL130, CP-9200SH, CP-9300MS, MP-920, MP-930, CP-9200(H), PROGIC-8

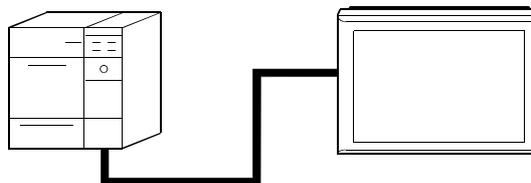


RS-422 communication/RS232C communication enables monitoring.

(8) Allen-Bradley PLC connection

Allows monitoring by connecting to the Allen-Bradley PLC.

- CPUs that allow monitoring
SLC 5/03, SLC 5/04

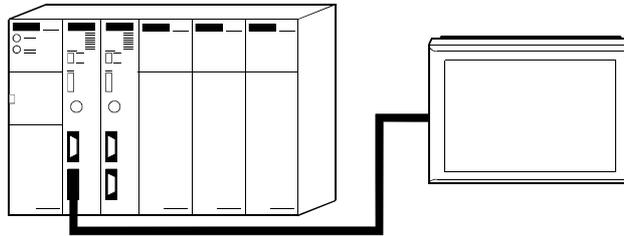


Monitored with RS-232C communication

(9) Sharp PLC connection

Allows monitoring by connecting to the Sharp PLC.

- CPUs that allow monitoring
 JW-21CU, JW-22CU, JW-31CUH, JW-32CUH, JW-33CUH, JW-50CUH,
 JW-70CUH, JW-100CUH

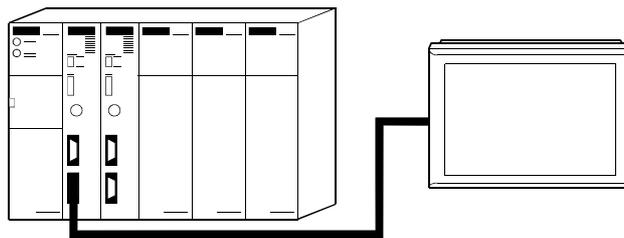


Monitored with RS-232C/RS-422 communication

(10) Toshiba PLC connection

Allows monitoring by connecting to a Toshiba PLC.

- CPUs that allow monitoring
 T3, T3H

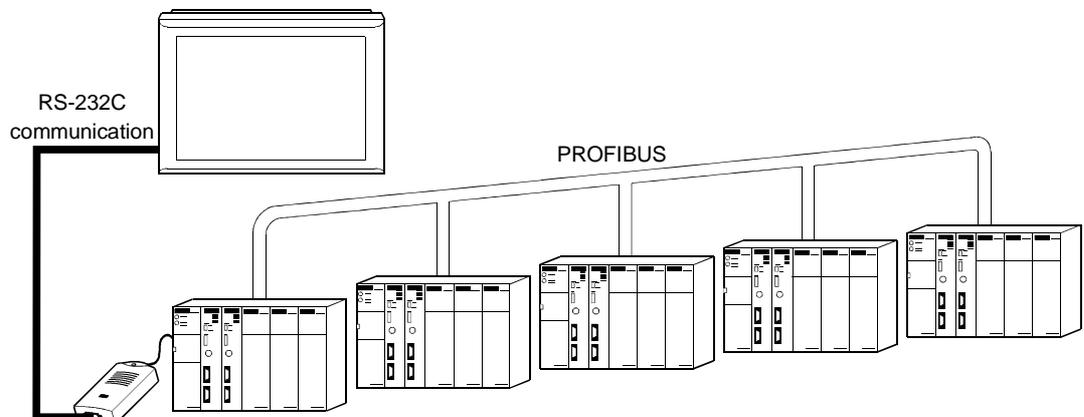


Monitored with RS-422 communication

(11) SIEMENS PLC connection

Connecting to the HMI adaptor allows monitoring of multiple SIEMENS PLCs connected by PROFIBUS.

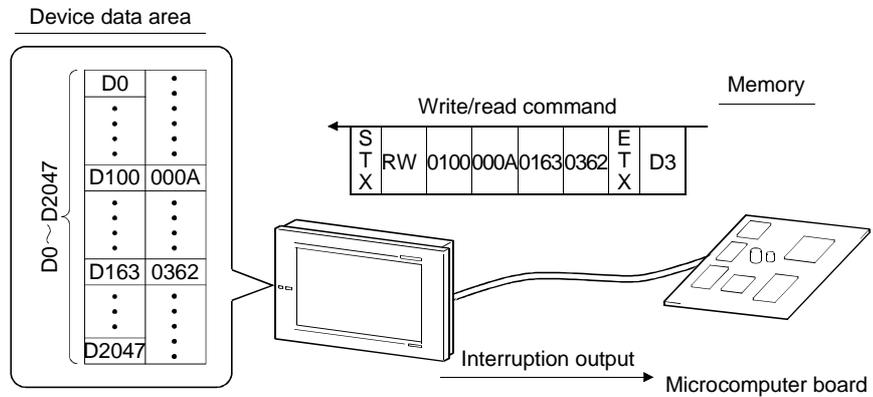
- CPUs that allow monitoring
 SIMATIC S7-300 series, SIMATIC S7-400 series



Monitoring allowed via HMI adaptor

(12) Microcomputer connection

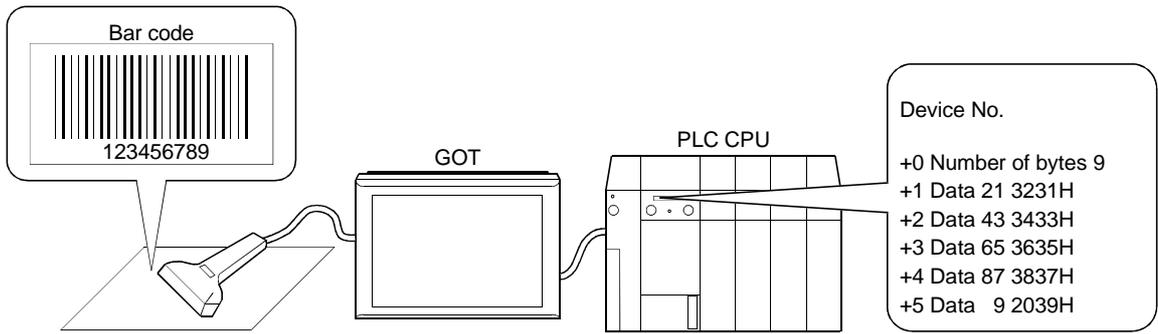
Virtual device (D) of the GOT can be monitored by sending/receiving data from/to a personal computer, microcomputer board, PLC, etc. (hereinafter referred to as "host")



(13) Optional devices connection

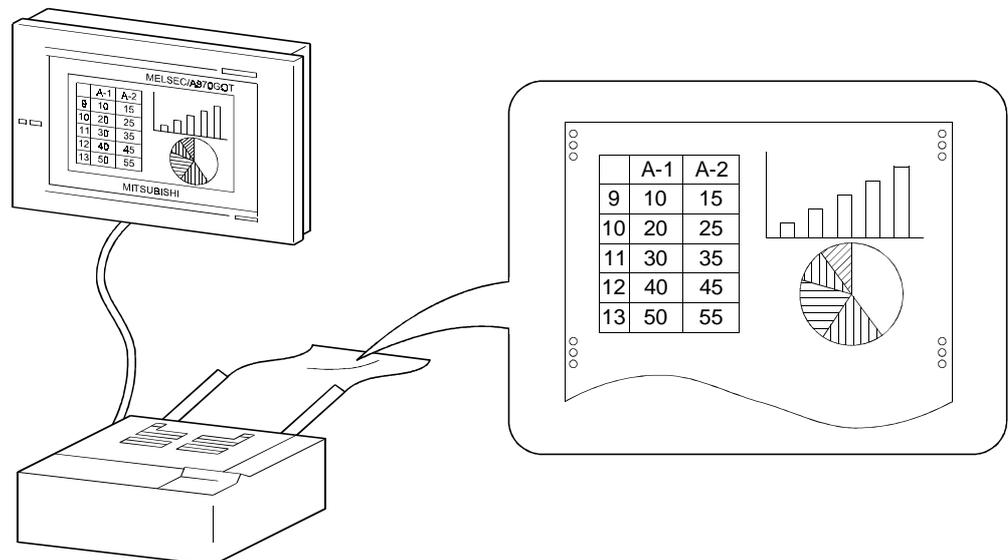
(a) Bar code reader

If connected to a bar code reader, the GOT can write data read with the bar code reader to the PLC CPU.



(b) Printer

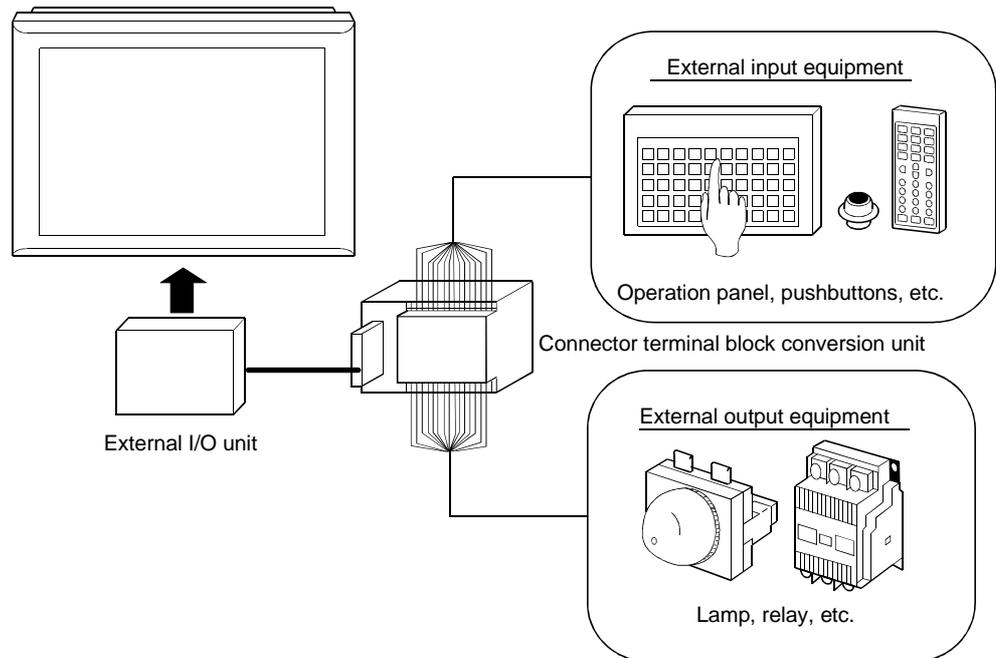
If connected to a printer, the GOT can print data of alarm history and hard copy functions.



(c) External I/O equipment

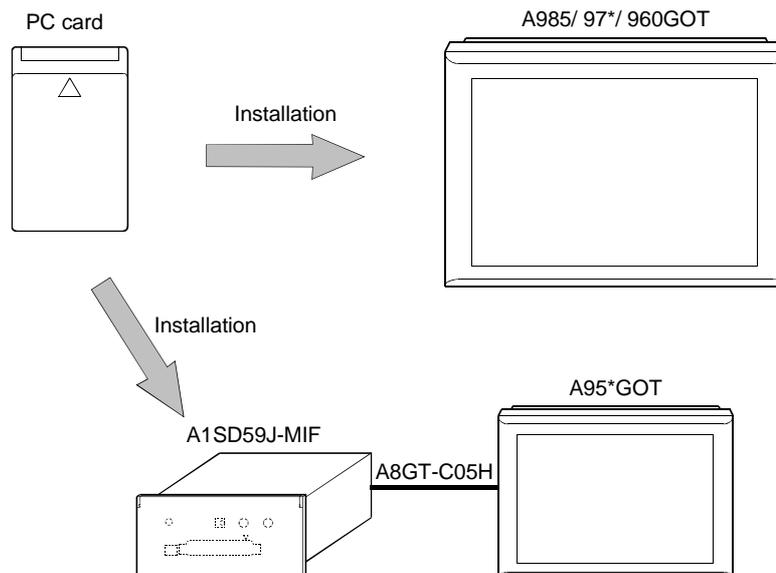
By connection of input equipment (operation panel, ten-key panel, pushbuttons, etc.), you can write to devices, e.g. touch input, numerical input and screen switching, from outside the GOT.

In addition, you can connect output equipment (lamps, relays, etc.) to provide outputs from the GOT to the outside.



(d) PC card

Installation of PC card on the GOT allows storage of data used in the transfer data (system program, monitor screen data) and object function (alarm history function, recipe function, etc.).



Chapter2 Specification

2.1 PLC CPU that allows monitoring

The PLC CPU that can be monitored by the GOT changes with the system up to the PLC CPU monitored (connection form).

The PLC CPUs that can be monitored by the GOT are indicated below per connection form.

PLC CPU Monitored*1	Bus Connection	CPU Direct Connection	Computer Link Connection	MELSECNET Connection			CC-Link Connection	
				Network system		Data link system	Intelligent device station	Remote device station*3
				MELSEC NET/10H	MELSEC NET/10	MELSEC NET/B,(II)		
QCPU (Q mode)	○	○	○	×	△*4	×	○	○
QCPU (A mode)	×	○	○	×	○	○	○	○
QnACPU	○	○	○	×	△*4	○	○	○
ACPU Other than A1FXCPU	△*5	△*6	△*6*7*8	×	△*6	△*6	△*6	○
ACPU A1FXCPU	×	○	×	×	×	×	×	×
FXCPU	×	○	×	×	×	×	×	×
FA controller	×	×	×	×	○	○	×	×
Motion controller CPU	○	○	△*8	×	○	○	○	○
Omron PLC	×	×	○	×	×	×	×	×
Yasukawa PLC	×	○	○	×	×	×	×	×
Allen-Bradley PLC	×	○	×	×	×	×	×	×
Sharp PLC	×	○	○	×	×	×	×	×
Toshiba PLC	×	×	○	×	×	×	×	×
SIEMENS PLC	×	○	×	×	×	×	×	×

*1 In a system where a remote I/O station exists, monitoring cannot be done independently of the PLC CPU and connection form.

*2 Including the case where the MELSECNET/10H is used in the NET/10 mode.

*3 For connection as a remote device station, only the link devices (RX, RY, RWw, RWr) assigned to the GOT may be monitored.

*4 When creating a monitor screen (project data) with the drawing software, note the following two points.

- When setting the monitor devices, note that the device ranges that can be monitored are the ranges for monitoring the ACPUs (A3ACPU equivalent).
- The PLC CPUs monitored are the QCPU (Q mode) and QnACPU, but the PLC type must be set to "MELSEC-A".

*5 The A2CCPU and A2CCPUC24 do not allow bus connection.

*6 When monitoring the AnNCPU(S1), A2SCPU, A0J2HCPU or A2CCPU, data cannot be written to the CPU earlier than the following version.

- AnNCPU(S1): Version L or later for the one with link, version H or later for the one without link
- A2SCPU: Version H or later
- A0J2HCPU: Version E or later
- A2CCPU: Version H or later

*7 The A2CCPU does not allow computer link connection.

*8 For computer link connection of the A2SCPU, A2SHCPU-S1, A2SHCPU, A1SHCPU, A1SJHCPU, A0J2HCPU, A171SHCPU and A172SHCPU, use the computer link module whose software version is version U or later.

In addition, the A0J2-C214-S1 (A0J2HCPU-dedicated computer link module) cannot be used.

2.2 Device name that allows monitoring

(1) QCPU (A Mode), ACPU

Device name		Available range for monitoring	
Bit device	Input (X)	X0 to X1FFF	
	Output (Y)	Y0 to Y1FFF	
	Internal relay (M)	M0 to M8191	
	Annunciator (F)	F0 to F2047	
	Link relay (B)	B0 to B1FFF	
	Special internal relay (M)	M9000 to M9255	
	Latch relay (L)	L0 to L8191	
	Timer	Contact (TT)	TT0 to TT2047
		Coil (TC)	TC0 to TC2047
	Counter	Contact (CT)	CT0 to CT1023
		Coil (CC)	CC0 to CC1023
	Link special relay (SB)	SB0 to SB7FF	
	Word device bit	Designated bit of the following word devices (except for index register and buffer memory)	
GOT bit register (GB)	GB64 to GB1023		
Word device	Data register (D)	D0 to D8191	
	Special data register (D)	D9000 to D9255	
	Link register (W)	W0 to W1FFF	
	Timer (current value) (TN)	TN0 to TN2047	
	Counter (current value) (CN)	CN0 to CN1023	
	Link special register (SW)	SW0 to SW7FF	
	File register (R)	R0 to R8191	
	Extended file register (ER)	Block	1 to 255
		Device	R0 to R8191
	Index register *2	(Z)	Z0 to Z6(Z0=Z)
		(V)	V0 to V6(V0=V)
	Accumulator (A)	A0 to A1	
	Buffer memory (special function unit) (BM)	BM0 to BMn*1	
Bit device word *3 *4	Converting the above bit devices to words (except for timer and counter)		
GOT data register (GD)	GD64 to GD1023		

*1 Only special function units of the GOT connection station can be designated.

Set within the address range of the buffer memory of the designated special function unit.

*2 Writing to the index register is prohibited during computer link connection.

*3 Use a multiple of 16 for setting device number.

*4 If converting the special internal relay (M) to a bit device word, regard 9000 as 0 and use a multiple of 16 for the device number.

(Example) M9000, M9016, M9240

(2) QCPU (Q Mode), QnACPU

Device name		Allowable range of monitoring	
Bit device	Input (X)	X0 to X1FFF	
	Output (Y)	Y0 to Y1FFF	
	Internal relay (M)	M0 to M32767	
	Latch relay (L)	L0 to L32767	
	Annunciator (F)	F0 to F32767	
	Link relay (B)	B0 to B1FFF	
	Timer	Contact (TT)	TT0 to TT32767
		Coil (TC)	TC0 to TC32767
	Counter	Contact (CT)	CT0 to CT32767
		Coil (CC)	CC0 to CC32767
	Special relay (SM)	SM0 to SM2047	
	Retentive timer	Contact (SS)	SS0 to SS32767
		Coil (SC)	SC0 to SC32767
	Step relay (S)	S0 to S32767	
	Link special relay (SB)	SB0 to SB7FF	
	Word device bit	Designated bit of the following word devices (except for index register and buffer memory)	
GOT bit register (GB)	GB64 to GB1023		
Word device	Data register (D)	D0 to D32767	
	Special data register (SD)	SD0 to SD2047	
	Link register (W)	W0 to W1FFF	
	Timer (current value) (TN)	TN0 to TN32767	
	Counter (current value) (CN)	CN0 to CN32767	
	Retentive timer (current value) (SN)	SN0 to SN32767	
	Link special register (SW)	SW0 to SW7FF	
	File register (R)	R0 to R32767* ¹	
	Extended file register (ER)	Block	0 to 31
		Device	R0 to R32767
	Extended file register (ZR)	ZR0 to ZR1042431* ²	
	Index register (Z)	Z0 to Z15	
	Buffer memory (special function unit) (BM)	BM0 to BMn* ³	
	Bit device word * ⁴	Converting the above bit devices to words	
GOT data register (GD)	GD64 to GD1023		

*1 Block file register that is switched by the RSET command is monitored.

*2 Block file register that is switched by the QDRSET command is monitored.

*3 Only special function units of the GOT connection station can be designated.

Set within the address range of the buffer memory of the designated special function unit.

*4 Set the device numbers in multiples of 16.

(3) CC-Link connection (Remote device)

Device name		Available range for monitoring
Bit device	Remove input (RX)	X0 to X7FF
	Remote output (RY)	Y0 to Y7FF
	Bit designation of remote register write area (RWw)	Ww0 to WwFF
	Bit designation of remote register read area (RWr)	Wr0 to WrFF
	GOT bit register (GB)	GB64 to GB1023
	Bit designation of GOT data register (GD)	GD64 to GD1023
Word device	Remote register write area (RWw)	Ww0 to WwFF
	Remote register read area (RWr)	Wr0 to WrFF
	GOT data register (GD)	GD64 to GD1023
	Converting GOT bit register to word (GB)	GB64 to GB1023

(4) MELSEC-FXCPU

Device name		Available range for monitoring	Device number expression
Bit device	Input relay (X)	X0000 to X0377	Octal notation
	Output relay (Y)	Y0000 to Y0377	
	Auxiliary relay (M)	M0000 to M3071	
	State (S)	S0000 to S0999	Decimal notation
	Special auxiliary relay (M)	M8000 to M8255	
	Timer contact (T)	T000 to T255	
	Counter contact (C)	C000 to C255	
	Word device bit * ¹	—	—
GOT bit register (GB)	GB64 to GB1023	—	
Word device	Timer (current value) (T)	T000 to T255	Decimal notation
	Counter (current value) (C)	C000 to C255	
	Data register (D)	D000 to D0999	
	RAM file register (D)	D1000 to D7999	
	Special data register (D)	D8000 to D8255	
	Bit device word * ² * ³	—	
	GOT data register (GD)	GD64 to GD1023	

*1 While the touch key function to which a word device bit is designated as the monitor device is executed, do not write the word device in a sequence program.

*2 Bit devices of the timer contact (T) and counter contact (C) cannot be converted to words.

*3 Use a multiple of 16 for designating the device number.

(5) Omron PLC

Device name		Available range for monitoring
Bit device	I/O relay	..0000 to 51115
	Internal auxiliary relay	
	Data link relay (LR)	LR0000 to LR6315
	Auxiliary memory relay (AR)	AR0000 to AR2715
	Holding relay (HR)	HR0000 to HR9915
	Timer contact (TIM) *1	TIM000 to TIM511
	Counter contact (CNT) *1	CNT000 to CNT511
	Data memory (DM) *2	DM0000 to DM9999
	Timer (current value) (TIM) *2	TIM000 to TIM511
	Counter (current value) (CNT) *2	CNT000 to CNT511
	GOT bit register	GB64 to GB1023
	Word device	I/O relay
Data link relay (LR)		LR0000 to LR0063
Auxiliary memory relay (AR)		AR0000 to AR0027
Holding relay (HR)		HR0000 to HR0099
Data memory (DM)		DM0000 to DM9999
Timer (current value) (TIM)		TIM000 to TIM511
Counter (current value) (CNT)		CNT000 to CNT511
GOT data register		GD64 to GD1023

*1 If CV1000 is used, no writing is available.

*2 While the touch key function to which a word device bit is designated as the monitor device is executed, do not write the word device in a sequence program.

(6) Yasukawa PLC

(a) When using GL60S, GL60H, GL70H, GL120 or GL130

Device name		Available range for monitoring
Bit device	Coil	O01 to O63424
	Input relay	I1 to I63424
	Link coil	D1 to D2048
		D10001 to D12048 D20001 to D22048
	GOT bit register	GB64 to GB1023
Word device	Input register	Z1 to Z31840*1
	Holding register	W1 to W28291*2
	Link register	R1 to R2048
		R10001 to R12048 R20001 to R22048
	Constant register	K1 to K4096*3
GOT data register	GD64 to GD1023	

*1 Change the input register 30001 to 30512 to Z1 to Z512. (Example of setting in default)

*2 Change the input register 40001 to 49999 to W1 to W9999. (Example of setting in default)

*3 Change the constant register 31001 to 35096 to K1 to K4096. (Example of setting in default)

(b) When using CP-9200SH, MP-920, MP-930

Device name		Available range for monitoring
Bit device	Coil	MB0 to MB4095F
	Input relay	IB0000 to IBFFFF
	GOT bit register	GB64 to GB1023
Word device	Input register	IW0 to IW7FFF
	Holding register	MW0 to MW32767
	GOT data register	GD64 to GD1023

(c) When using CP-9300MS

Device name		Available range for monitoring
Bit device	Coil	MB0 to MB3071F
	Input relay	IB0000 to IB3FF
	GOT bit register	GB64 to GB1023
Word device	Input register	IW0 to IW3F
	Holding register	MW0 to MW3071
	GOT data register	GD64 to GD1023

(d) When using CP-9200(H)

Device name		Available range for monitoring
Bit device	Coil	OB00000 to OB007FF
	Input relay	IB00000 to IB007FF
	GOT bit register	GB64 to GB1023
Word device	Input register	IW00000 to IW007F
	Output register	OW0000 to OW007F
	Data register	DW0000 to DW02047
		ZD0000 to ZD02047 *1
	Common register	MW0000 to MW7694
GOT data register	GD64 to GD1023	

*1 May be set only when CP-9200H is used.

(e) When using PROGIC-8

Device name		Available range for monitoring
Bit device	Coil	o0001 to o2048 *1
	Input relay	I0001 to I0512
	Link coil	D0001 to D1024
	GOT bit register	GB64 to GB1023
Word device	Input register	Z0001 to Z0128
	Holding register	W0001 to W2048
	Link register	R0001 to R1024
	GOT data register	GD64 to GD1023

*1 Internal coils N1 to N1536 may be set as o513 to o2048.

However, make setting to avoid o1 to o512 from overlapping o513 to o2048.

(7) Allen-Bradley PLC

Device name		Monitoring range	Device No. notation
Word device	Bit (B)	B0030000 to B003255F B0100000 to B255255F	Decimal
	Timer (timing bit) (TT)	TT0040000 to TT0042550 TT0100000 to TT2552550	
	Timer (timing bit) (TN)	TN0040000 to TN0042550 TN0100000 to TN2552550	
	Counter (up counter) (CU)	CU0050000 to CU0052550 CU0100000 to CU2552550	
	Counter (down counter) (CD)	CD0050000 to CD0052550 CD0100000 to CD2552550	
	Counter (completion bit) (CN)	CN0050000 to CN0052550 CN0100000 to CN2552550	
	Integer (N)	N007000 to N007255 N010000 to N255255	
	GOT internal bit register (GB)	GB64 to GB1023	
Bit device	Bit (B)	B003000 to B003255 *1 B010000 to B255255	Decimal
	Timer (set value) (TP)	TP004000 to TP004255 *1 TP010000 to TP255255	
	Timer (current value) (TA)	TA004000 to TA004255 *1 TA010000 to TA255255	
	Counter (set value) (CP)	CP005000 to CP005255 *1 CP010000 to CP255255	
	Counter (current value) (CA)	CA005000 to CA005255 *1 CA010000 to CA255255	
	Integer (N)	N007000 to N007255 *1 N010000 to N255255	
	GOT internal data register (GD)	GD64 to GD1023	

*1 Writing on device is not allowed for 32 bit data.

(8) Sharp PLC

Device name	Setting monitor	Device No. notation
I/O relay	0 to 15777 20000 to 75777	Octal
Timer counter (contact)	T/C0000 to T/C1777	
Timer counter (current value)	T/C0000 to T/C1777 (b0000 to b3776)	
Register	09000 to 09776	
	19000 to 19776	
	29000 to 29776	
	39000 to 39776	
	49000 to 49776	
	59000 to 59776	
	69000 to 69776	
	79000 to 79776	
	89000 to 89776	
	99000 to 99776	
	E0000 to E0776	
	E1000 to E1776	
E2000 to E2776		
E3000 to E3776		
E4000 to E4776		
E5000 to E5776		
E6000 to E6776		
E7000 to E7776		
File register	1000000 to 1177776	
	2000000 to 2177776	
	3000000 to 3177776	
	4000000 to 4177776	
	5000000 to 5177776	
	6000000 to 6177776	
7000000 to 7177776		

(9) Toshiba PLC

Device name		Available range for setting monitor
Bit device	External input (X)	X0000 to X511F
	External output (Y)	Y0000 to Y511F
	Internal relay (R)	R0000 to R999F
	Special relay (S)	S0000 to S255F
	Link register relay (Z)	Z0000 to Z999F
	Link relay (L)	L0000 to L255F
	Timer (contact) (T) *4	T000 to T999
	Counter (contact) (C) *4	C000 to C511
	Word device bit *5	Designated bit of the following word devices (except timer (current value) and counter (current value))
	GOT bit register (GB)	GB64 to GB1023
Word device	External input (X)	XW000 to XW511
	External output (Y)	YW000 to YW511
	Internal relay (R)	RW000 to RW999
	Special relay (S)	SW000 to SW255
	Link register relay (Z)	—*3
	Link relay (L)	LW000 to LW255
	Timer (current value) (T) *4	T000 to T999
	Counter (current value) (C) *4	C000 to C511
	Data register (D) *2	D0000 to D8191
	Link register (W)	W0000 to W2047
	File register (F)	F0000 to F32467 *1
	Bit device word	Conversion of the above bit devices to words (except link register relay, timer (contact) and counter (contact)) GOT data register (GD)
	GOT data register (GD)	GD64 to GD1023

*1 The extended file register is not supported.

*2 When the mode switch on the CPU module is set to "P-RUN", D0000 to D4095 are write disabled.

*3 The Z relay corresponds to 1 bit in 1000 words from W registers 0 to 999.

*4 The contacts and current values of the timers/counters are written after they have been read once. During that period, therefore, do not change them in the sequence program.

*5 The bit of the word device is designated after it has been read once. During that period, therefore, do not change it in the sequence program.

(10) SIEMENS PLC connection
 (a) SIMATIC S7-300 series

Device name		Available range for monitoring
Bit device	Input relay	I0000 to I1277
	Output relay	Q0000 to Q1277
	Bit memory	M0000 to M2557
	GOT bit register	GB64 to GB1023
Word device	Input relay	IW000 to IW126
	Output relay	QW000 to QW126
	Bit memory	MW000 to MW254
	Timer (present value)	T000 to T127
	Counter (present value)	C00 to C63
	Data register	D000100000 to D000108190 D000200000 to D000208190 D000300000 to D000308190 • • • D012600000 to D012608190 D012700000 to D012708190
	GOT data register	GD64 to GD1023

(b) SIMATIC S7-400 series

Device name		Available range for monitoring
Bit device	Input relay	I0000 to I5117
	Output relay	Q0000 to Q5117
	Bit memory	M00000 to M20477
	GOT bit register	GB64 to GB1023
Word device	Input relay	IW000 to IW510
	Output relay	QW000 to QW510
	Bit memory	MW0000 to MW2046
	Timer (present value)	T000 to T511
	Counter (present value)	C000 to C511
	Data register	D000100000 to D000165534 D000200000 to D000265534 D000300000 to D000365534 • • • D409400000 to D409465534 D409500000 to D409565534
	GOT data register	GD64 to GD1023

(11) Microcomputer connection

Device name		Available range for monitoring
Bit device	GOT bit register (GB)	GB64 to GB1023* ¹
	Data register (D)	D0 to D2047
	Bit designation of word device (C)	___* ¹
Word device	Data register (D)	D0 to D2047
	GOT data register (GD)	GD64 to GD1023* ¹

*1 Writing and reading operations are not available from the host to devices GB and GD.

2.3 Monitoring of special function unit

Monitoring of special function unit is limited to the following stations.

- (1) When using bus connection/CPU direct connection/computer link connection
 - The special function modules on the bases of the connected station and other stations can be monitored.
- (2) When using MELSECNET(II) connection/MELSECNET/B connection
 - The special function module on the base of the master station can be monitored. (Cannot be monitored when the master station is the QnACPU.)
 - The special function modules on the bases of local stations cannot be monitored.
- (3) When using MELSECNET/10 connection
 - The special function modules on the bases of the control station and normal stations can be monitored. (Cannot be monitored when the stations are the QnACPU.)
- (4) When using CC-Link connection (remote device station)
 - The special function modules cannot be monitored.
- (5) When using CC-Link connection (intelligent device station)
 - The special function modules on the bases of the master and local stations can be monitored.
- (6) When using the system configuration where remote I/O stations exist
 - The special function modules cannot be monitored in any connection form.

2.4 Access range for monitoring

POINT

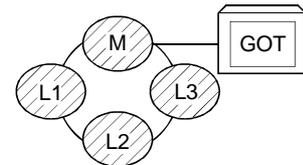
It should be noted that you cannot connect the GOT to monitor a remote I/O station in a network system or data link system.

2.4.1 Data link system access range for monitoring

(1) Bus connection/CPU direct connection/Computer link connection

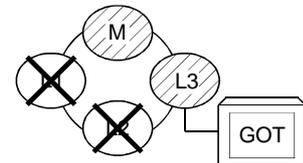
(a) If connected to master station

- Local stations can be monitored. If the PLC CPU of the local station is QnACPU, devices other than B and W that are allocated by the link parameter cannot be monitored.



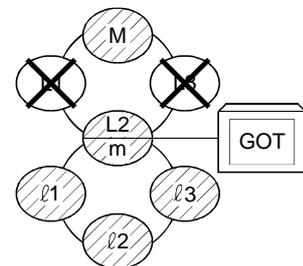
(b) If connected to local station

- The master station can be monitored. If the PLC CPU of the local station is QnACPU, devices other than B and W that are allocated by the link parameter cannot be monitored.
- Other local stations cannot be monitored.



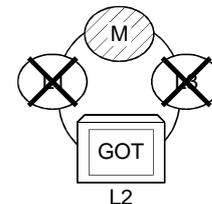
(c) If connected to the master station on the third layer

- The master station on the second layer and local stations on the third layer can be monitored. If the PLC CPU of the local station is QnACPU, devices other than B and W that are allocated by the link parameter cannot be monitored.
- Local stations on the second layer cannot be monitored.



(2) MELSECNET/B connection and MELSECNET(II) connection

- The GOT is regarded as a local station and can monitor only the master station. If the PLC CPU of the local station is QnACPU, devices other than B and W that are allocated by the link parameter cannot be monitored.
- Local devices cannot be monitored.



POINT

For monitoring devices B and W that are allocated by the link parameter, make sure to use the local device number if designating devices allocated to other station. If not, display speed will be reduced.

When setting the monitor device, designate the NW number and the station number as follows.

When monitoring devices B and W that are allocated by the link parameter :

NW number : 0, Station number : Local

When monitoring devices other than B and W of the master station :

NW number : 0, Station number :

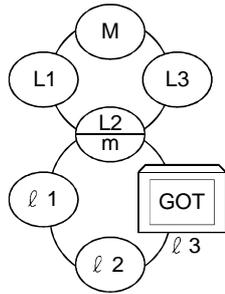
Others (Station number : 0)

(3) Monitoring devices of other stations

If other devices on the data link system are monitored, display speed will be significantly reduced. Therefore monitor link relay (B) and link register (W) that are allocated by the link parameter.

(4) Setting method of monitor device

Describes the NW numbers for setting monitor devices and method of setting station numbers with an example shown below.



POINT
 For monitoring devices B and W that are allocated by the link parameter, make sure to use the local device number if designating devices allocated to other station. If not, display speed will be reduced.

- (a) When monitoring devices B and W that are allocated by the connected station (local station) and link parameter :
 NW number : 0, Station number : Local
- (b) When monitoring devices of other stations :
 NW number : 0, Station number : Refer to the following table.

Station number setting

Station connected to GOT \ Station to be accessed	M	L1	L2 m	L3	l1	l2	l3
M	Local	Other 1	Other 2	Other 3	—	—	—
L1	Other 0	Local	—	—	—	—	—
L2 m	Other 0	—	Local	—	Other 1	Other 2	—
L3	Other 0	—	—	Local	—	—	—
l1	—	—	Other 0	—	Local	—	—
l2	—	—	Other 0	—	—	Local	—
l3(GOT)	—	—	Other 0	—	—	—	—

2.4.2 Network system access range for monitoring

- (1) Bus connection
 - (a) If connected to QCPU(Q Mode)/QnACPU/AnUCPU
 - 1) The control station on the network and all normal stations can be monitored.
 - 2) The control station on the other network and all normal stations can be monitored.
(To monitor the other network, be sure to designate the routing parameter.)
 - 3) If connected to an intermediate station and the data link system is included, the master station and local stations can be monitored.
 - 4) If connected to an intermediate station, it is not necessary to designate the data link parameter "Effective unit number for accessing other stations" for the PLC CPU of the connected station. (If designated, the parameter will be ignored.)
 - 5) Devices of other stations (other than devices B and W that are allocated by the network parameter) may not allow monitoring depending on their PLC CPU.
Refer to Examples 1 to 4.in (7).
 - (b) If connected to AnACPU/AnNCPU
 - 1) Control stations on the network can be monitored.
If the PLC CPU of the local station is QCPU (Q Mode)/QnACPU, devices other than B and W that are allocated by the network parameter cannot be monitored.
 - 2) Normal stations on the network cannot be monitored.
 - 3) Stations on the other network cannot be monitored.
- (2) CPU direct connection/computer link connection
 - (a) If connected to QCPU (Q Mode)/QnACPU
 - 1) Access range is as described in (1) (a).
 - (b) If connected to QCPU (A Mode)/AnUCPU
 - 1) Control station on the network and all normal stations can be monitored.
When devices of other stations (other than devices B and W that are allocated by the network parameter) are monitored, monitoring is not available if the PLC CPU to be monitored is QCPU (Q Mode)/QnACPU.
 - 2) If connected to an intermediate station, use data link parameter "Effective unit number to access other stations" to designate the unit number that is connected to the network to be monitored.
 - (c) If connected to AnACPU/AnNCPU
 - 1) Control stations on the network can be monitored.
If the PLC CPU of the control station is QCPU (Q Mode)/QnACPU, devices other than B and W that are allocated by the network parameter cannot be monitored.
 - 2) Normal stations on the network cannot be monitored.
 - 3) The other network cannot be monitored.
- (3) CC-Link connection (intelligent device station)
 - Connected stations can be monitored.
 - Other stations on the network system cannot be monitored.

(4) MELSECNET/10 connection

- (a) The GOT is regarded as a normal station. The control station on the network and all normal stations can be monitored.
If the PLC CPU to be monitored is QCPU (Q Mode)/QnACPU, monitoring is available within the device access range for AnA. (The access range for monitoring of timer (T) and counter (C) is limited to 0 to 225. File registers (R, ER, ZR) cannot be monitored.)
- (b) The other network cannot be monitored.
- (c) If devices of other stations (other than devices B and W that are allocated by the network parameter) are monitored, monitoring may not be available depending on the PLC CPU of the network system to be monitored. Refer to (Example 6).

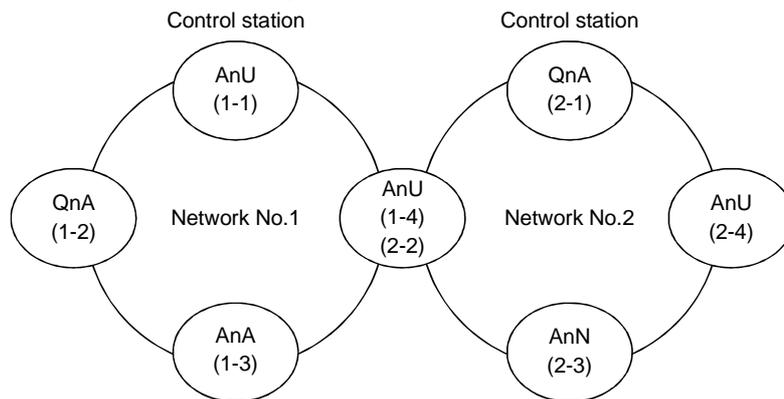
(5) Monitoring devices of other stations on network

If devices of other stations on the network system are monitored, display speed will be significantly reduced. Therefore monitor link relay (B) and link register (W) that are allocated by the network parameter.

(6) Monitoring devices of the other network

- (a) Be sure to designate the routing parameter to the PLC CPU of the connected station.
- (b) If the other network is monitored, display speed of sprite etc. will be significantly reduced.

(7) Monitor access range of other stations and setting method of monitor devices (Example 1) When using bus connection



• Monitor access range of other station devices (other than B and W)/other network

Station connected to GOT	Network No.1				Network No.2			
	AnU (1-1)	QnA (1-2)	AnA (1-3)	AnU (1-4)	QnA (2-1)	AnU (2-2)	AnN (2-3)	AnU (2-4)
AnU (1-1)	○ Local	×	○	○	×	○	×	○
QnA (1-2)	○	○ Local	×	○	○	○	×	○
AnA (1-3)	○	×	○ Local	×	×	×	×	×
AnU (1-4) (2-2)	○	×	×	○ Local	×	○ Local	×	○
QnA (2-1)	○	○	×	○	○ Local	○	○	○
AnN (2-3)	×	×	×	×	×	×	○ Local	×
AnU (2-4)	○	×	×	○	×	○	×	○ Local

○ : Accessible × : Not accessible

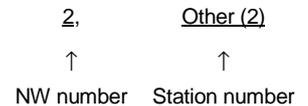
POINT

For monitoring devices B and W that are allocated by the network parameter, make sure to use the local device number if designating devices allocated to other station. If not, display speed will be reduced.

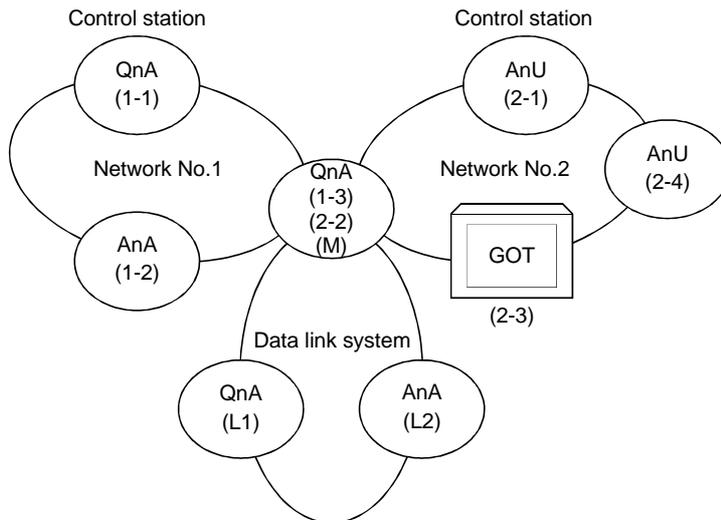
- Designating NW number and station number for setting monitor device
 - 1) Monitoring devices B and W that are allocated by the network parameter at the connected station (local station)
NW number: 0, Station number: Local
 - 2) When monitoring other stations (other than B and W)/other network

Station connected to GOT	Network No.1				Network No.2			
	AnU (1-1)	QnA (1-2)	AnA (1-3)	AnU (1-4)	QnA (2-1)	AnU (2-2)	AnN (2-3)	AnU (2-4)
AnU (1-1)	0, Local	—	1, Other (3)	1, Other (4)	—	2, Other (2)	—	2, Other (4)
QnA (1-2)	1, Other (1)	0, Local	—	1, Other (4)	2, Other (1)	2, Other (2)	—	2, Other (4)
AnA (1-3)	0, Other (0)	—	0, Local	—	—	—	—	—
AnU (1-4) (2-2)	1, Other (1)	—	—	0, Local	—	0, Local	—	2, Other (4)
QnA (2-1)	1, Other (1)	1, Other (2)	—	1, Other (4)	0, Local	2, Other (2)	2, Other (3)	2, Other (4)
AnN (2-3)	—	—	—	—	—	—	0, Local	—
AnU (2-4)	1, Other (1)	—	—	1, Other (4)	—	2, Other (2)	—	0, Local

How to read the table



(Example 2) When using bus connection



- Monitor access range of other station devices (other than B and W)/other network

Station connected to GOT	Network No.1				Network No.2			Data link system		
	QnA (1-1)	AnA (1-2)	QnA (1-3)	AnU (2-1)	QnA (2-2)	GOT (2-3)	AnU (2-4)	QnA (M)	QnA (L1)	AnA (L2)
QnA (1-1)	○ Local	○	○	○	○	—	○	○	×	×
AnA (1-2)	×	○ Local	×	×	×	—	×	×	×	×
QnA (1-3) (2-2) (M)	○	×	○ Local	○	○ Local	—	○	○ Local	×	○
AnU (2-1)	×	×	×	○ Local	×	—	○	×	×	×
GOT (2-3)	×	×	×	○	△	—	○	△	×	×
AnU (2-4)	×	×	×	○	×	—	○ Local	×	×	×
QnA (L1)	×	×	×	×	×	—	×	×	○ Local	×
AnA (L2)	×	×	×	×	×	—	×	×	×	○ Local

○ : Accessible △ : Accessible within the range for AnA (T/C: 0 to 255, R/ER/ZR cannot be monitored)
 × : Not accessible

POINT
 For monitoring devices B and W that are allocated by the network parameter, make sure to use the local device number if designating devices allocated to other station. If not, display speed will be reduced.

- Designating NW number and station number for setting monitor device
 - 1) When monitoring devices B and W that are allocated by the network parameter at the connected station (local station)
 NW number: 0, Station number: Local station
 - 2) When monitoring other stations (other than B and W)/other network

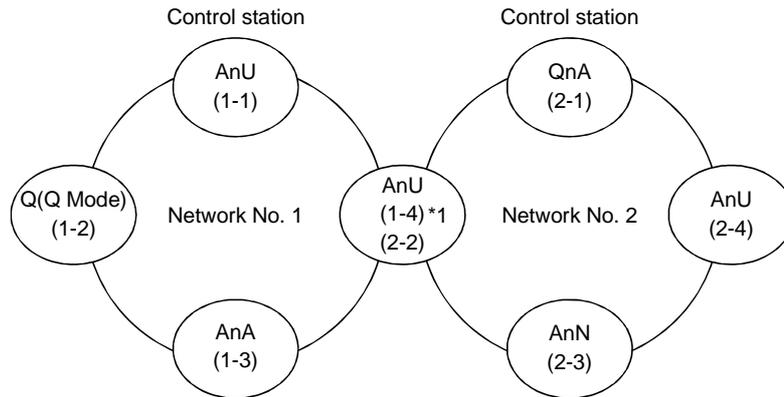
Station connected to GOT	Station to be accessed		Network No.1				Network No.2			Data link system		
	QnA (1-1)	AnA (1-2)	QnA (1-3)	AnU (2-1)	QnA (2-2)	GOT (2-3)	AnU (2-4)	QnA (M)	QnA (L1)	AnA (L2)		
QnA (1-1)	0, Local	1, Other (2)	1, Other (3)	2, Other (1)	2, Other (2)	—	2, Other (4)	1, Other (3) or 2, Other (2)	—	—		
AnA (1-2)	—	0, Local	—	—	0, Local	—	—	—	—	—		
QnA (1-3)	1, Other (1)	—	0, Local	2, Other (1)	—	—	2, Other (4)	0, Local	—	0, Other (2) *1		
QnA (2-2)	—	—	—	0, Local	—	—	2, Other (4)	—	—	—		
AnU (2-1)	—	—	—	0, Local	—	—	2, Other (4)	—	—	—		
GOT (2-3)	—	—	—	0, Other (1)	0, Other (2)	—	0, Other (4)	0, Other (2)	—	—		
AnU (2-4)	—	—	—	2, Other (1)	—	—	0, Local	—	—	—		
QnA (L1)	—	—	—	—	—	—	—	—	0, Local	—		
AnA (L2)	—	—	—	—	—	—	—	—	—	0, Local		

*1 When monitoring the data link system, designate the NW number as 0.

How to read the table

2,	<u>Other (2)</u>
↑	↑
NW number	Station number

(Example 3) When using CPU direct connection or computer link connection



*1 Data link parameter "Effective unit number for accessing other stations" is designated to the unit number that is connected to the network No. 1.

- Monitor access range of other station devices (other than B and W)/other network

Station to be accessed Station connected to GOT	Network No.1				Network No.2			
	AnU (1-1)	Q(Q Mode) (1-2)	AnA (1-3)	AnU (1-4)	QnA (2-1)	AnU (2-2)	AnN (2-3)	AnU (2-4)
AnU (1-1)	○ Local	×	○	○	×	○	×	×
Q(Q Mode) (1-2)	○	○ Local	×	○	○	○	×	○
AnA (1-3)	○	×	○ Local	×	×	×	×	×
AnU (1-4) (2-2)	○	×	×	○ Local	×	○ Local	×	×
QnA (2-1)	○	○	×	○	○ Local	○	○	○
AnN (2-3)	×	×	×	×	×	×	○ Local	×
AnU (2-4)	×	×	×	×	×	○	×	○ Local

○ : Accessible × : Not accessible

POINT
For monitoring devices B and W that are allocated by the network parameter, make sure to use the local device number if designating devices allocated to other station. If not, display speed will be reduced.

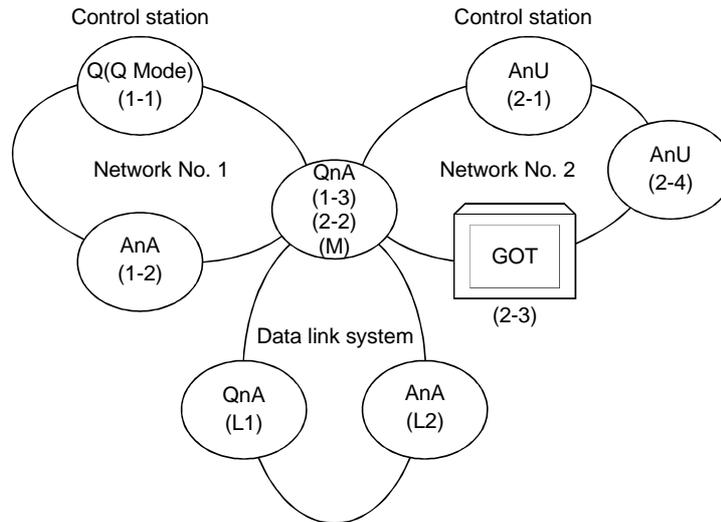
- Designating NW number and station number for setting monitor device
 - 1) Monitoring devices B and W that are allocated by the network parameter at the connected station (local station)
NW number: 0, Station number: Local
 - 2) When monitoring other stations (other than B and W)/other network

Station to be accessed Station connected to GOT	Network No.1				Network No.2			
	AnU (1-1)	Q(Q Mode) (1-2)	AnA (1-3)	AnU (1-4)	QnA (2-1)	AnU (2-2)	AnN (2-3)	AnU (2-4)
AnU (1-1)	0, Local	—	0, Other (3)	0, Other (4)	—	0, Other (4)	—	—
Q(Q Mode) (1-2)	1, Other (1)	0, Local	—	1, Other (4)	2, Other (1)	2, Other (2)	—	2, Other (4)
AnA (1-3)	0, Other (0)	—	0, Local	—	—	—	—	—
AnU (1-4) (2-2)	0, Other (1)	—	—	0, Local	—	0, Local	—	—
QnA (2-1)	1, Other (1)	1, Other (2)	—	1, Other (4)	0, Local	2, Other (2)	2, Other (3)	2, Other (4)
AnN (2-3)	—	—	—	—	—	—	0, Local	—
AnU (2-4)	—	—	—	—	—	0, Other (2)	—	0, Local

How to read the table

2, Other (2)
 ↑ ↑
 NW number Station number

(Example 4) When using CPU direct connection or computer link connection



• Monitor access range of other station devices (other than B and W)/other network

Station connected to GOT \ Station to be accessed	Network No.1			Network No.2				Data link system		
	Q(Q Mode) (1-1)	AnA (1-2)	QnA (1-3)	AnU (2-1)	QnA (2-2)	GOT (2-3)	AnU (2-4)	QnA (M)	QnA (L1)	AnA (L2)
Q(Q Mode) (1-1)	○ Local	○	○	○	○	—	○	○	×	×
AnA (1-2)	×	○ Local	×	×	×	—	×	×	×	×
QnA (1-3), (2-2), (M)	○	×	○ Local	○	○ Local	—	○	○ Local	×	○
AnU (2-1)	×	×	×	○ Local	×	—	○	×	×	×
GOT (2-3)	×	×	×	○	△	—	○	△	×	×
AnU (2-4)	×	×	×	○	×	—	○ Local	×	×	×
QnA (L1)	×	×	×	×	×	—	×	×	○ Local	×
AnA (L2)	×	×	×	×	×	—	×	×	×	○ Local

○ : Accessible △ : Accessible within the range for AnA (T/C: 0 to 255, R/ER/ZR cannot be monitored)
 × : Not accessible

POINT
 For monitoring devices B and W that are allocated by the network parameter, make sure to use the local device number if designating devices allocated to other station. If not, display speed will be reduced.

- Designating NW number and station number for setting monitor device
 - 1) When monitoring devices B and W that are allocated by the network parameter at the connected station (local station)
 NW number: 0, Station number: Local station
 - 2) When monitoring other stations (other than B and W)/other network

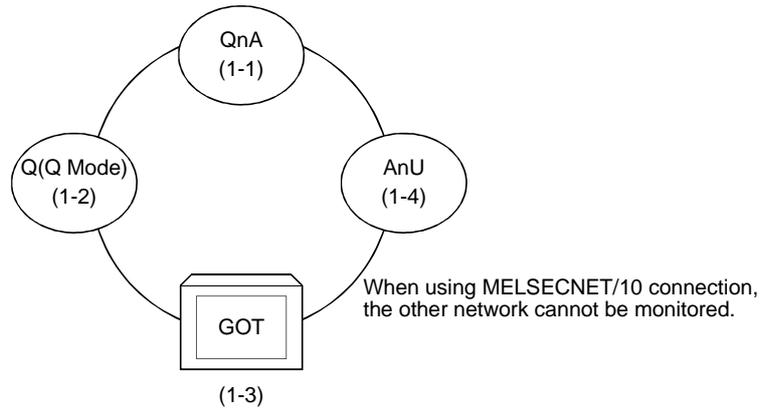
Station connected to GOT	Station to be cessed	Network No.1			Network No.2				Data link system		
		Q(Q Mode) (1-1)	AnA (1-2)	QnA (1-3)	AnU (2-1)	QnA (2-2)	GOT (2-3)	AnU (2-4)	QnA (M)	QnA (L1)	AnA (L2)
Q(Q Mode) (1-1)		0, Local	1, Other (2)	1, Other (3)	2, Other (1)	2, Other (2)	—	2, Other (4)	1, Other (3) or 2, Other (2)	—	—
AnA (1-2)		—	0, Local	—	—	—	—	—	—	—	—
QnA (2-2) (M)		1, Other (1)	—	0, Local	2, Other (1)	0, Local	—	2, Other (4)	0, Local	—	0, Other (2) *1
AnU (2-1)		—	—	—	0, Local	—	—	2, Other (4)	—	—	—
GOT (2-3)		—	—	—	0, Other (1)	0, Other (2)	—	0, Other (4)	0, Other (2)	—	—
AnU (2-4)		—	—	—	2, Other (1)	—	—	0, Local	—	—	—
QnA (L1)		—	—	—	—	—	—	—	—	0, Local	—
AnA (L2)		—	—	—	—	—	—	—	—	—	0, Local

*1 When monitoring the data link system, designate the NW number as 0.

How to read the table

2,	<u>Other (2)</u>
↑	↑
NW number	Station number

(Example 5) When using MELSECNET/10 connection



• Monitor access range for other station devices (other than B and W)

Station connected to GOT	Station to be accessed	QnA (1-1)	Q(Q Mode) (1-2)	GOT (1-3)	AnU (1-4)
GOT (1-3)		△	△	—	○

○ : Accessible
 △ : Accessible within the range of AnA (T/C: 0 to 255, R/ER/ZR cannot be monitored.)
 × : Not accessible

POINT

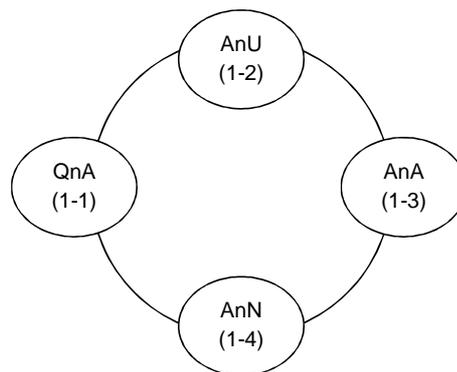
For monitoring devices B and W that are allocated by the network parameter, make sure to use the local device number if designating devices allocated to other station. If not, display speed will be reduced.

- Designating NW number and station number for setting monitor device
 - 1) Monitoring devices B and W that are allocated by network parameter
 NW number: 0, Station number: Local
 - 2) Monitoring other stations (other than B and W)

Station connected to GOT	Station to be accessed	QnA (1-1)	Q(Q Mode) (1-2)	GOT (1-3)	AnU (1-4)
GOT (1-3)		0, Other (1)	0, Other (2)	—	0, Other (4)

How to read the table 0, Other (2)
 NW number Station number

(Example 6) When using CC-Link connection (intelligent device station)



Station connected to GOT	Station to be accessed	QnA (1-1)	AnU (1-2)	AnA (1-3)	AnN (1-4)
QnA (1-1)		×	×	×	×
AnU (1-2)		×	○	×	×
AnA (1-3)		×	×	○	×
AnN (1-4)		×	×	×	○

○ : Accessible
 × : Not accessible

2.4.3 CC-Link system access range for monitoring

- (1) When using Bus connection/CPU direct connection/computer link connection
Only connected stations can be monitored.
- (2) When using CC-link connection (remote device station)
- (a) Access range
Devices RX, RY, RWw, RWr for which the GOT is allocated to the master station by setting the CC-Link parameter and the internal device of the GOT can be monitored.
Other devices RX, RY, RWw, RWr allocated to the master station cannot be monitored.
- (b) Designating NW number and station number
Be sure to designate as follows.
NW number:0, Station number: Local
- (c) Designating device name and device number
Use the following device names.
For devices RX, RY, RWw and RWr, designate the addresses allocated by station number setting.

Device to be monitored		Device name to be set by drawing software	Device setting range
Remote input	RX	X	X0 to X7FF
Remote output	RY	Y	Y0 to Y7FF
Remote register (writing area)	RWw	Ww	Ww0 to WwFF
Remote register (reading area)	RWr	Wr	Wr0 to WrFF
GOT internal bit device	GB	GB	GB0 to GB1023
GOT internal word device	GD	GD	GD0 to GD1023

(3) When using CC-Link connection (intelligent device station)

(a) Access range

Master station/local station can be monitored.

By setting CC-Link parameter, all devices RX, RY, RWw and RWr that are allocated to the master station can be monitored.

POINT

For monitoring devices RX, RY, RWw and RWr that are allocated by setting CC-Link parameter, make sure to use the local device number if designating devices allocated to other station. If not, display speed will be reduced.

(b) Setting NW number and station number

1) When monitoring devices RX, RY, RWw and RWr that are allocated to the master station by setting CC-Link parameter

NW number: 0, PLC station number: Local

2) When monitoring PLC CPU devices of other station

NW number: 0, PLC station number: Other (Station number: n)

(n: Station number of other station you want to monitor (0: Master station, 1-64: Local station))

(c) Setting device name and device number

1) Monitoring devices RX, RY, RWw and RWr that are allocated by setting CC-Link parameter

Use the following device names.

For devices RX, RY, RWw and RWr, designate the addresses allocated by station number setting.

Device to be monitored		Device name to be set by drawing software	Device setting range
Remote input	RX	X	X0 to X7FF
Remote output	RY	Y	Y0 to Y7FF
Remote register (writing area)	RWw	Ww	Ww0 to WwFF
Remote register (reading area)	RWr	Wr	Wr0 to WrFF

2) Monitoring PLC CPU devices of other stations

For device name and device number, refer to 2.2.

2.4.4 Access range for monitoring when using MELSEC-FXCPU, other PLC and microcomputer connections

Only the connected CPU can be monitored. Other stations cannot be monitored.

Chapter3 Bus connection

3.1 First step in bus connection

POINT	<p>If the GOT, where the basic function OS and the PLC communication driver for QCPU (Q mode) bus connection are not installed, is bus-connected with the QCPU (Q mode), the QCPU will be reset, disabling communications with the QCPU using GPPW or the like.</p> <p>In this case, disconnecting the bus connection cable of the GOT cancels the resetting of the QCPU.</p>
-------	---

3.1.1 GOT handling from PLC CPU in bus connection

GOT handling as viewed from PLC CPU is described below.

(1) Connection with QCPU (Q mode)

The PLC CPU recognizes the GOT as a 16 I/O point intelligent function module. Hence, the GOT must be assigned to the empty points of the PLC CPU. The GOT occupies one extension stage (16 points * 10 slots) of the PLC CPU and can be assigned to the occupation location. (Cannot be assigned to the main/extension bases.)

(2) Connection with other than QCPU (Q mode)

The PLC CPU recognizes the GOT as a 32 I/O point special function module. Hence, the GOT must be assigned to the empty points of the PLC CPU. The GOT can be assigned to the location of empty points within the maximum I/O points of the PLC CPU, excluding those of the main base. (Cannot be assigned to the main base.)

3.1.2 Restriction on the number of GOTs by the PLC CPU connected to

In bus connection, note that the number of GOTs connected is restricted by the PLC CPU connected to and the number of special function modules loaded.

CPU Connected To		Number of Connectable GOTs	Total Number of GOTs and Special Function Modules*1 Connectable
QCPU (Q mode)		Max. 5	GOTs 5 + Special Function Modules 6 *2
QCPU (A mode)		Not connectable	——
QnACPU		Max. 3	6 in all
ACPU	AnUCPU,AnACPU,A2US(H)CPU	Max. 3	6 in all
	AnNCPU,AnS(H)CPU,A1SJ(H)CPU	Max. 2	2 in all
	A0J2HCPU	Max. 1	2 in all
	A1FXCPU	Not connectable	——
Motion controller CPU	A273U(H)CPU, A273UHCPU-S3, A373UCPU(-S3),A173UHCPU	Max. 3	6 in all
	A171SCPU-S3,A171SHCPU,A172SHCPU	Max. 2	2 in all

*1 Indicates the following types of special function modules.
 AD51(S3),AD51H(S3),AD51FD(S3),AD57G(S3),AJ71C21(S1),AJ71C22(S1),AJ71C23, AJ71C24(S3/S6/S8),AJ71E71(-S3),AJ71UC24,A1SJ71C24(-R2/PRF/R4), A1SJ71UC24(-R2/PRF/R4),A1SJ71E71-B2/B5(-S3),A1SD51S

*2 It should be only A1SD51S that the special function modules cannot be connected to the QCPU (Q mode).

3.1.3 Power supply of PLC CPU and GOT

Note the following when supplying power to the PLC CPU and GOT.

 CAUTION	<ul style="list-style-type: none"> • To prevent trouble from occurring, the extension cable which connects the PLC CPU and GOT should be unplugged when the PLC CPU and GOT are off.
--	---

- (1) Precautions for switching power on
 Switch on the PLC CPU and GOT in either of the following methods. (This also applies to the case where several GOTs are connected.)
 - (a) Switch on the PLC CPU and GOT at the same time.
 - (b) Switch on the PLC CPU and GOT in this order.
 Switching on the GOT runs the PLC CPU.
 When several GOTs are connected, there is no specific sequence of switching on the GOTs.
 Switching on all GOTs runs the PLC CPU.

- (2) Precautions for switching off the PLC CPU
 Switching off the PLC CPU during monitoring will cause a communication error in the GOT.
 When a communication error has occurred, switch off the GOT and switch on the PLC CPU and GOT in the method in above (1).

- (3) Precautions for switching off the GOT
 If the GOT is switched off during monitoring, the PLC CPU continues running.

- (4) Precautions for system design
 In the status described in above (3), the GOT does not operate but the PLC CPU (power supply module of the main base unit) supplies the following consumptive current to the GOT.
 Hence, design the system so that the sum of the 5VDC consumptive currents of the modules installed on the main base unit and the GOT consumptive currents does not exceed the 5VDC rated output current (8A) of the power supply module.

CPU Connected To	Number of GOTs Connected	Total Consumptive Current [mA]
Connection with QCPU (Q mode)	5	1275
	4	1020
	3	765
	2	510
	1	255
Connection with other than QCPU (Q mode)	3	660
	2	440
	1	220

3.1.4 Restriction when PLC CPU is used in direct method

Note that the inputs X of the empty slots cannot be used when the I/O control system of the PLC CPU to be connected to is the direct method and a 5m extension cable (AC50B(-R), A1SC50NB) is used to connect the first GOT and main/extension base unit.

There are no restrictions when the I/O control system is the refresh method. When the PLC CPU allows the I/O control system to be changed with the switch, use it in the refresh method.

POINT
<p>The following examples indicate how to use the inputs X of the empty slots.</p> <ul style="list-style-type: none"> • Inputs X are assigned in a MELSECNET(II/B) data link or MELSECNET/10 network. • The receive data of a MELSECNET/MINI-S3 data link is read to inputs X under the FROM instruction. • The inputs X of the empty slots are switched on/off from a computer link unit. • The inputs X of the empty slots are switched on/off with the touch switch function (bit SET/RST/alternate/momentary) of the GOT.

3.1.5 Precautions for use of A1SJCPU and A1SJHCPU

Note that the GOT cannot be used when an extension base unit is connected to the A1SJCPU or A1SJHCPU.

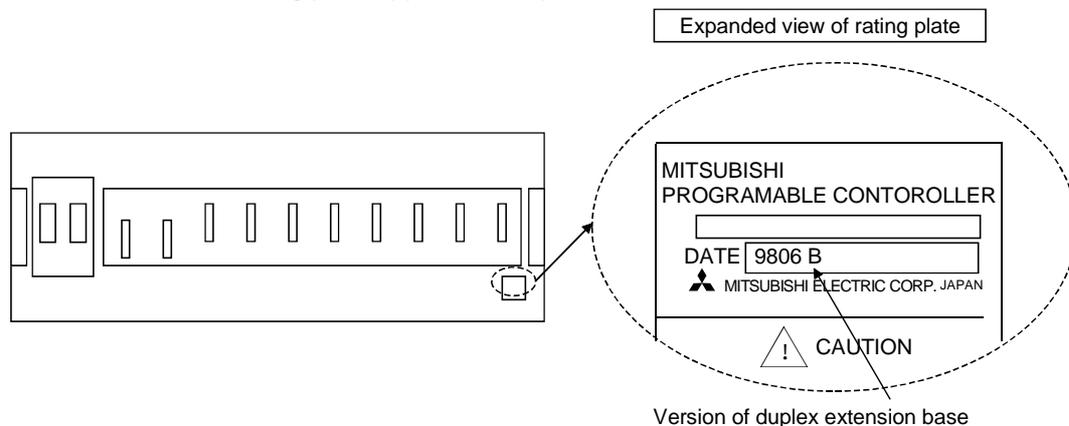
3.1.6 Precautions for GOT connection in duplex system

Note the following when bus-connecting the GOT to the duplex system of the Q4ARCPU.

When connecting the GOT to a duplex system, connect the GOT to the duplex extension base (A68RB) in the last stage of the duplex system.

Also, use the duplex extension base of version B or later.

For the way of confirming the version of the duplex extension base, refer to the DATE column of the rating plate applied to the portion show below.



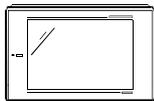
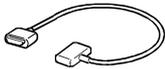
POINT
<p>The GOT will not operate properly in the following system configurations.</p> <ul style="list-style-type: none"> • The GOT is bus-connected to the duplex main base (A32RB, A33RB) • The GOT is bus-connected to the duplex extension base (A68RB) of version A

3.2 System configuration

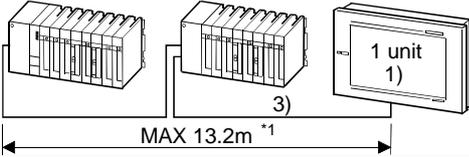
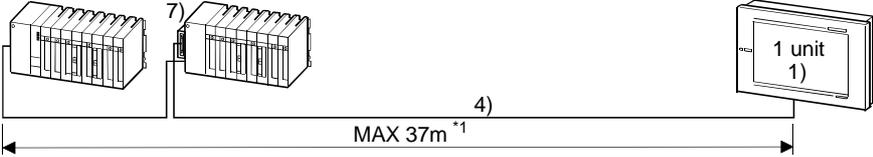
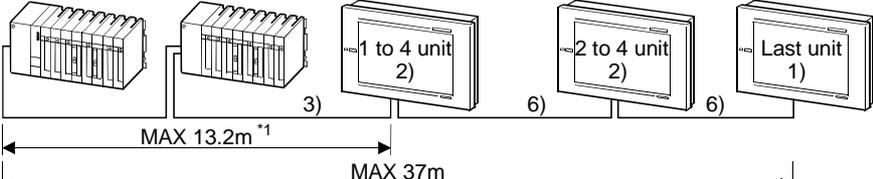
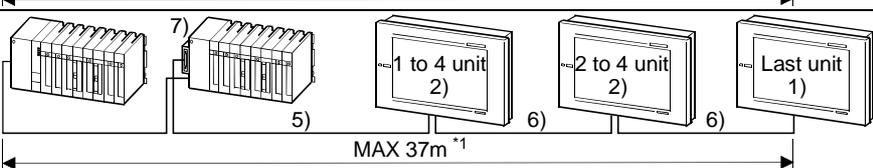
The bus connection system configuration changes with such conditions as the CPU connected to, number of GOTs connected, and GOT installation distance. This section gives various system configurations.

3.2.1 Connection with QCPU (Q mode)

The numbers indicated in the system configurations shown below indicate the following equipment.

Item	Sketch	Number	System Equipment (Module Type)
GOT		1)	A985GOT/A97*GOT/A960GOT + A9GT-QBUSS/A9GT-QBUS2S A956GOT + A9GT-QBUS2SU A951GOT-Q
		2)	A985GOT/A97*GOT/A960GOT + A9GT-QBUS2S A956GOT + A9GT-QBUS2SU
		3)	QC06B(0.6m)/QC12B(1.2m)/QC30B(3m)/QC50B(5m)/QC100B(10m)
Connection cable		4)	A9GT-QC150BS(15m)/A9GT-QC200BS(20m)/A9GT-QC250BS(25m)/ A9GT-QC300BS(30m)/A9GT-QC350BS(35m)
		5)	A9GT-QC150BS(15m)/A9GT-QC200BS(20m)/A9GT-QC250BS(25m)/ A9GT-QC300BS(30m)
		6)	QC06B(0.6m)/QC12B(1.2m)/QC30B(3m)/QC50B(5m)/QC100B(10m)/ A9GT-QC150BS(15m)/A9GT-QC200BS(20m)/A9GT-QC250BS(25m)/ A9GT-QC300BS(30m)
		7)*1	A9GT-QCNB

*1 In the system configuration which uses the A9GT-QCNB, the same STAGE No. as that of the GOT must be set to the A9GT-QCNB. For the setting of the STAGE No., refer to Section 3.3.

Number of GOTs Connected	Installation Distance	System Configuration
1	Within 13.2m	
	More than 13.2m	
2 to 5	First GOT is within 13.2m	
	First GOT is more than 13.2m	

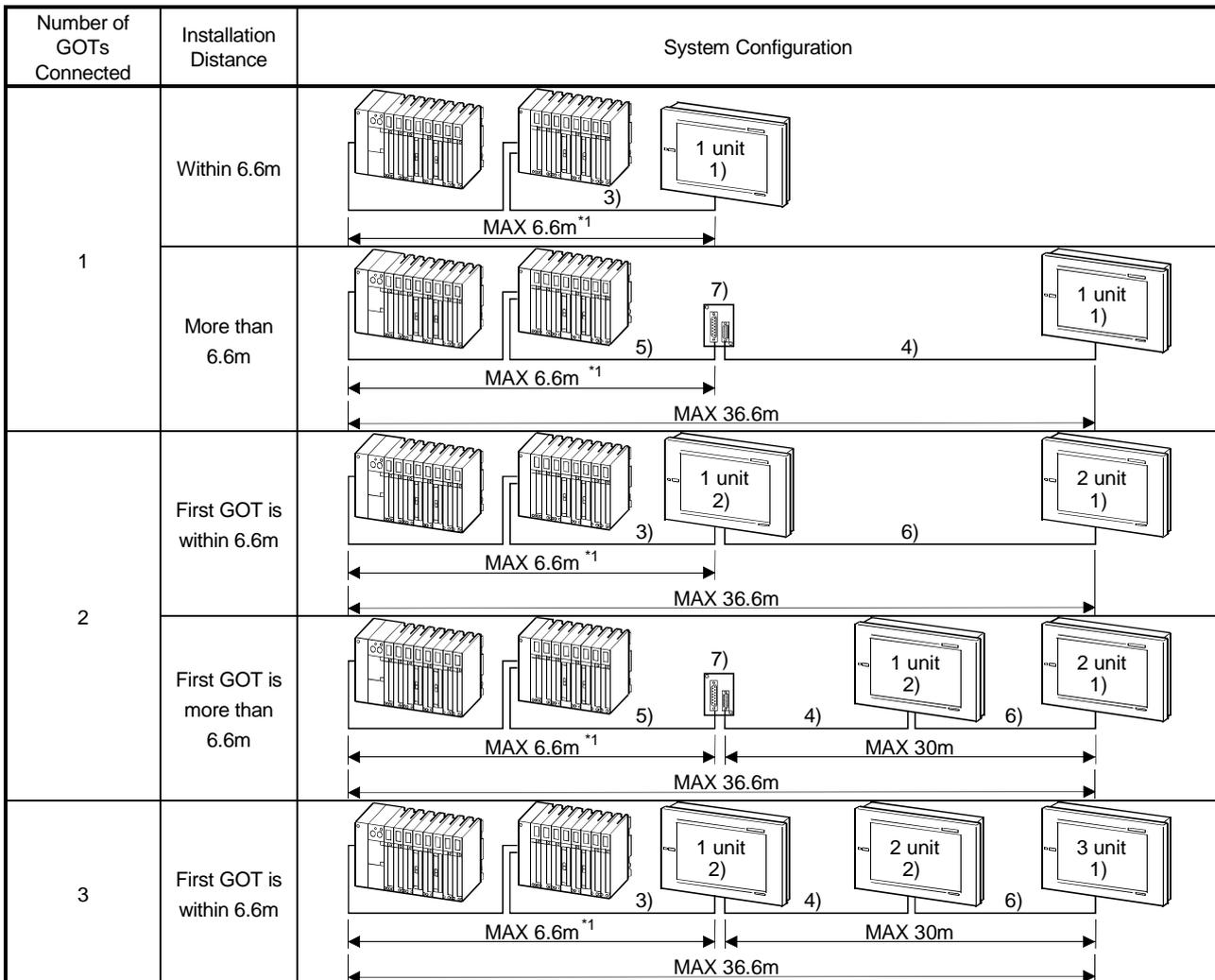
*1 When using an extension base unit, this distance includes the extension cable length (between base units).

3.2.2 Connection with QnACPU (large type) or ACPUCPU (large type)

The numbers indicated in the system configurations shown below indicate the following equipment.

Item	Sketch	Number	System Equipment (Module Type)	
GOT		1)	A985GOT/A97*GOT/A960GOT + A9GT-BUSS/A9GT-BUS2S/A9GT-BUSSU/A9GT-BUS2SU	
			A956GOT + A9GT-BUSSU/A9GT-BUS2SU/A7GT-BUSS/A7GT-BUS2S	
			A951GOT	
Connection cable		2)	A985GOT/A97*GOT/A960GOT + A9GT-BUS2S/A9GT-BUS2SU	
			A956GOT + A9GT-BUS2SU/A7GT-BUS2S	
			3)	A8GT-C12NB(1.2m)/A8GT-C30NB(3m)/A8GT-C50NB(5m)
				A8GT-C100EXSS(10m)/A8GT-C200EXSS(20m)/A8GT-C300EXSS(30m)
4)*1	AC06B(0.6m)/AC12B(1.2m)/AC12B-R(1.2m)/AC30B(3m)/AC30B-R(3m)/AC50B(5m)/AC50B-R(5m)			
	A1SC07B(0.7m)/A1SC12B(1.2m)/A1SC30B(3m)/A1SC50B(5m)/A8GT-C100BS(10m)/A8GT-C200BS(20m)/A8GT-C300BS(30m)			
Bus connector conversion box		7)	A7GT-CNB	

*1 When using the bus connection cable (A8GT-C100EXSS, A8GT-C200EXSS, A8GT-C300EXSS), plug the connectors of the connection cable as indicated below.
 Connector "COM1" — " PLC CPU side
 Connector "COM2" — " GOT side



*1 When using an extension base unit, this distance includes the extension cable length (between base units).

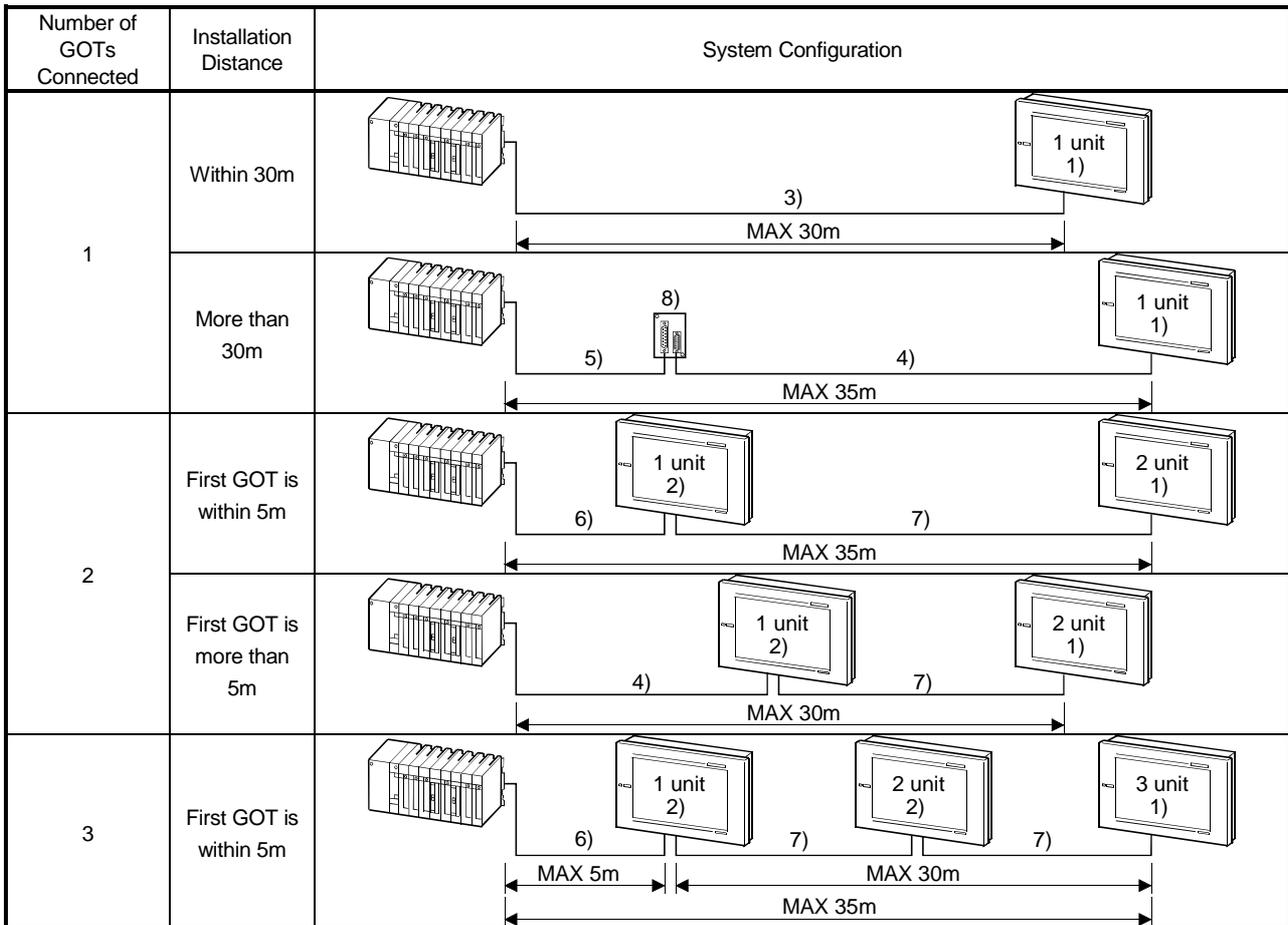
3.2.3 Connection with QnACPU (small type) or ACPU (small type)

The numbers indicated in the system configurations shown below indicate the following equipment.

Item	Sketch	Number	System Equipment (Module Type)	
GOT		1)	A985GOT/A97*GOT/A960GOT + A9GT-BUSS/A9GT-BUS2S/A9GT-BUSSU/A9GT-BUS2SU	
			A956GOT + A9GT-BUSSU/A9GT-BUS2SU/A7GT-BUSS/A7GT-BUS2S	
			A951GOT	
Connection cable		2)	A985GOT/A97*GOT/A960GOT + A9GT-BUS2S/A9GT-BUS2SU	
			A956GOT + A9GT-BUS2SU/A7GT-BUS2S	
		3)*1	A1SC07B(0.7m)/A1SC12B(1.2m)/A1SC30B(3m)/A1SC50B(5m)/A8GT-C100EXSS(10m)/A8GT-C200EXSS(20m)/A8GT-C300EXSS(30m)	
			4)*1	A8GT-C100EXSS(10m)/A8GT-C200EXSS(20m)/A8GT-C300EXSS(30m)
			5)*2	A1SC05NB(0.5m)/A1SC07NB(0.7m)/A1SC30NB(3m)/A1SC50NB(5m)
6)	A1SC07B(0.7m)/A1SC12B(1.2m)/A1SC30B(3m)/A1SC50B(5m)			
7)	A1SC07B(0.7m)/A1SC12B(1.2m)/A1SC30B(3m)/A1SC50B(5m)/A8GT-C100BS(10m)/A8GT-C200BS(20m)/A8GT-C300BS(30m)			
Bus connector conversion box		8)	A7GT-CNB	

*1 When using the bus connection cable (A8GT-C100EXSS, A8GT-C200EXSS, A8GT-C300EXSS), plug the connectors of the connection cable as indicated below.
 Connector "COM1" — " PLC CPU side
 Connector "COM2" — " GOT side

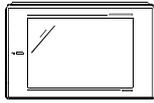
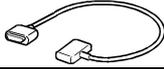
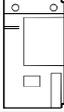
*2 When using an extension base unit, the total cable length of the extension cable (between main base and extension base) and bus connection cable (this cable) should be within 6m.

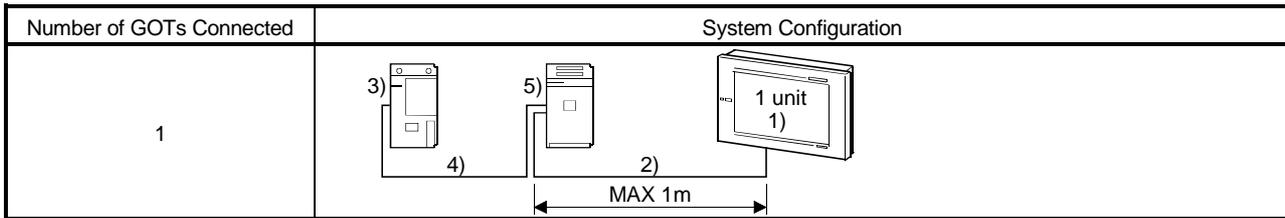


*1 When using an extension base unit, this distance includes the extension cable length (between base units).

3.2.4 Connection with A0J2HCPU

The numbers indicated in the system configurations shown below indicate the following equipment.

Item	Sketch	Number	System Equipment (Module Type)
GOT		1)	A985GOT/A97*GOT/A960GOT + A9GT-BUSS/A9GT-BUS2S/A9GT-BUSSU/A9GT-BUS2SU
			A956GOT + A9GT-BUSSU/A9GT-BUS2SU/A7GT-BUSS/A7GT-BUS2S
			A951GOT
Connection cable		2)	A9GT-J2C10B(1m)
CPU		3)	A0J2HCPU
I/O cable		4)	A0J2C**
Power supply module		5)	A0J2-PW



3.2.5 Connection with motion controller CPU

(1) Connection with A273U(H)CPU, A273UHCPU-S3, A373UCPU(-S3) or A173UHCPU
 The numbers indicated in the system configurations shown below indicate the following equipment.

Item	Sketch	Number	System Equipment (Module Type)
GOT		1)	A985GOT/A97*GOT/A960GOT + A9GT-BUSS/A9GT-BUS2S/A9GT-BUSSU/A9GT-BUS2SU
			A956GOT + A9GT-BUSSU/A9GT-BUS2SU/A7GT-BUSS/A7GT-BUS2S
			A951GOT
		2)	A985GOT/A97*GOT/A960GOT + A9GT-BUS2S/A9GT-BUS2SU
A956GOT + A9GT-BUS2SU/A7GT-BUS2S			
Connection cable		3)*1	A370C12B-S1(1.2m)/A370C25B-S1(2.5m)
		4)*1	A370C12B(1.2m)/A370C25B(2.5m)
		5)	AC06B(0.6m)/AC12B(1.2m)/AC12B-R(1.2m)/AC30B(3m)/AC30B-R(3m)/AC50B(5m)/AC50B-R(5m)
		6)*2	A8GT-C100EXSS(10m)/A8GT-C200EXSS(20m)/A8GT-C300EXSS(30m)
		7)	A1SC07B(0.7m)/A1SC12B(1.2m)/A1SC30B(3m)/A1SC50B(5m)/A8GT-C100BS(10m)/A8GT-C200BS(20m)/A8GT-C300BS(30m)
		8)	A8GT-C12NB(1.2m)/A8GT-C30NB(3m)/A8GT-C50NB(5m)
Bus connector conversion box		9)	A7GT-CNB

*1 Plug the connection cable to the PLC extension-dedicated connector.

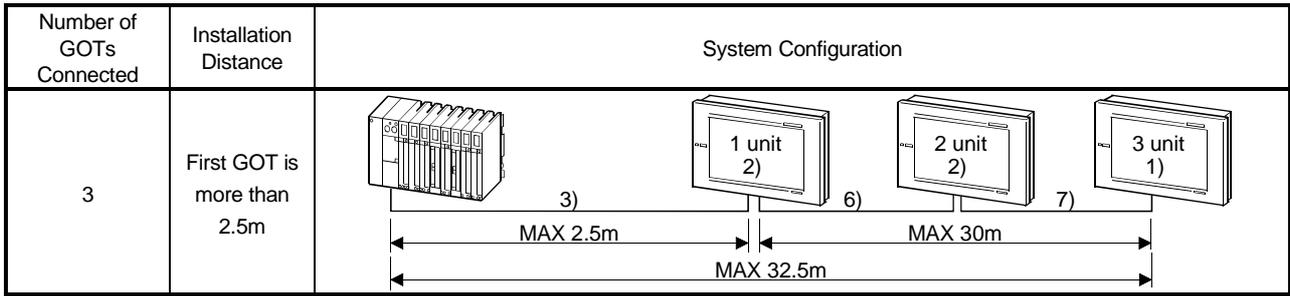
*2 When using the bus connection cable (A8GT-C100EXSS, A8GT-C200EXSS, A8GT-C300EXSS), plug the connectors of the connection cable as indicated below.

Connector "COM1" — " PLC CPU side

Connector "COM2" — " GOT side

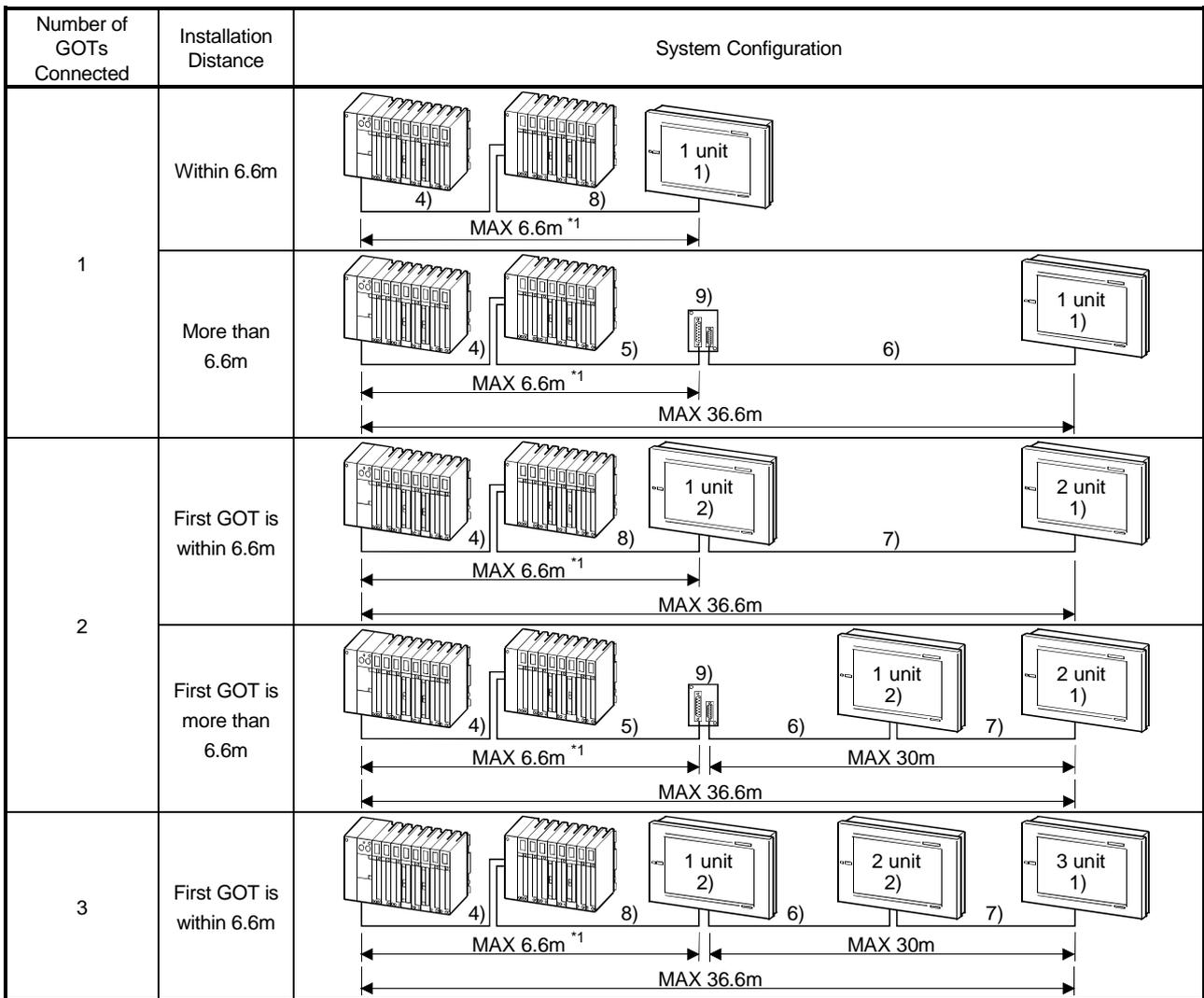
(a) When not using a PLC extension base unit

Number of GOTs Connected	Installation Distance	System Configuration
1	Within 2.5m	
	More than 2.5m	
2	First GOT is within 2.5m	
	First GOT is more than 2.5m	



(b) When using a PLC extension base unit

Use the A65B as the PLC extension base unit for connection of the GOT.

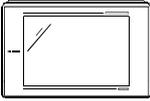
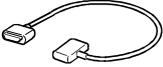


*1 When using an extension base unit, this distance includes the extension cable length (between base units).

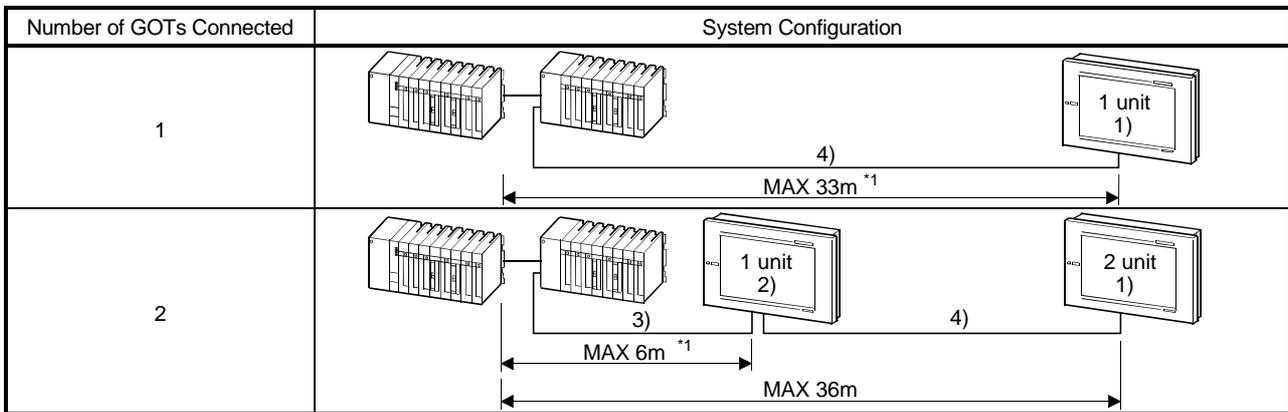
(2) Connection with A171SCPU-S3, A171SHCPU or A172HCPU

The numbers indicated in the system configurations shown below indicate the following equipment.

Use the A168B as the PLC extension base unit for connection of the GOT.

Item	Sketch	Number	System Equipment (Module Type)
GOT		1)	A985GOT/A97*GOT/A960GOT + A9GT-BUSS/A9GT-BUS2S/A9GT-BUSSU/A9GT-BUS2SU
			A956GOT + A9GT-BUSSU/A9GT-BUS2SU/A7GT-BUSS/A7GT-BUS2S
			A951GOT
GOT		2)	A985GOT/A97*GOT/A960GOT + A9GT-BUS2S/A9GT-BUS2SU
			A956GOT + A9GT-BUS2SU/A7GT-BUS2S
Connection cable		3)*1	A1SC01B(0.055m)/ A1SC03B(0.33m)/ A1SC07B(0.7m)/ A1SC12B(1.2m)/ A1SC30B(3m)
			4)

*1 Plug the connection cable to the PLC extension-dedicated connector.



*1 When using an extension base unit, this distance includes the extension cable length (between base units).

POINT

- The utility function can be started by switching power on again after installing the system programs (system operating system, communication driver, etc.) into the GOT.

After starting, touch the [Setup] icon to show the setup screen, and make settings related to bus connection.

- In the system configuration which uses the A9GT-QCNB, the same STAGE No. as that of the GOT must be set to the A9GT-QCNB.

For details of the setting method, refer to the A9GT-QCNB Bus Extension Connector Box User's Manual.

- When using the QA1S6*B extension base unit, connect the GOT after the extension base unit in terms of hardware, but assign the I/O number after the Q**B base unit.

<Example>
 When 16-point modules are loaded to all slots in the following configuration

	STAGE No.	I/O number
Q38B main base unit		00 to 7F
Q68B extension base unit	1	80 to FF
QA1S68B extension base unit	3	1A0 to 21F
GOT	2	100 to 19F

REMARK

GPPW has the system monitor function which batch-monitors the status of the PLC system. Note that there are the following restrictions on monitoring the module detail information of the GOT.

<Screen display example for GPPW system monitor function>

The screenshot shows a window titled "Module's Detailed Information" with the following sections:

- Module:**
 - Module Name: GOT900
 - I/O Address: 0
 - Implementation Position: Main Base 0Slot
 - Product information: 01091000000000 - A
- Module Information:**
 - Unit access: Possible
 - Status of External Power Supply: ---
 - Fuse Status: ---
 - Status of I/O Address Verify: Agreement
 - I/O Clear / Hold Settings: ---
 - Noise Filter Setting: ---
 - Input Type: ---
- Error Display:**
 - Present Error: No Error
 - Display format: HEX (selected), DEC
 - Error History: (Empty table with columns No. and Error)
 - Text: "The display sequence turn of the error history is displayed from an old error. The error of the latest is displayed in the line in the under."

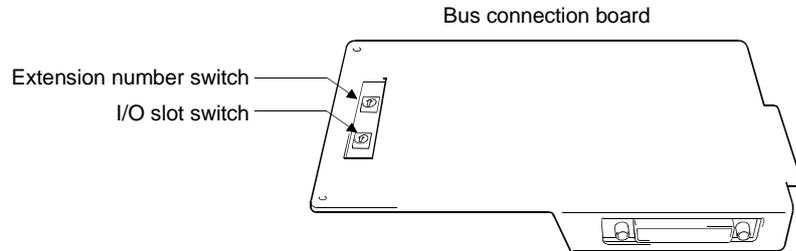
Buttons at the bottom include: "H/W Information..." (labeled "Not shown."), "Start monitor", "Stop monitor", and "Close".

Hence, confirm the module information of the GOT using the GOT side function (e.g. utility function, system alarm function).

3.3.2 Connection with other than QCPU

For bus connection with any CPU other than the QCPU, the GOT must be assigned to an empty I/O slot on the extension base unit.

To make assignment setting, use the bus connection board/unit installed on the GOT or the STAGE No. switch or I/O slot switch of the A951GOT.

Extension number switch

Set the extension number of the empty I/O slot to which the GOT will be assigned.

1 to 7 : Set the extension number.

0, 8, 9 : Must not be used.

(Factory-set to 0)

I/O slot switch

Set the empty I/O slot number to which the GOT will be assigned.

0 to 7 : Set the empty I/O slot number.

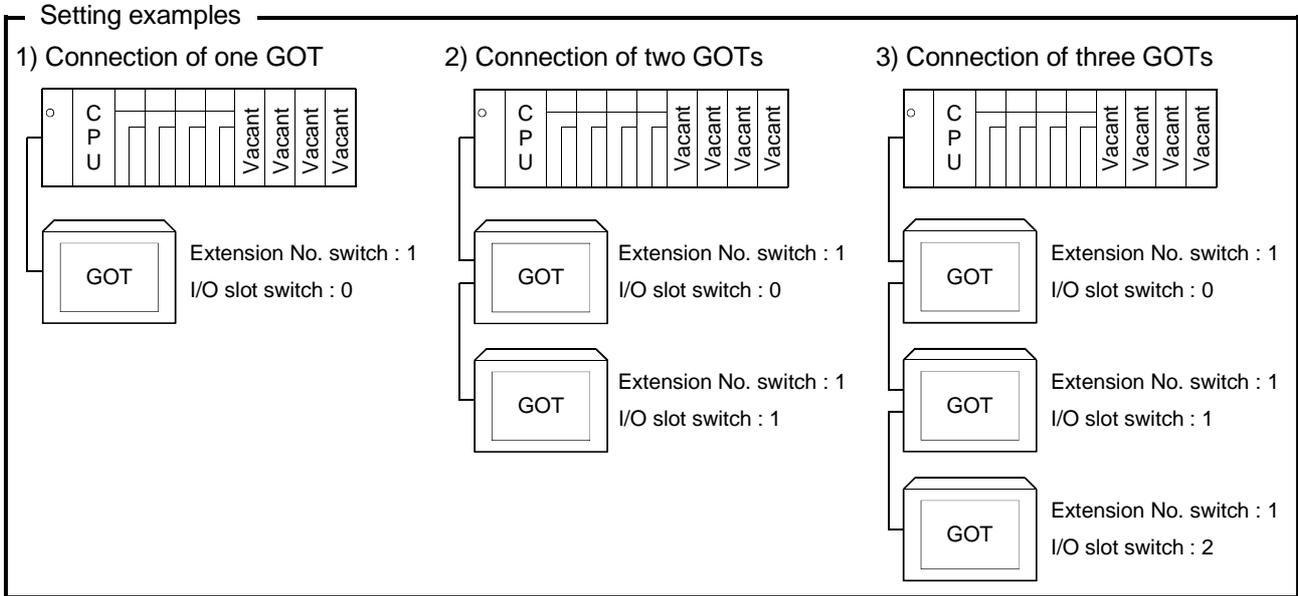
8, 9 : Must not be used.

(Factory-set to 0)

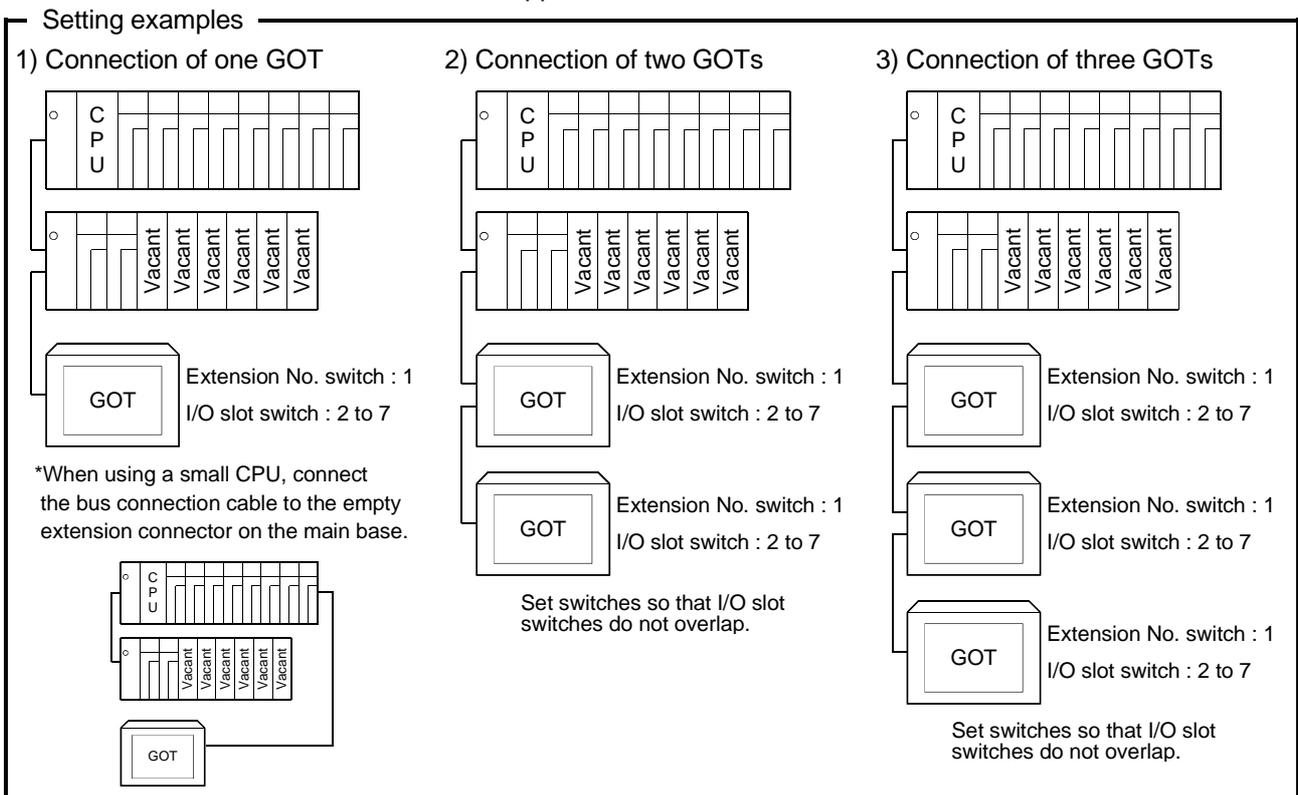
POINT

You cannot assign the GOT to the empty I/O slot on the main base. Therefore, even in a system which does not use the extension base, always allocate the GOT to a vacant I/O slot on the extension base (slot having the vacant points within the maximum I/O points of the PLC CPU, with the exception of those of the standard base).

- (1) Setting method used when there is no extension base unit connected
 Since the GOT cannot be assigned to an empty slot on the main base, make setting to assign it to the empty slot of the first extension if there is no extension base unit connected.



- (2) Setting method used for assignment of GOT(s) to empty slot(s) of extension base unit
 Set the extension number(s) and slot number(s) of the empty slot(s) to be assigned to.
 Note that the following setting examples assume the use of a large CPU but the same method applies to the use of a small CPU.

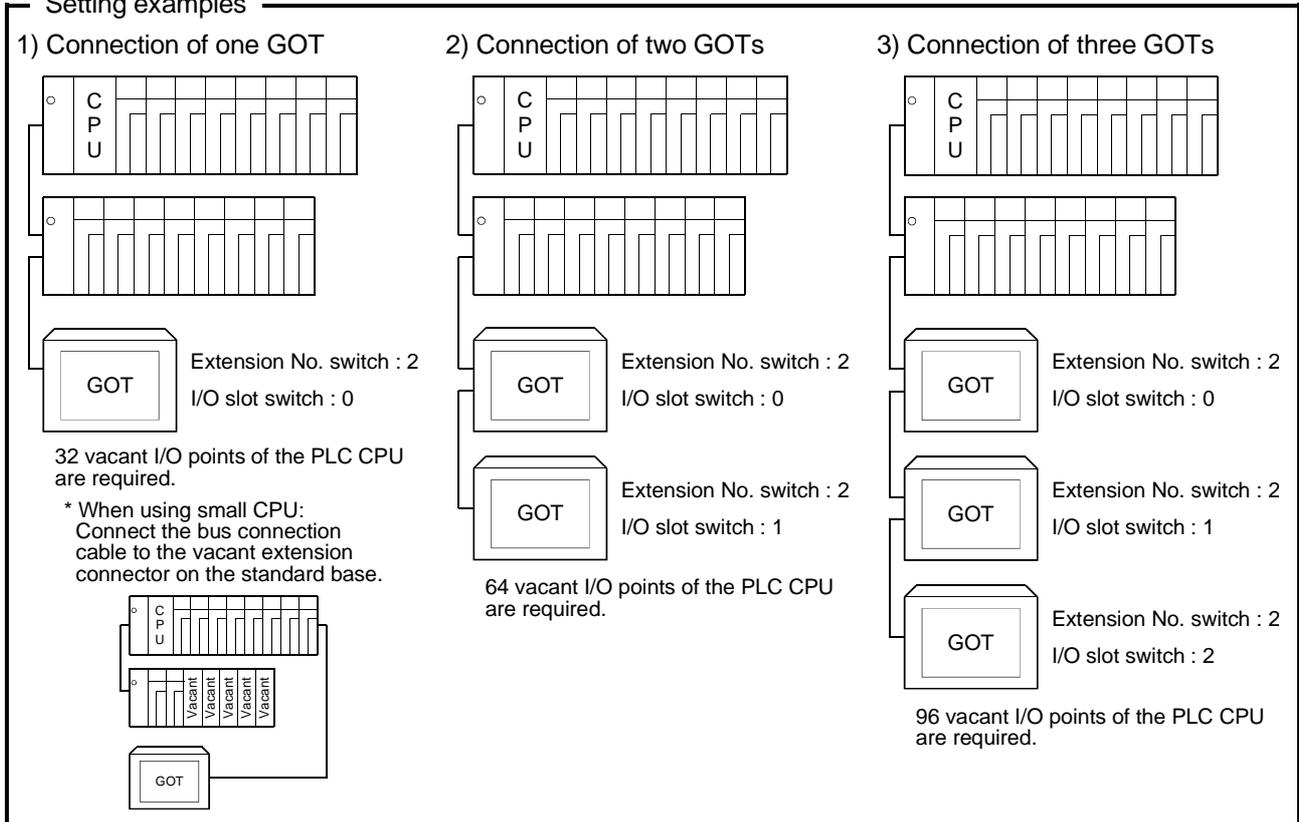


(3) Setting method used when there are no empty slots on the extension base unit connected

When there are no empty I/O slots on the base unit, set the extension number switch(es) and I/O slot switch(es) as indicated below.

Note that the following setting examples assume the use of a large CPU but the same method applies to the use of a small CPU.

Setting examples



POINT

When using the Q3ACPU, Q4A(R)CPU, A3□ CPU, A4UCPU or A0J2HCPU, the above setting cannot be made.

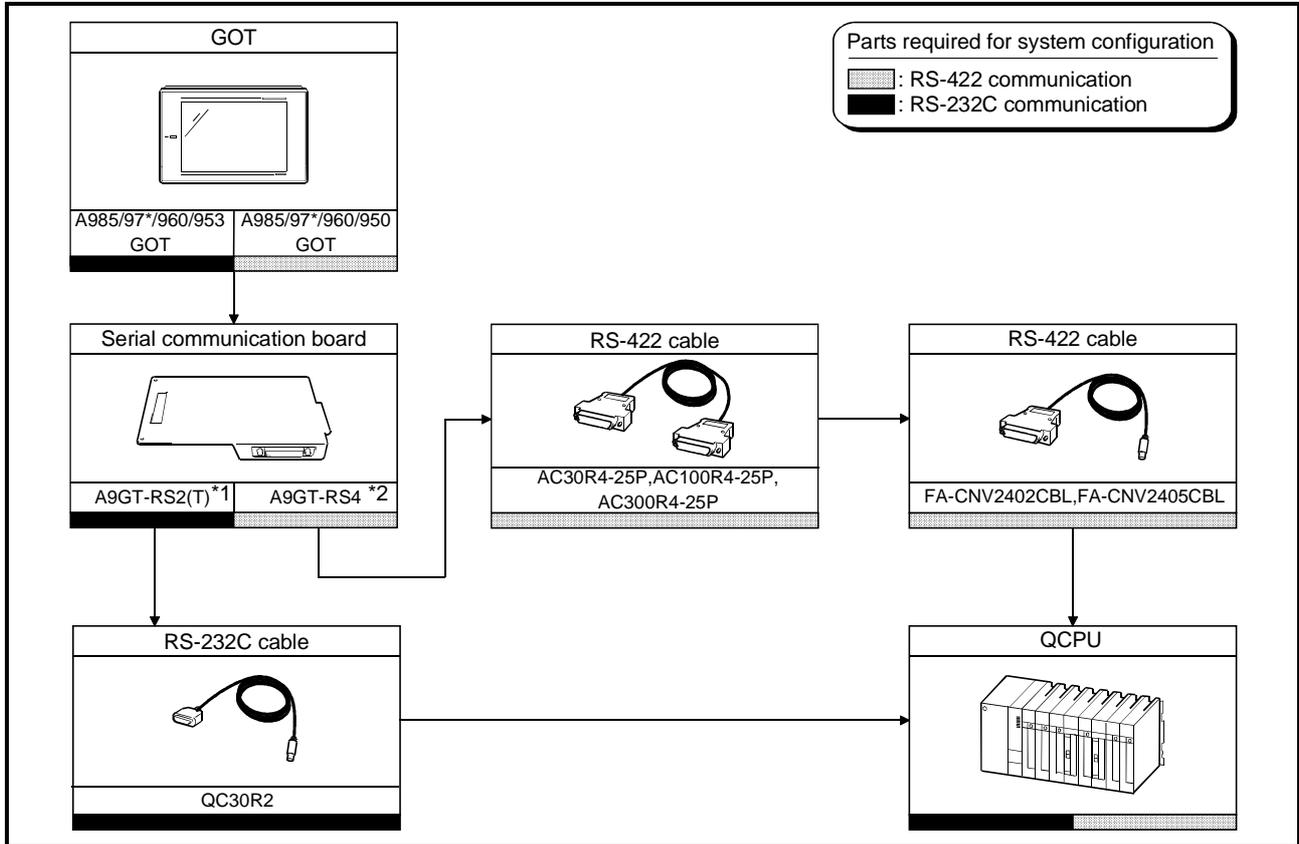
Empty I/O slots are always needed on the extension base unit.

Also, when using the A0J2HCPU, assign the GOT(s) to I/O slot(s) 0 to 3 of the first extension.

Chapter4 Direct connection to CPU

4.1 System configuration

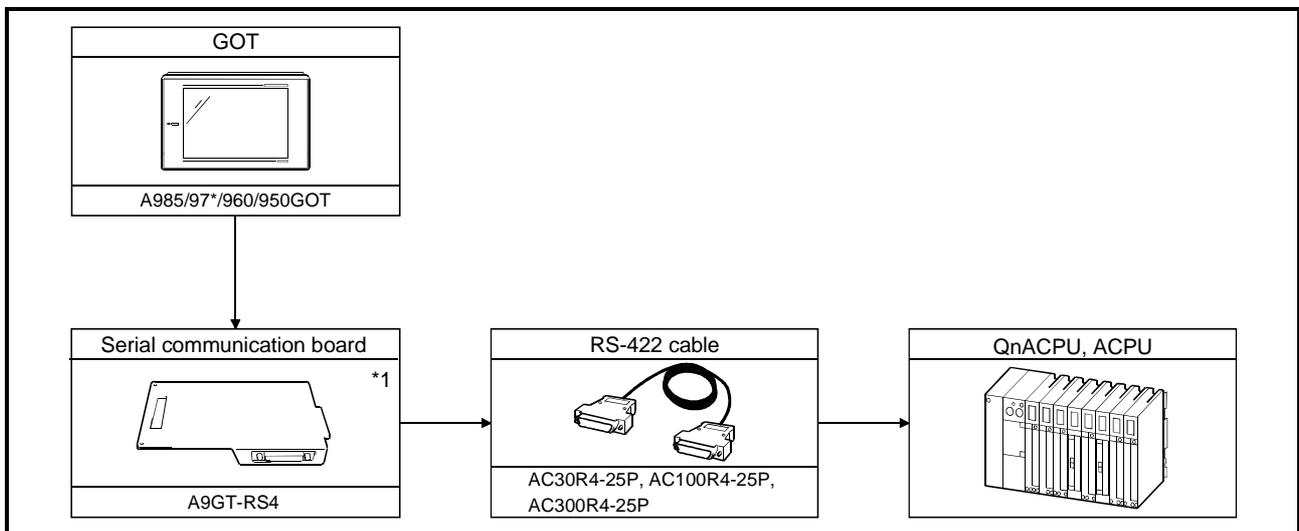
4.1.1 When connecting to QCPU



*1 This is not required when the A953GOT (with built-in serial communication interface) is used.

*2 This is not required when the A950GOT (with built-in serial communication interface) is used.

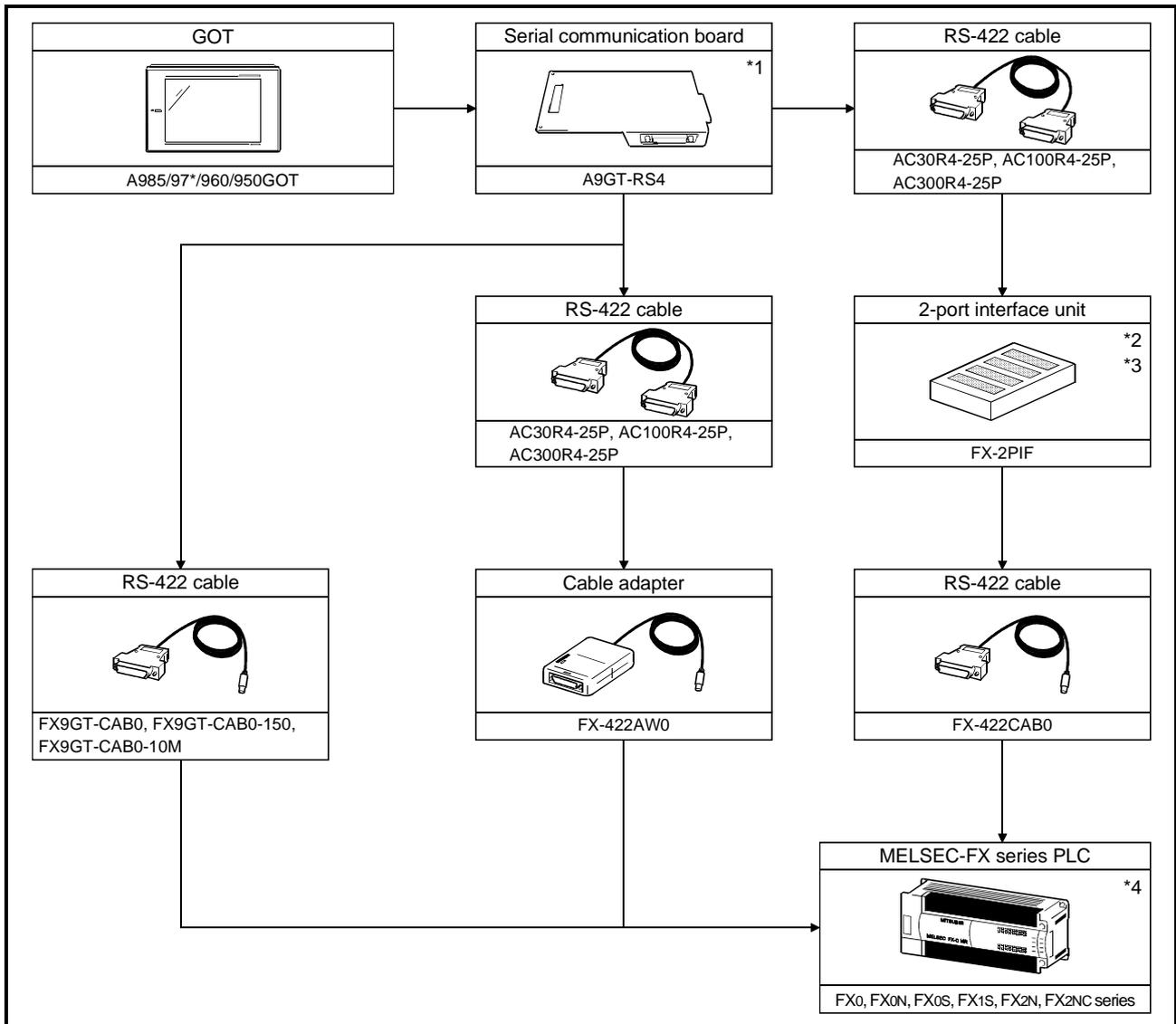
4.1.2 When connecting to QnACPU or ACPU



*1 This is not required when the A950GOT (with built-in serial communication interface) is used.

4.1.3 When connecting to FXCPU

(1) When connecting to FX0, FX1S, FX0N, FX0S, FX2N, FX2NC series



*1 This is not required when the A950GOT (with built-in serial communication interface) is used.

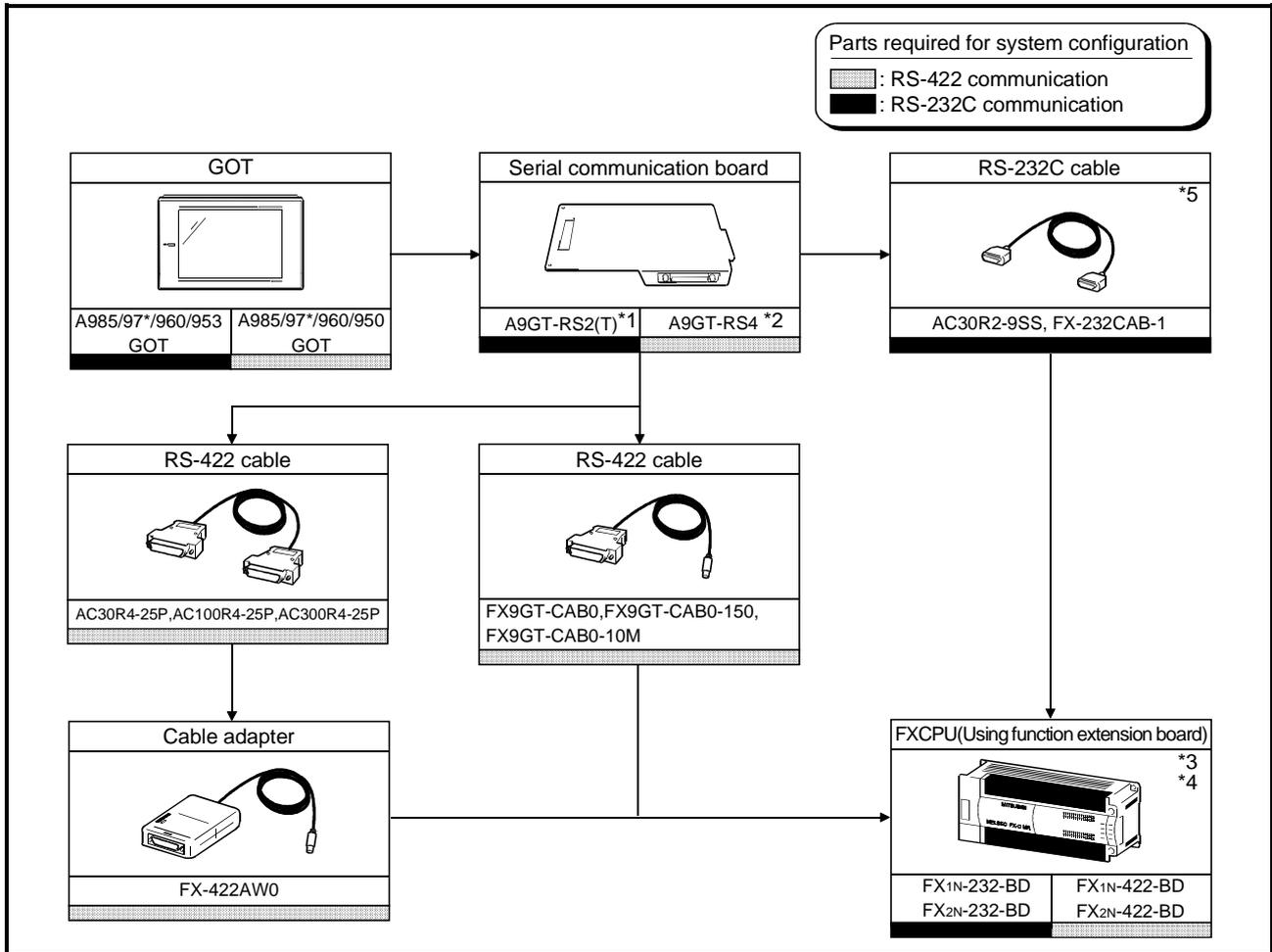
*2 When connecting the GOT to FX2N series via FX-2PIF, use FX-2PIF Version 3.0 or later.

*3 Use FX-2PIF when connecting the GOT together with the peripheral devices for MELSEC-FX series (A6GPP, A6PHP, A7GPP, A7PHP, etc.).

For applicable models and system configuration for connecting the peripheral devices for MELSEC-FX series, refer to the instruction manual of the MELSEC-FX series PLC.

*4 For the FX1S and FX2N series, the function extension board can be used (refer to (2)).

(2) When using function extension board



*1 This is not required when the A953GOT (with built-in serial communication interface) is used.

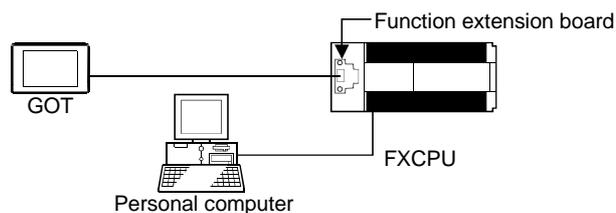
*2 This is not required when the A950GOT (with built-in serial communication interface) is used.

*3 The function extension board used depends on the type of the FXCPU connected.

Use the function extension board as indicated in the following table.

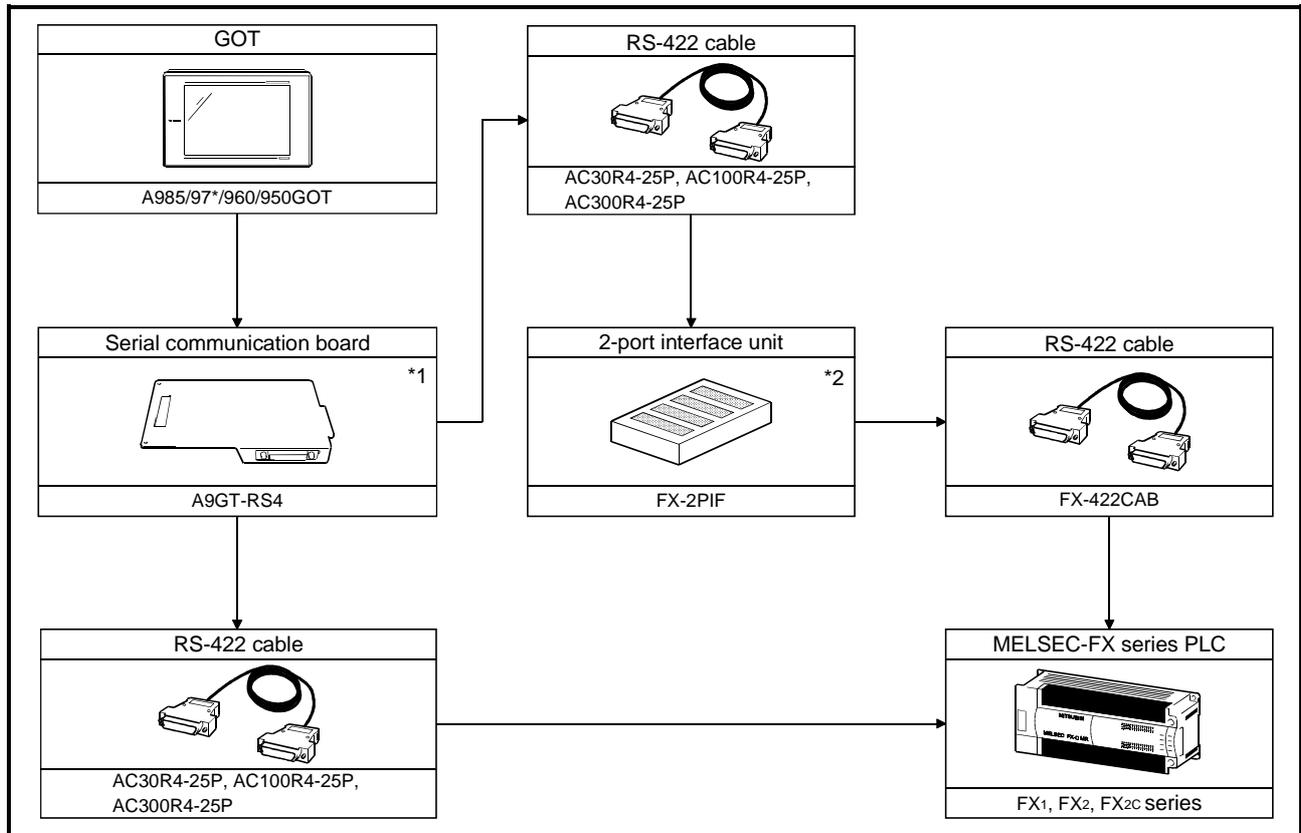
Item	Function Extension Board Used	
	When FX1s series is connected	When FX2N series is connected
For RS-232C communication	FX1N-232-BD	FX2N-232-BD
For RS-422 communication	FX1N-422-BD	FX2N-422-BD

*4 When using the function extension board, you can connect one GOT and one GPP or other peripheral to the function extension board and FXCPU, respectively.



*5 RS-232C cable can be prepared by the user. Refer to 4.2 for details of preparation.

(3) When connecting to FX1, FX2, FX2c series



*1 This is not required when the A950GOT (with built-in serial communication interface) is used.

*2 Use FX-2PIF when connecting the GOT with the peripheral devices for MELSEC-FX series (A6GPP, A6PHP, A7GPP, A7PHP, etc.).

For available models and system configuration when connecting the peripheral devices for MELSEC-FX series, refer to the instruction manual of the MELSEC-FX series PLC.

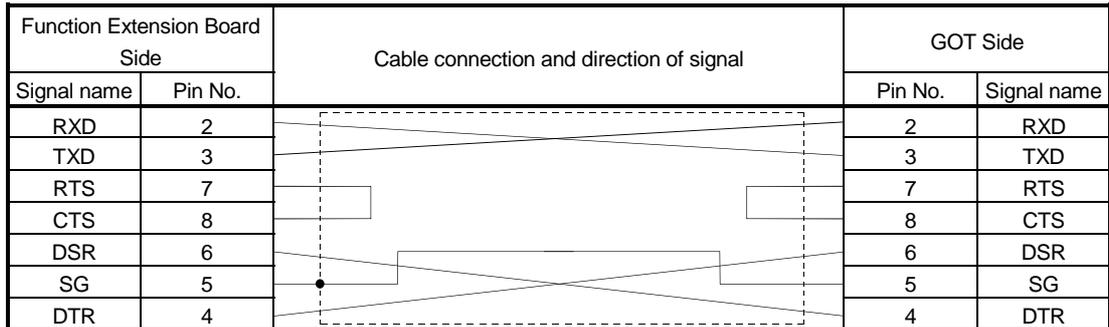
4.2 Connection Cables

This section gives the connection diagrams and connectors of the RS-232C cables which are used to connect the GOT and function extension board (when the FX1S or FX2N series is used).

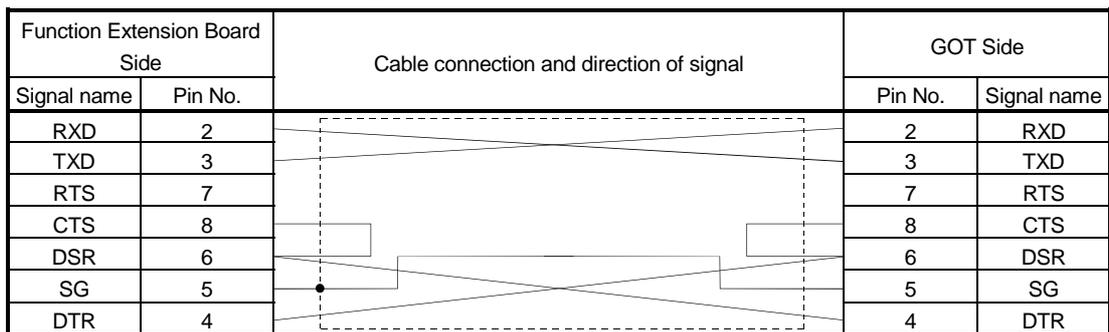
You can use either of the following connection diagrams (a) and (b).

(1) Connection diagram

(a) Connection diagram of AC30R2-9SS



(b) Connection diagram of FX-232CAB-1



(2) Connector and connector cover

- GOT connector
Use the screw-in type connector (inch) for the GOT side.
- Function extension board connector
Use the connector compatible with the function extension board.

(3) Precautions for cable preparation

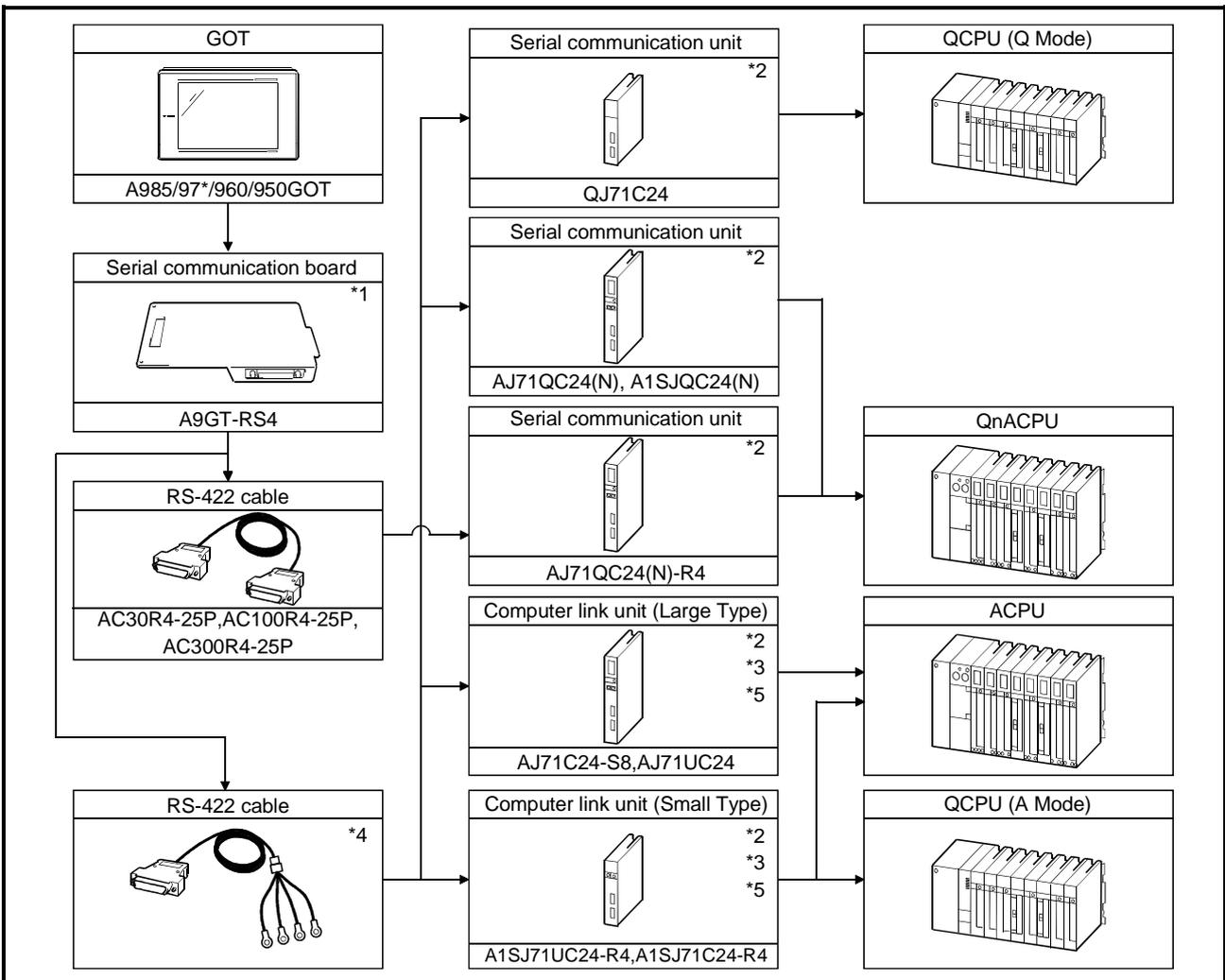
The cable must be 15 m (49.21 feet) or shorter.

Chapter5 Computer link connection (RS-422 communication)

The computer link connection (RS-422 communication) has the following features.

- Since this method allows one-to-one connection between the computer link unit and the GOT, multiple GOT units can be connected according to the number of computer link units loaded to the PLC CPU.
- While monitoring the GOT, a peripheral device for GPP function can be connected on the PLC CPU for debugging of the PLC program.

5.1 System configuration



*1 This is not required when the A950GOT (with built-in serial communication interface) is used.

*2 For system configuration of the computer link unit and the serial communication unit, refer to the user's manuals of the computer link unit and the serial communication unit respectively.

*3 On the GOT side, connection is not needed as the termination resistor is built in.

*4 RS-422 cable must be prepared by the customer.

For details of preparation, refer to 5.4.

*5 When the AJ71C24-S8 or A1SJ71C24-R4 is used and the connection target PLC CPU is the AnUCPU, the monitorable access range is the range of the AnACPU.

5.2 Initial settings

5.2.1 Computer link module and serial communication module side settings

When connecting the GOT and the computer link unit and serial communication unit for monitoring, set the switches of the computer link unit and serial communication unit as follows.

(1) When connecting to QJ71C24

Use I/O assignment setting of GPPW to set the QJ71C24 switches.

For details of the setting method, refer to GPPW Operating Manual.

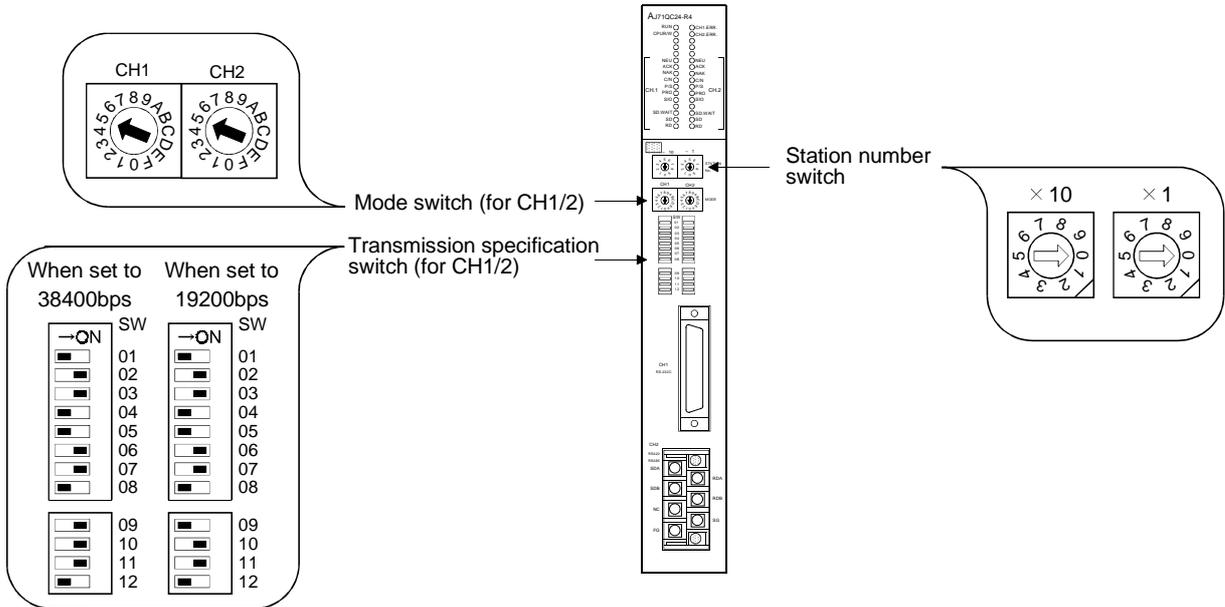
Settings depend on the channel (interface number) of the serial communication unit to which the GOT is connected.

Set the switches as indicated below according to the channel where the GOT is connected.

Channel Where GOT Is Connected	Settings																																													
CH1	<p>Switch setting for I/O and intelligent functional module</p> <p>Input format: <input type="text" value="HEX."/></p> <table border="1"> <thead> <tr> <th></th> <th>Slot</th> <th>Type</th> <th>Model name</th> <th>Switch 1</th> <th>Switch 2</th> <th>Switch 3</th> <th>Switch 4</th> <th>Switch 5</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>PLC</td> <td>PLC</td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> </tr> <tr> <td>1</td> <td>0[*:0]</td> <td>Intelli.</td> <td>QJ71C24(-R2)</td> <td>0000</td> <td>0000</td> <td></td> <td></td> <td>0000</td> </tr> <tr> <td>2</td> <td>1[*:1]</td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> </tr> <tr> <td>3</td> <td>2[*:2]</td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> </tr> </tbody> </table>		Slot	Type	Model name	Switch 1	Switch 2	Switch 3	Switch 4	Switch 5	0	PLC	PLC							1	0[*:0]	Intelli.	QJ71C24(-R2)	0000	0000			0000	2	1[*:1]								3	2[*:2]							
	Slot	Type	Model name	Switch 1	Switch 2	Switch 3	Switch 4	Switch 5																																						
0	PLC	PLC																																												
1	0[*:0]	Intelli.	QJ71C24(-R2)	0000	0000			0000																																						
2	1[*:1]																																													
3	2[*:2]																																													
CH2	<p>Switch setting for I/O and intelligent functional module</p> <p>Input format: <input type="text" value="HEX."/></p> <table border="1"> <thead> <tr> <th></th> <th>Slot</th> <th>Type</th> <th>Model name</th> <th>Switch 1</th> <th>Switch 2</th> <th>Switch 3</th> <th>Switch 4</th> <th>Switch 5</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>PLC</td> <td>PLC</td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> </tr> <tr> <td>1</td> <td>0[*:0]</td> <td>Intelli.</td> <td>QJ71C24(-R2)</td> <td></td> <td></td> <td>0000</td> <td>0000</td> <td>0000</td> </tr> <tr> <td>2</td> <td>1[*:1]</td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> </tr> <tr> <td>3</td> <td>2[*:2]</td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> </tr> </tbody> </table>		Slot	Type	Model name	Switch 1	Switch 2	Switch 3	Switch 4	Switch 5	0	PLC	PLC							1	0[*:0]	Intelli.	QJ71C24(-R2)			0000	0000	0000	2	1[*:1]								3	2[*:2]							
	Slot	Type	Model name	Switch 1	Switch 2	Switch 3	Switch 4	Switch 5																																						
0	PLC	PLC																																												
1	0[*:0]	Intelli.	QJ71C24(-R2)			0000	0000	0000																																						
2	1[*:1]																																													
3	2[*:2]																																													

POINT
<p>When the GOT is connected for use, CH1 and CH2 of the serial communication unit cannot be used concurrently.</p> <p>Hence, note that the GOT and GPP function peripheral device or two GOTs cannot be connected for use with one serial communication unit.</p>

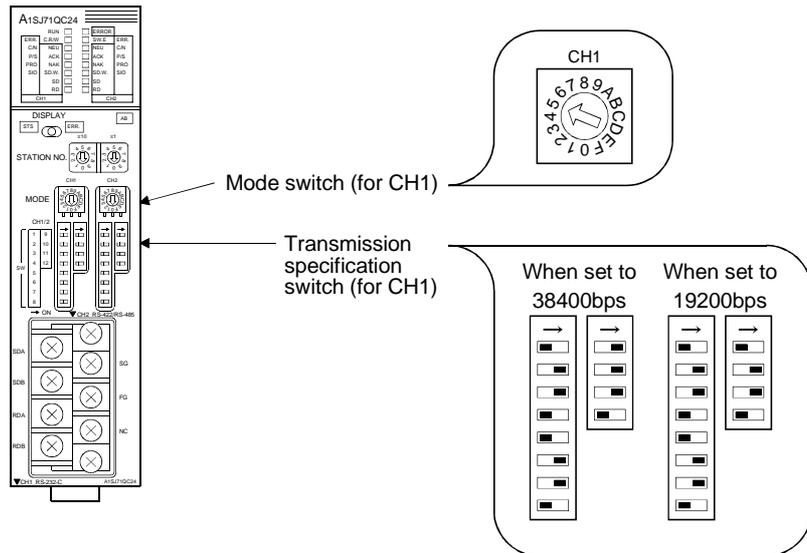
(2) When connecting to AJ71QC24(N)(-R4)



POINT

- The value of the mode switch of an unused channel must be set to the value except 0(Interlocking operation).
- When the AJ71QC24N(-R4) is used and the transmission speed is set to 38400bps, the GOT side transmission speed must be re-set. For details of the setting method, refer to Section 5.2.2.

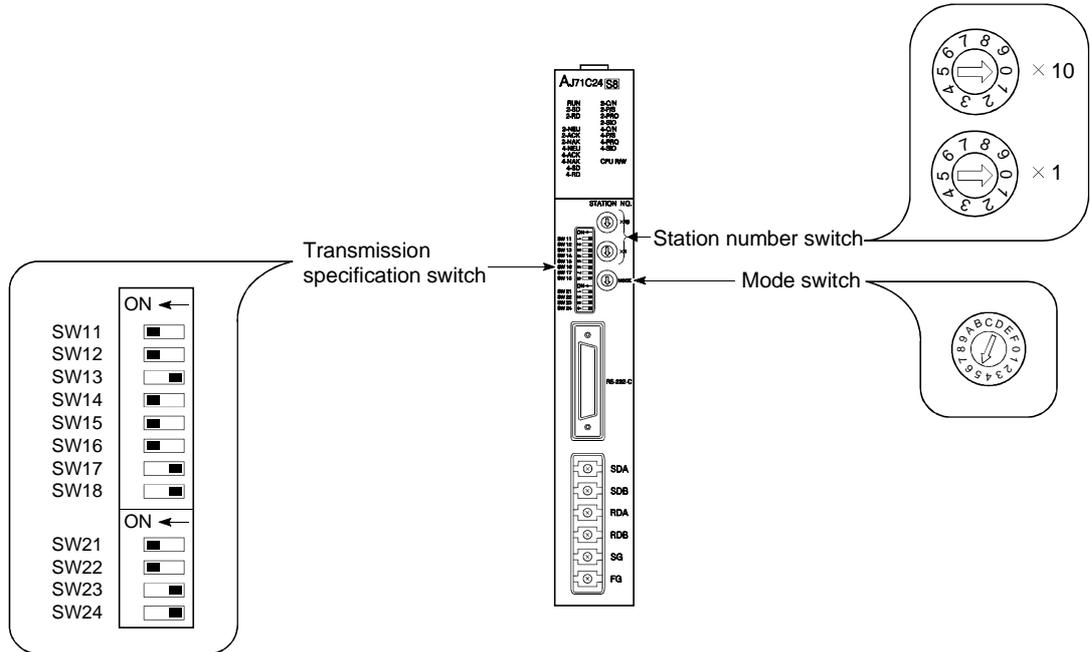
(3) When connecting to A1SJ71QC24(N)



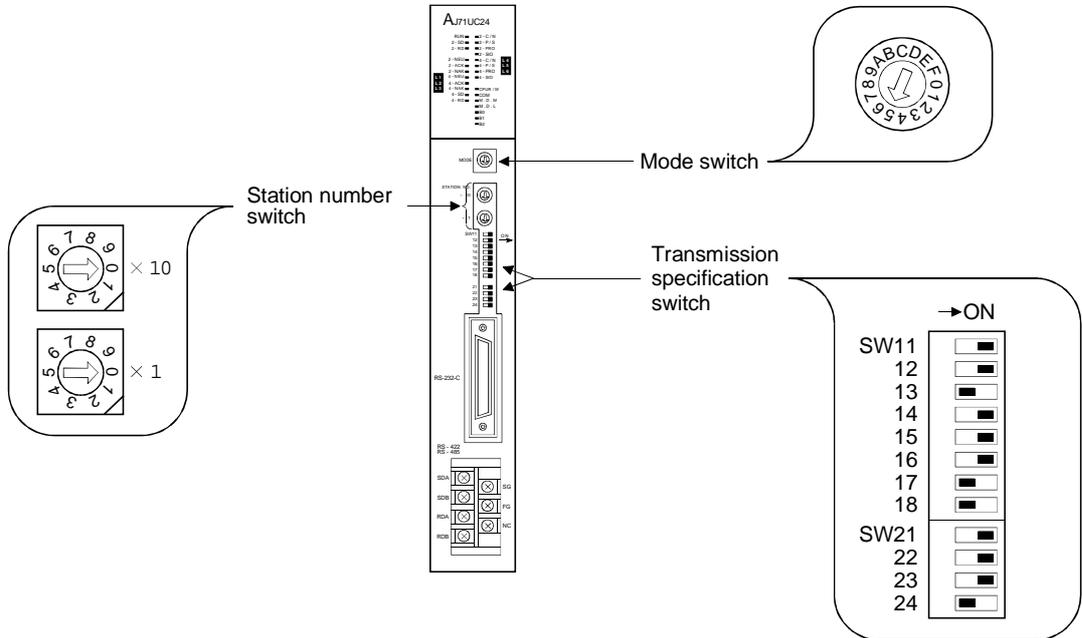
POINT

When the A1SJ71QC24N is used and the transmission speed is set to 38400bps, the GOT side transmission speed must be re-set. For details of the setting method, refer to Section 5.2.2.

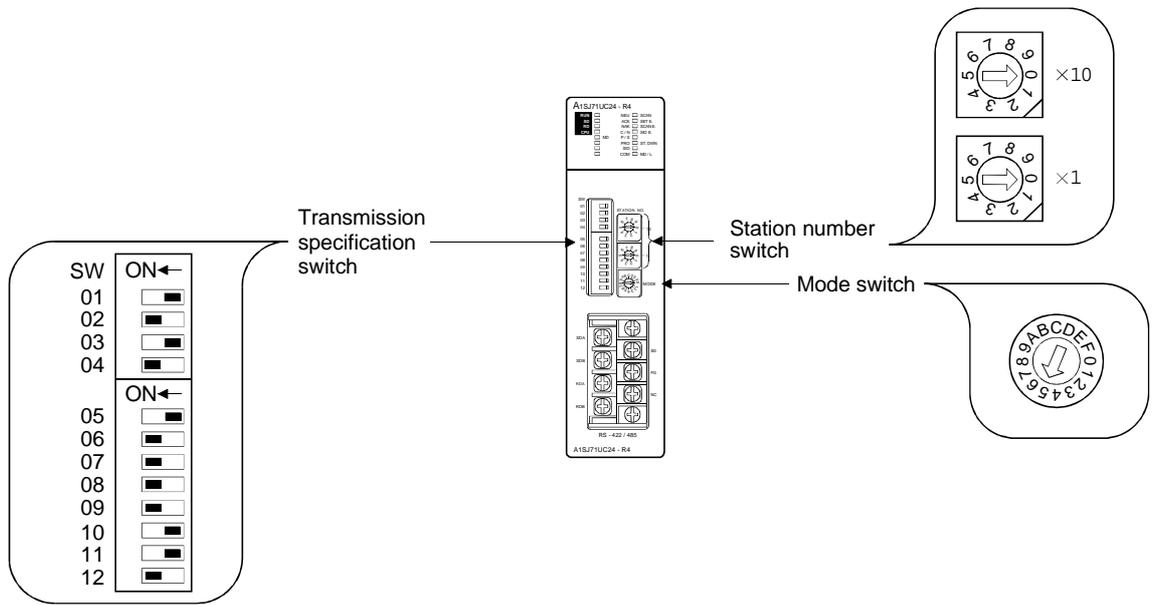
(3) When connecting to AJ71C24-S8



(5) When connecting to AJ71UC24



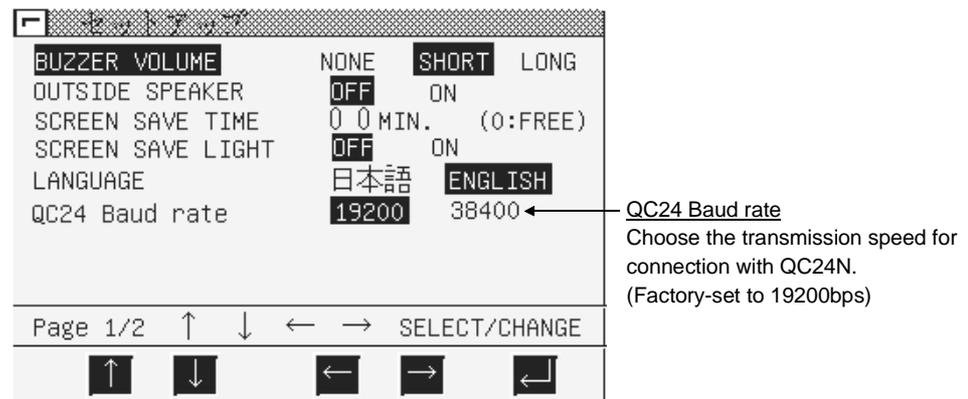
(6) When connecting to A1SJ71UC24-R4, A1SJ71C24-R4



5.2.2 GOT side settings

When the GOT is connected with the computer link module or serial communication module for monitoring, the GOT side settings need not be made basically. However, when you use the AJ71QC24N(-R4) or A1SJ71QC24N and want to make data transmission of 38400bps, the GOT side settings must be changed.

Set the transmission speed on Setup of the GOT's utility function. For details of the utility function, refer to the GOT-A900 Series Operating Manual (SW4D5C-GOTR-PACKE Compatible Extended • Option Function Manual).



POINT

The utility function can be started by switching power on again after installing the system programs (system OS, communication driver, etc.) into the GOT. After the utility function has started, touch the [Setup] icon to display the setup screen, and make settings related to computer link connection.

5.3 Transmission specifications

The following transmission specifications apply to the case where communication is made between the GOT and computer link or serial communication module.

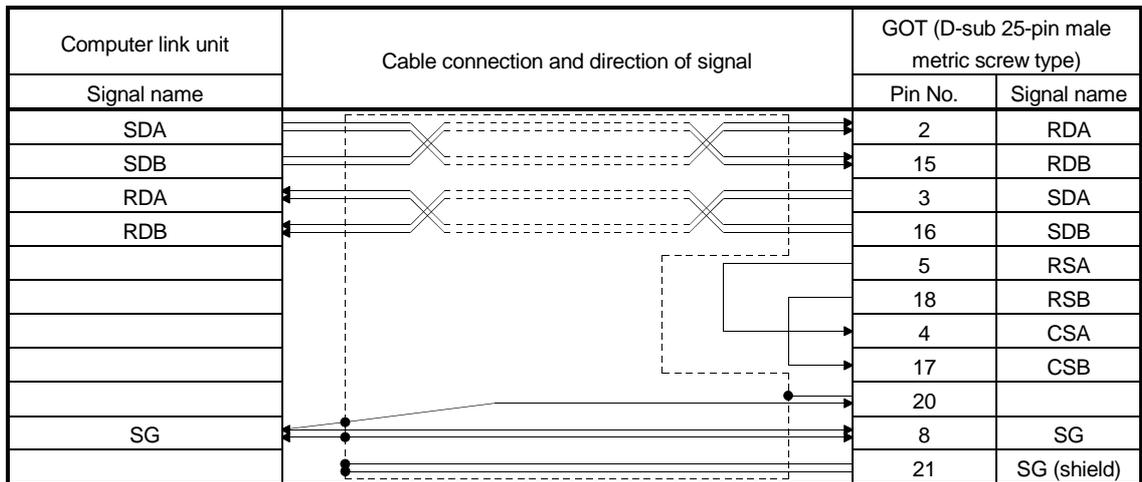
Item	Settings		
	Using QJ71C24	Using AJ71QC24N(-R4) or A1SJ71QC24N	Using any module other than those indicated on left
Transmission speed	38400bps	19200bps/38400bps	19200bps
Data length	8 bits		
Stop bit	1 bit		
Parity bit	Yes (odd)		
Sum check	Yes		

5.4 Connection cable

The user needs to fabricate the RS-422 cable which is used to connect the GOT and PLC CPU side (serial communication or computer link module).

The RS-422 cable connection diagram, connector and others are indicated below.

(1) Connection diagram



(2) Connector, crimp terminal and cable

No.	Description	Model	Manufacturer
1)	Connector with cover	17JE-23250-02(D8A6)	DDK
2)	Round-type crimp terminal (recommended part)	V1.25-M4	Nippon Crimping Terminal
3)	20-core shield cable (recommended part)	RF VV-SB-24×20	Toyokuni Power Cables

(3) Precautions for cable preparation

- The maximum cable length depends on the PLC CPU connected. Fabricate the cable within the following maximum cable length.

PLC CPU Connected to	Maximum Cable Length (m)
QCPU	1200
QnACPU, ACPUC	200

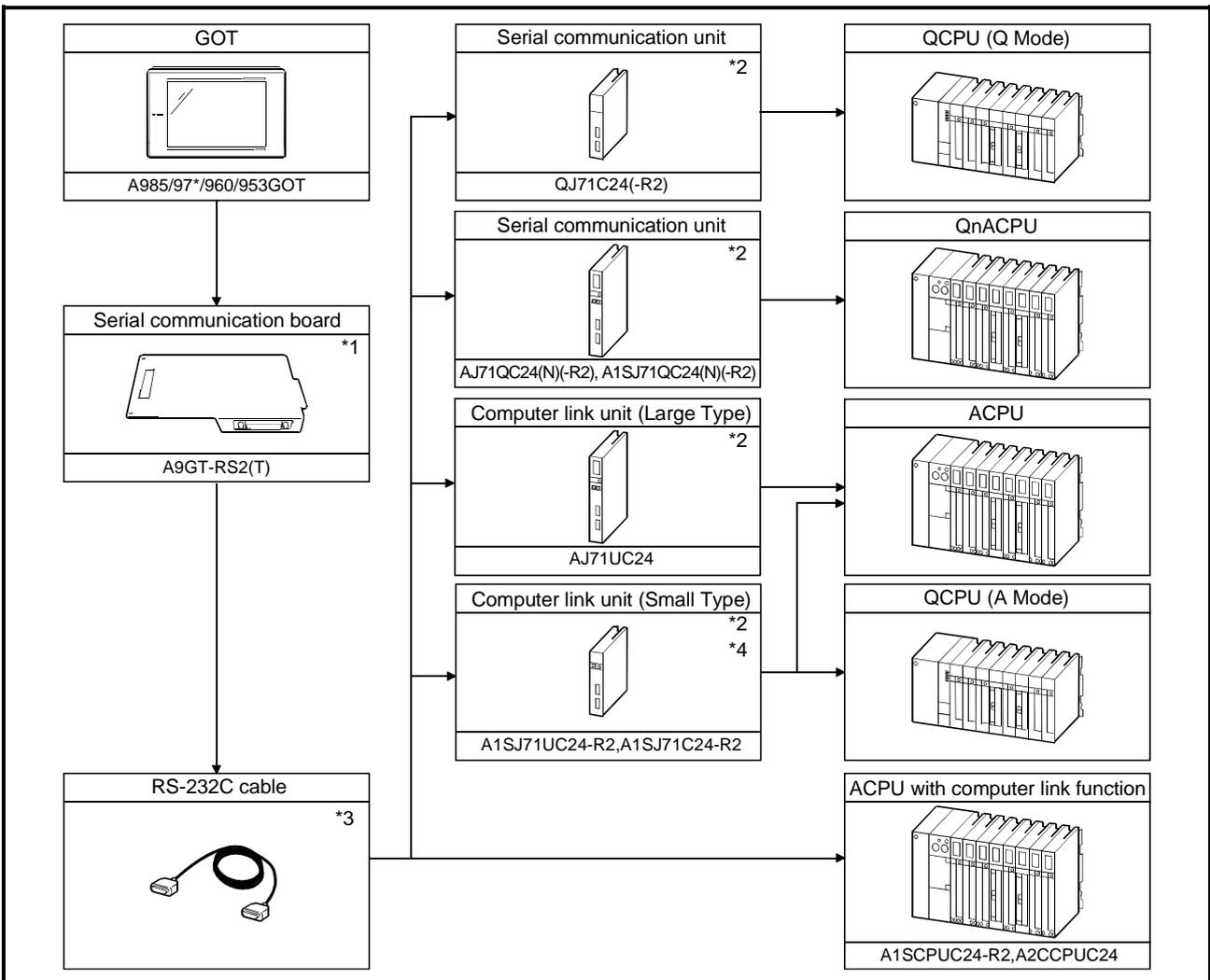
- When using 2) and 3) in the above table for preparing the cable :
If one electric wire is used, the wire may come off the crimp terminal. Therefore, connect 2 wires as described in connection diagram (1).

Chapter6 Computer link connection (RS-232C communication)

The computer link connection (RS-232C communication) has the following features.

- Since this method allows one-to-one connection between the computer link unit and the GOT, multiple GOT units can be connected according to the number of computer link units loaded to the PLC CPU.
- While monitoring the GOT, the peripheral device for GPP function can be connected on the PLC CPU for debugging of the PLC program.

6.1 System configuration



*1 This is not required when the A953GOT (with built-in serial communication interface) is used.

*2 For system configuration of the computer link unit, refer to the user's manuals of the computer link unit.

*3 RS-232C cable must be prepared by the user.

For details of preparation, refer to 6.4.

*4 When the A1SJ71C24-R2 is used and the connection target PLC CPU is the AnUCPU, the monitorable access range is the range of the AnACPU.

6.2 Initial settings

6.2.1 Computer link module and serial communication module side settings

When connecting the GOT and the computer link unit and serial communication unit for monitoring, set the switches of the computer link unit and serial communication unit as follows.

(1) When connecting to QJ71C24(-R2)

Use I/O assignment setting of GPPW to set the QJ71C24(-R2) switches.

For details of the setting method, refer to GPPW Operating Manual.

Settings depend on the channel (interface number) of the serial communication unit to which the GOT is connected.

Set the switches as indicated below according to the channel where the GOT is connected.

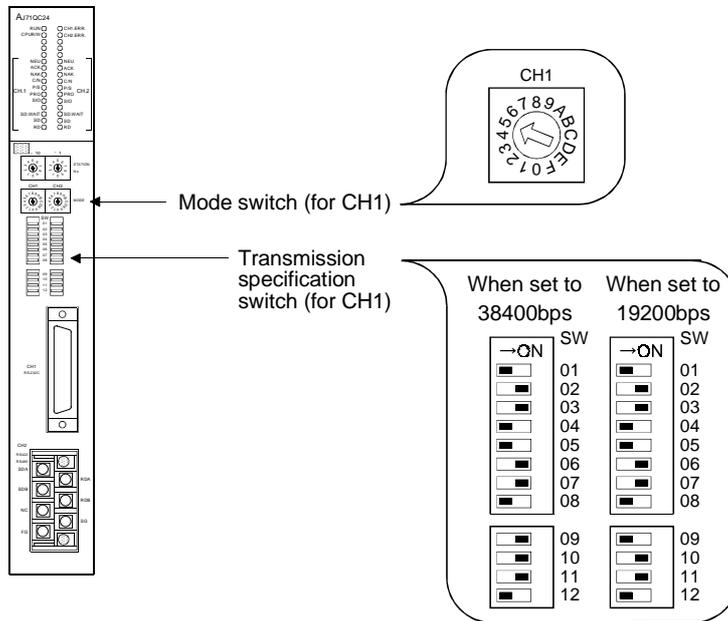
Channel Where GOT Is Connected	Settings																																													
CH1	<p>Switch setting for I/O and intelligent functional module</p> <p>Input format: <input type="text" value="HEX."/></p> <table border="1"> <thead> <tr> <th></th> <th>Slot</th> <th>Type</th> <th>Model name</th> <th>Switch 1</th> <th>Switch 2</th> <th>Switch 3</th> <th>Switch 4</th> <th>Switch 5</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>PLC</td> <td>PLC</td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> </tr> <tr> <td>1</td> <td>0[*-0]</td> <td>Intelli.</td> <td>QJ71C24(-R2)</td> <td>0000</td> <td>0000</td> <td></td> <td></td> <td>0000</td> </tr> <tr> <td>2</td> <td>1[*-1]</td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> </tr> <tr> <td>3</td> <td>2[*-2]</td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> </tr> </tbody> </table>		Slot	Type	Model name	Switch 1	Switch 2	Switch 3	Switch 4	Switch 5	0	PLC	PLC							1	0[*-0]	Intelli.	QJ71C24(-R2)	0000	0000			0000	2	1[*-1]								3	2[*-2]							
	Slot	Type	Model name	Switch 1	Switch 2	Switch 3	Switch 4	Switch 5																																						
0	PLC	PLC																																												
1	0[*-0]	Intelli.	QJ71C24(-R2)	0000	0000			0000																																						
2	1[*-1]																																													
3	2[*-2]																																													
CH2	<p>Switch setting for I/O and intelligent functional module</p> <p>Input format: <input type="text" value="HEX."/></p> <table border="1"> <thead> <tr> <th></th> <th>Slot</th> <th>Type</th> <th>Model name</th> <th>Switch 1</th> <th>Switch 2</th> <th>Switch 3</th> <th>Switch 4</th> <th>Switch 5</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>PLC</td> <td>PLC</td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> </tr> <tr> <td>1</td> <td>0[*-0]</td> <td>Intelli.</td> <td>QJ71C24(-R2)</td> <td></td> <td></td> <td>0000</td> <td>0000</td> <td>0000</td> </tr> <tr> <td>2</td> <td>1[*-1]</td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> </tr> <tr> <td>3</td> <td>2[*-2]</td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> </tr> </tbody> </table>		Slot	Type	Model name	Switch 1	Switch 2	Switch 3	Switch 4	Switch 5	0	PLC	PLC							1	0[*-0]	Intelli.	QJ71C24(-R2)			0000	0000	0000	2	1[*-1]								3	2[*-2]							
	Slot	Type	Model name	Switch 1	Switch 2	Switch 3	Switch 4	Switch 5																																						
0	PLC	PLC																																												
1	0[*-0]	Intelli.	QJ71C24(-R2)			0000	0000	0000																																						
2	1[*-1]																																													
3	2[*-2]																																													

POINT

When the GOT is connected for use, CH1 and CH2 of the serial communication unit cannot be used concurrently.

Hence, note that the GOT and GPP function peripheral device or two GOTs cannot be connected for use with one serial communication unit.

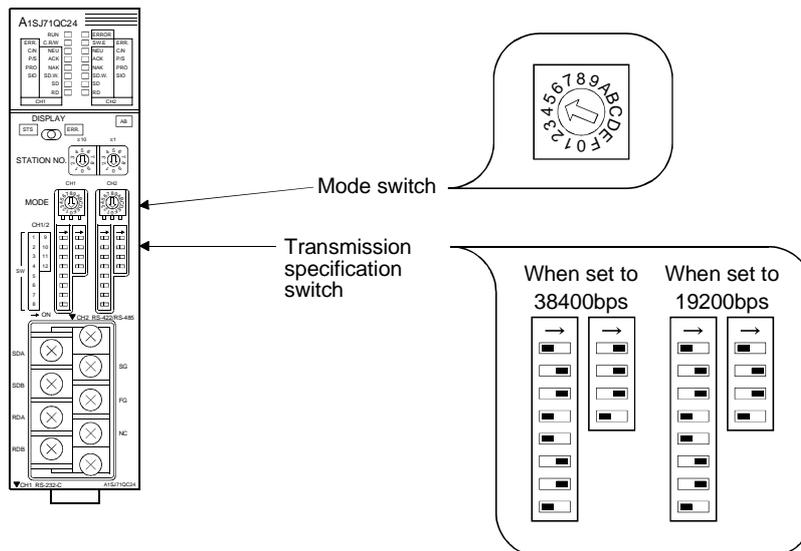
(2) When connecting to AJ71QC24(N)(-R2)



POINT

When the AJ71QC24N(-R2) is used and the transmission speed is set to 38400bps, the GOT side transmission speed must be re-set.
 For details of the setting method, refer to Section 6.2.2.

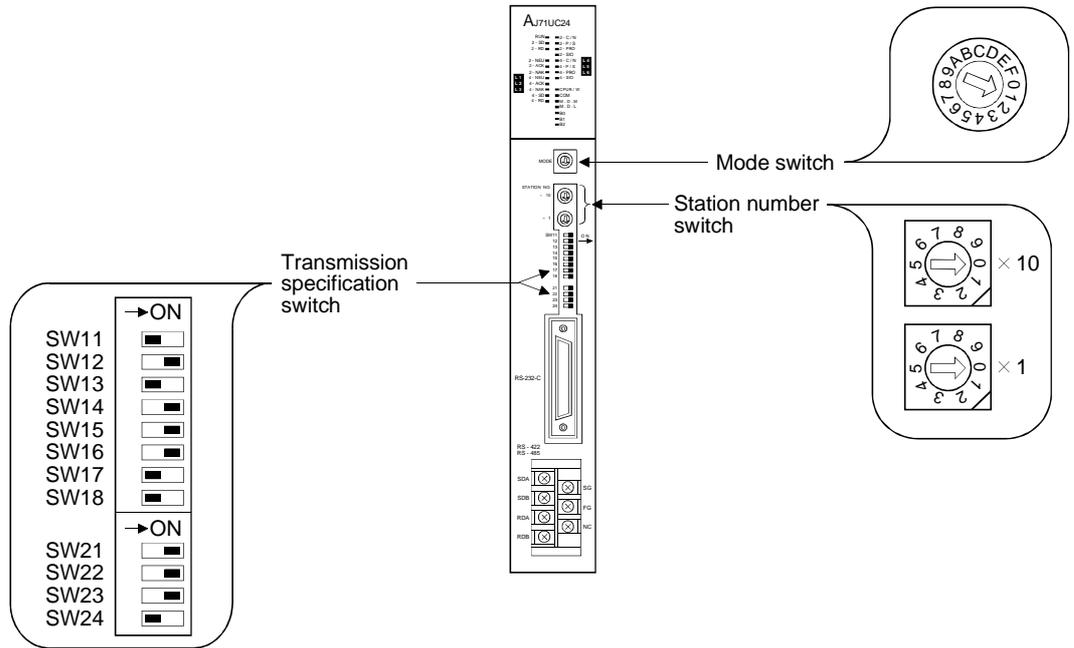
(3) When connecting to A1SJ71QC24(-R2)



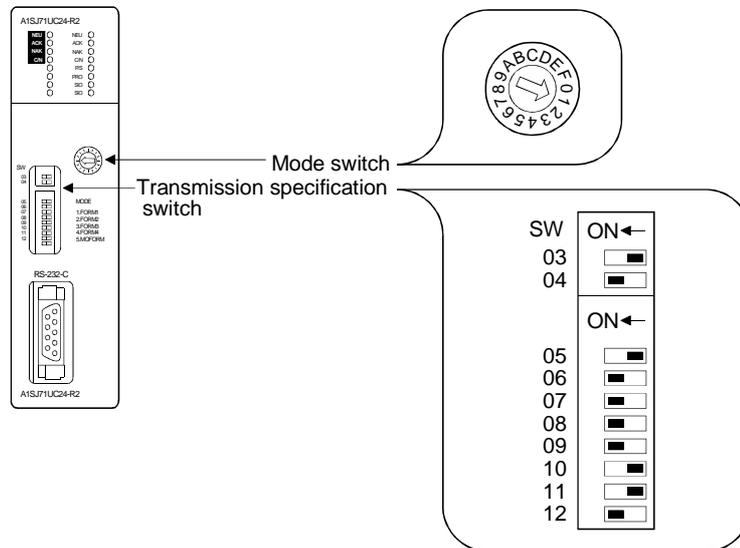
POINT

When the A1SJ71QC24N(-R2) is used and the transmission speed is set to 38400bps, the GOT side transmission speed must be re-set.
 For details of the setting method, refer to Section 6.2.2.

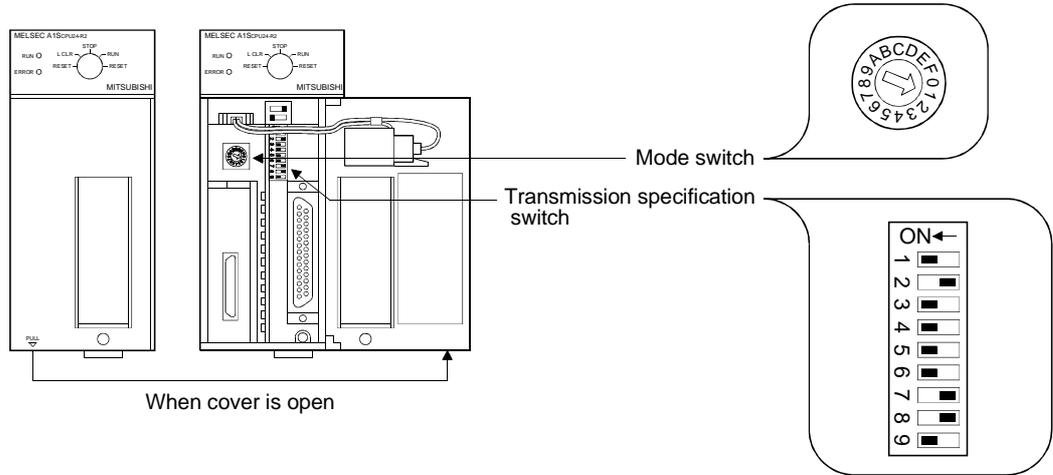
(4) When connecting to AJ71UC24



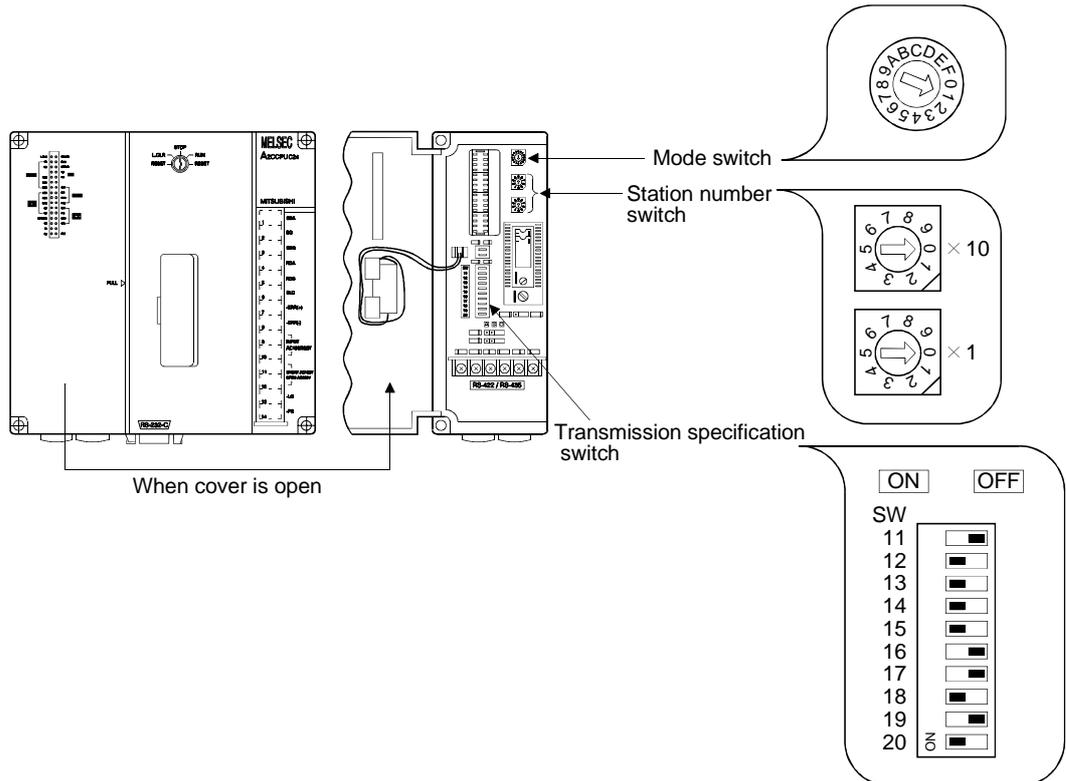
(5) When connecting to A1SJ71UC24-R2, A1SJ71C24-R2



(6) When connecting to A1SCPUC24-R2



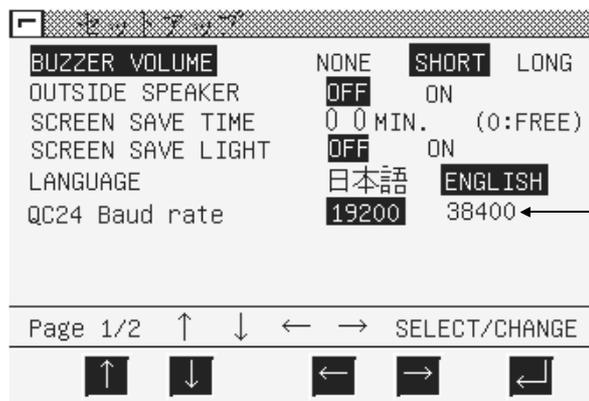
(7) When connecting to A2CCPUC24



6.2.2 GOT side settings

When the GOT is connected with the computer link module or serial communication module for monitoring, the GOT side settings need not be made basically. However, when you use the AJ71QC24N(-R2) or A1SJ71QC24N(-R2) and want to make data transmission of 38400bps, the GOT side transmission speed setting must be changed to 38400bps.

Set the transmission speed on Setup of the GOT's utility function. For details of the utility function, refer to the GOT-A900 Series Operating Manual (SW4D5C-GOTR-PACKE Compatible Extended • Option Function Manual).



QC24 Baud rate
Choose the transmission speed for connection with QC24N.
(Factory-set to 19200bps)

POINT

The utility function can be started by switching power on again after installing the system programs (system OS, communication driver, etc.) into the GOT. After the utility function has started, touch the [Setup] icon to display the setup screen, and make settings related to computer link connection.

6.3 Transmission specifications

The following transmission specifications apply to the case where communication is made between the GOT and computer link or serial communication module.

Item	Settings		
	Using QJ71C24(-R2)	Using AJ71QC24N(-R2) or A1SJ71QC24N(-R2)	Using any module other than those indicated on left
Transmission speed	38400bps	19200bps/38400bps	19200bps
Data length	8 bits		
Stop bit	1 bit		
Parity bit	Yes (odd)		
Sum check	Yes		

6.4 Connection cable

The user needs to fabricate the RS-232C cable which is used to connect the GOT and PLC CPU side (serial communication, computer link module or PLC CPU with computer link function).

The RS-232C cable connection diagram, connector and others are indicated below.

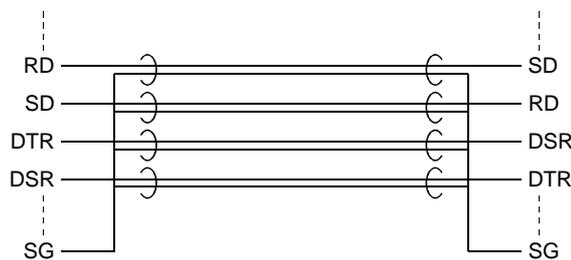
(1) Connection diagram

(a) PLC CPU side connector of D-sub 9 pins

(QJ71C24(-R2), A1SJ71QC24(-R2), A1SJ71UC24-R2, A1SJ71C24-R2, A1SCPUC24-R2, A2CCPUC24)

PLC CPU side		Cable connection and direction of signal	GOT(D-sub 9-pin female inch screw type)	
Signal name	Pin No.		Pin No.	Signal name
CD	1		1	CD
RD(RXD)	2		2	RD(RXD)
SD(TXD)	3		3	SD(TXD)
DTR(ER)	4		4	DTR(ER)
SG ^{*1}	5		5	SG
DSR(DR)	6		6	DSR(DR)
RS(RTS)	7		7	RS(RTS)
CS(CTS)	8		8	CS(CTS)
—	9			

*1 If monitoring is hindered by external noise in A1SJ71QC24 (-R2) connection, connect each cable for signals other than SG and FG together with the cable for SG.



(b) PLC CPU side connector of D-sub 25 pins

(AJ71QC24 (-R2), AJ71UC24)

PLC CPU side		Cable connection and direction of signal	GOT(D-sub 9-pin female inch screw type)	
Signal name	Pin No.		Pin No.	Signal name
FG	1		1	CD
SD(TXD)	2		2	RD(RXD)
RD(RXD)	3		3	SD(TXD)
RS(RTS)	4		4	DTR(ER)
CS(CTS)	5		5	SG
DSR(DR)	6		6	DSR(DR)
SG	7		7	RS(RTS)
CD	8		8	CS(CTS)
DTR(ER)	20		9	—

(2) Connector and connector cover

- GOT connector

Use the connector matching the following model for the GOT.

9-pin D-sub (male) inch screw type

Manufactured by DDK

17LE-23090-27 (D3CC)

- Connector of Computer link unit

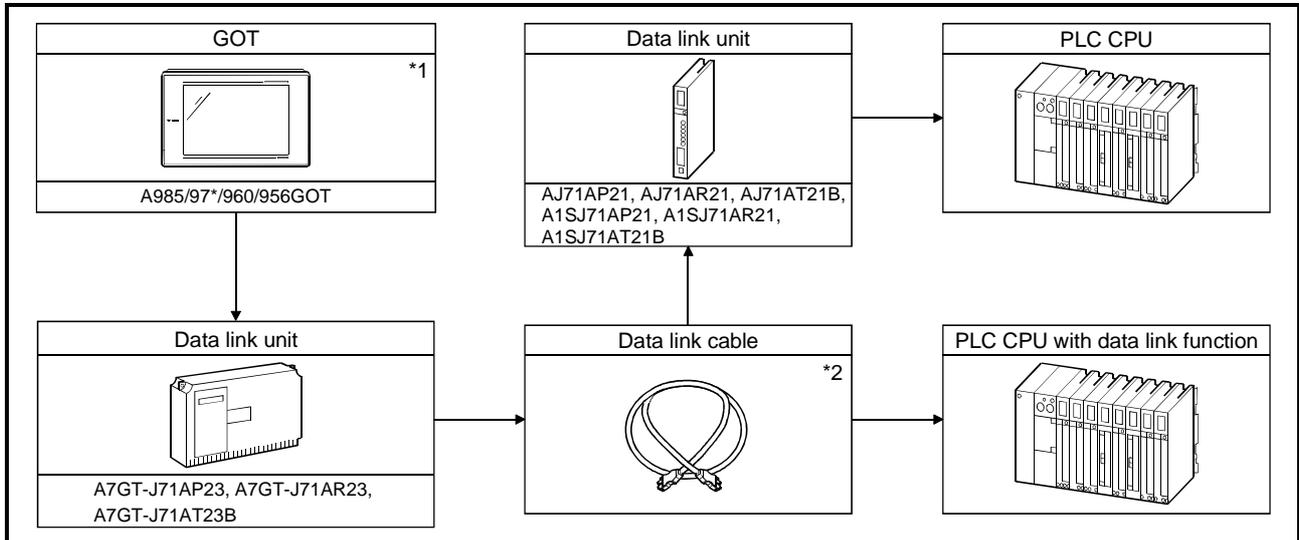
Refer to the user's manual of the computer link unit.

(3) Precautions for cable preparation

The cable must be 15 m (49.21 feet) or shorter.

Chapter7 MELSECNET connection (data link system)

7.1 System configuration



*1 The maximum number of GOT units that allow connection is the number of stations in each data link system that allow connection.

*2 For further details of data link cables (optical fiber cable, coaxial cable, twisted pair cable), refer to the reference manuals of MELSECNET or MELSECNET/B data link system.

7.2 Switch setting of data link unit

Describes about switch setting for using the data link unit.

(1) Station number switch

Since the data link unit is for local stations only, set the switch as follows :

MNET(II) : Stations 1 to 64 (0 : master station is not available)

MNET/B : Stations 1 to 31 (0 : master station is not available)

(2) Mode switch

When using the data link, set this switch to ONLINE.

(3) Baud rate switch (only for MNET/B)

Set the baud rate to the same level as designated for the master station.

7.3 Self-diagnosis test

Self-diagnosis test checks the hardware of the data link unit and for breakage of the link cable.

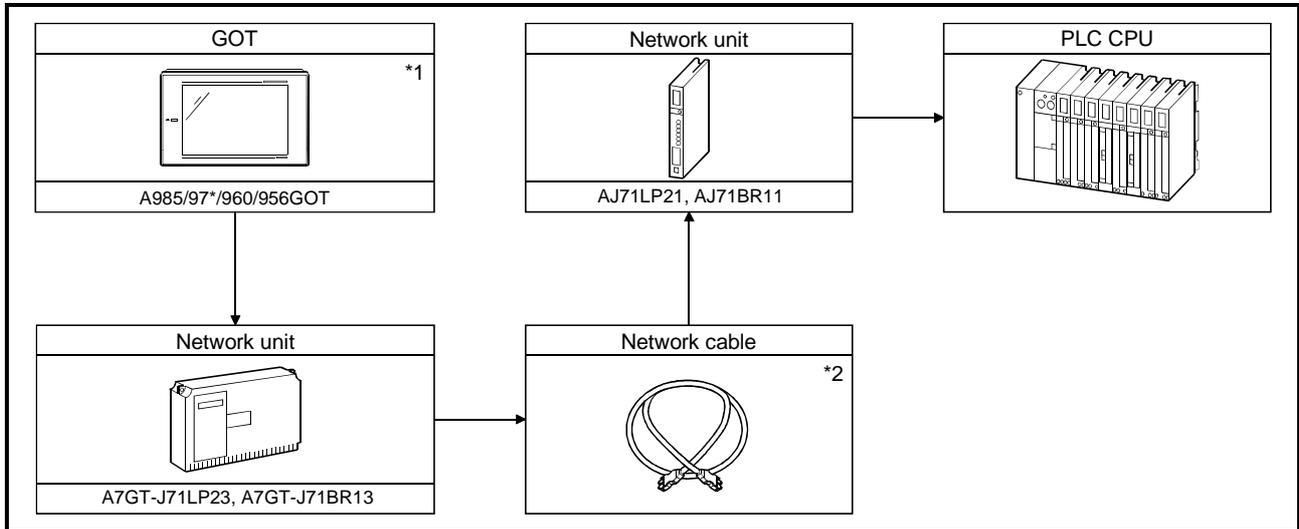
By using the mode switch of the data link unit, the following three modes can be selected.

For test procedures and analysis of the results, refer to the reference manuals of MELSENET or MELSENET/B data link system.

Switch setting	Description	Contents
5	Station-to-station test mode (Main station)	This mode checks the line between 2 stations. The station with more recent number is set as the main station and the one with older number as sub-station.
6	Station-to-station test mode (Sub station)	
7	Self-turning test	This mode checks the hardware including transmission/reception circuit by using a single data link unit.

Chapter8 MELSECNET connection (network system)

8.1 System configuration



*1 The maximum number of GOT units that allow connection is the number of stations in each data link system that allow connection.

*2 For further details of data link cables (optical fiber cable, coaxial cable, twisted pair cable), refer to the reference manual of MELSECNET/10 network system.

8.2 Switch setting of network unit

Describes about switch setting for using the data link unit.

(1) Network No. switch

Designates the network number connected to the network unit.

(2) Group No. switch

Designates the desired group number to incorporate the network unit.

If no group is designated, set this switch to 0.

(3) Station number switch

Designates the network unit as follows. Setting differs between optical loop system and coaxial bus system.

Optical loop system (When using A7GT-J71LP23) : Stations 1 to 64

Coaxial bus system (When using A7GT-J71BR13) : Stations 1 to 32

(4) Mode switch

When using network, set this switch to ONLINE.

8.3 Self-diagnosis test

Self-diagnosis test checks the hardware of the data link unit and for breakage of the link cable.

By using the mode switch of the data link unit, the following 10 modes can be selected.

For test procedures and analysis of the results, refer to the reference manual of MELSENET/10 network system.

Switch setting	Description	Contents
3	Loop test (Main loop)	Checks lines after all stations are connected. Stations other than test object is set to ONLINE before the check. (Only for optical loop system)
4	Loop test (Sub loop)	
5	Station-to-station test mode (Main station)	Checks the line between 2 stations. The station with more recent number is set as the main station and the one with older number as sub-station.
6	Station-to-station test mode (Sub-station)	
7	Self-turning test	Checks the hardware including transmission/reception circuit by using a single network unit.
8	Internal self-turning test	Checks the hardware including transmission/reception circuit by using a single network unit.
9	Hardware test	This mode checks the hardware in the network unit.
D	Network No. confirmation	Confirms the network number, group number, and station number designated for the network.
E	Network No. confirmation	
F	Station No. confirmation	

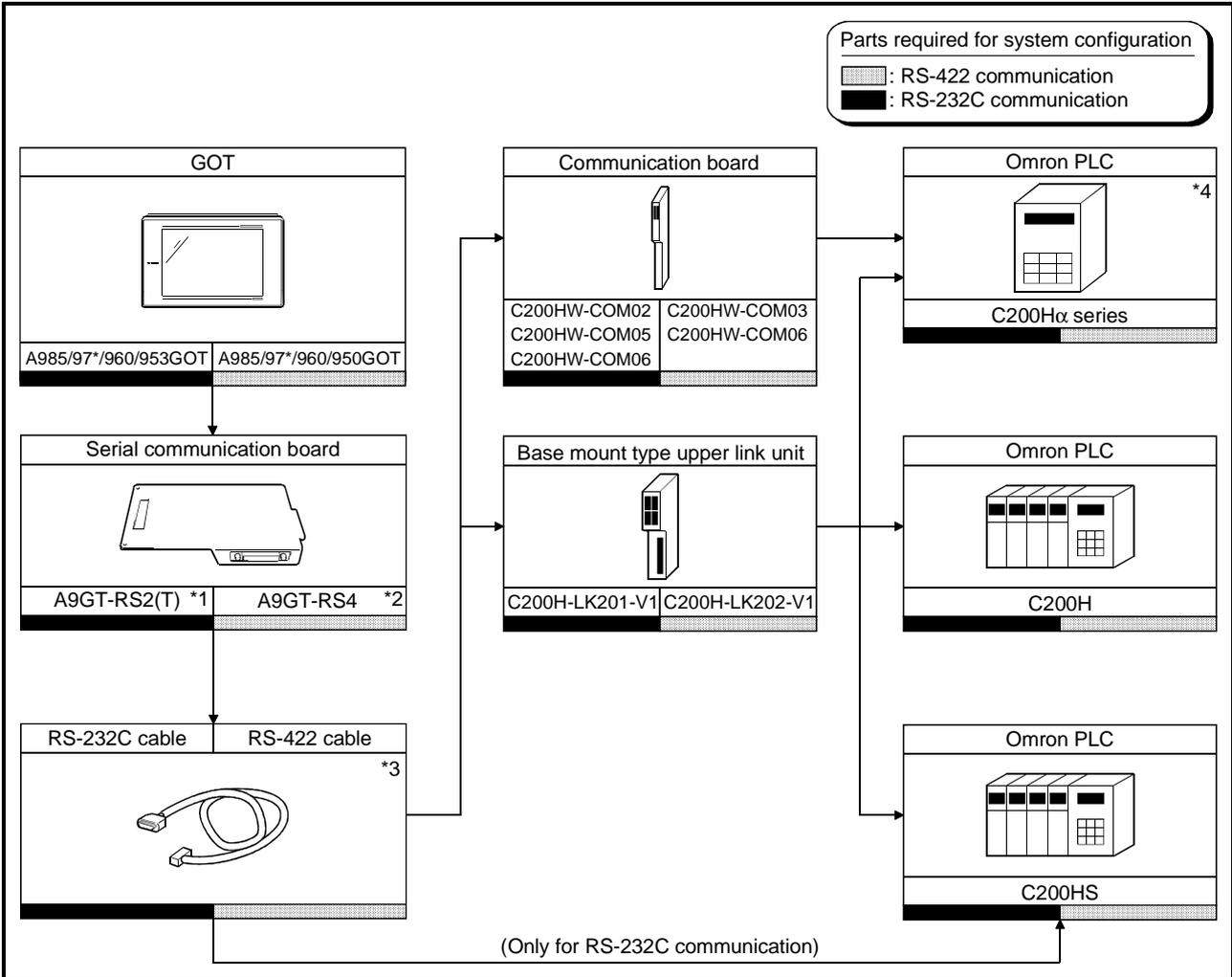
Chapter9 CC-Link connection

For system configuration and precautions of monitoring by CC-Link connection, refer to the user's manual of the CC-Link communication unit (A8GT-J61BT13 or A8GT-J61BT15).

Chapter10 Omron PLC connection

10.1 System configuration

10.1.1 System configuration of connection to C200H, C200HS and C200Hα series



*1 This is not required when the A953GOT (with built-in serial communication interface) is used.

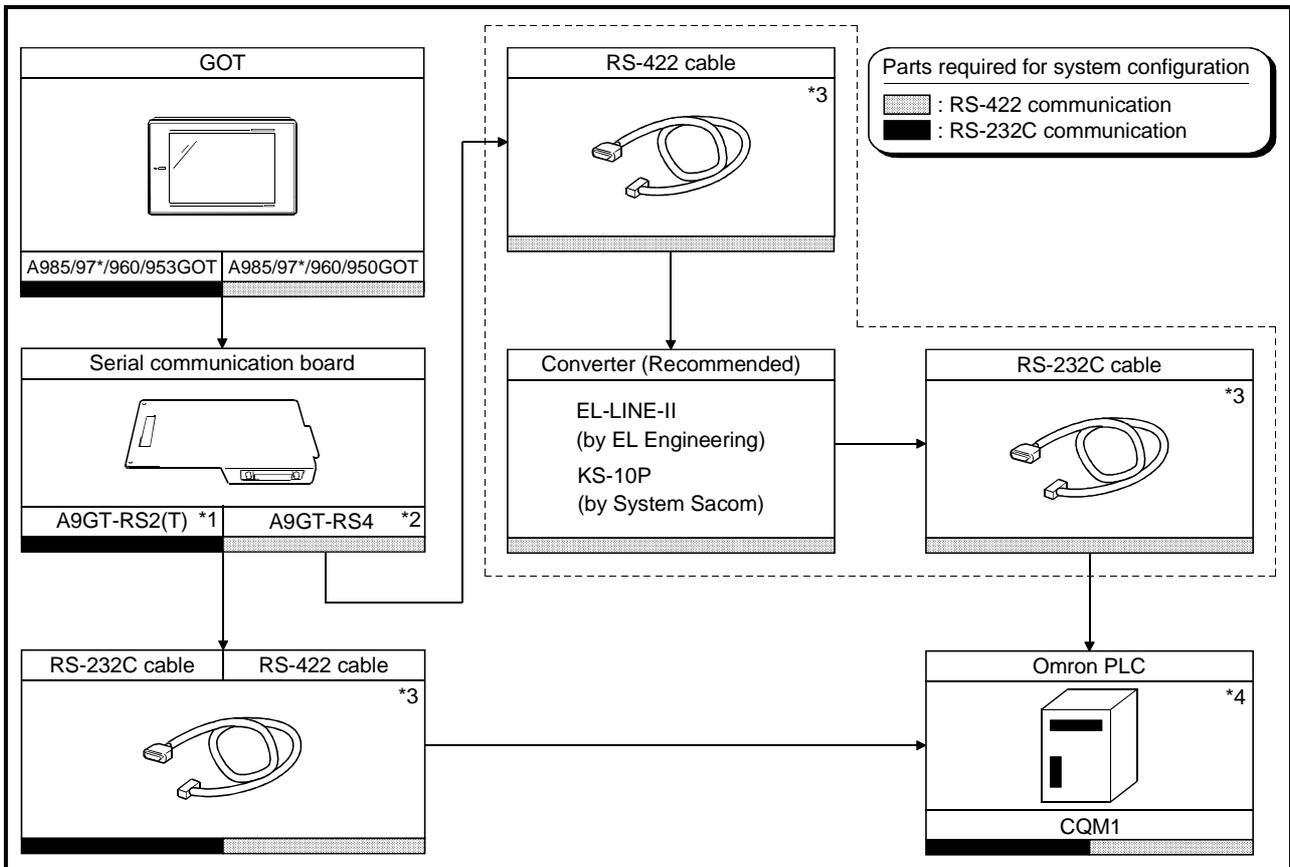
*2 This is not required when the A950GOT (with built-in serial communication interface) is used.

*3 Connection cable must be prepared by the user.

Pin wiring differs between the communication board and the upper link unit.
For details of preparation, refer to 10.3.

*4 The communication board cannot be mounted to C200HE-CPU11.
Mount the board via upper link unit.

10.1.2 System configuration of connection to CQM1



*1 This is not required when the A953GOT (with built-in serial communication interface) is used.

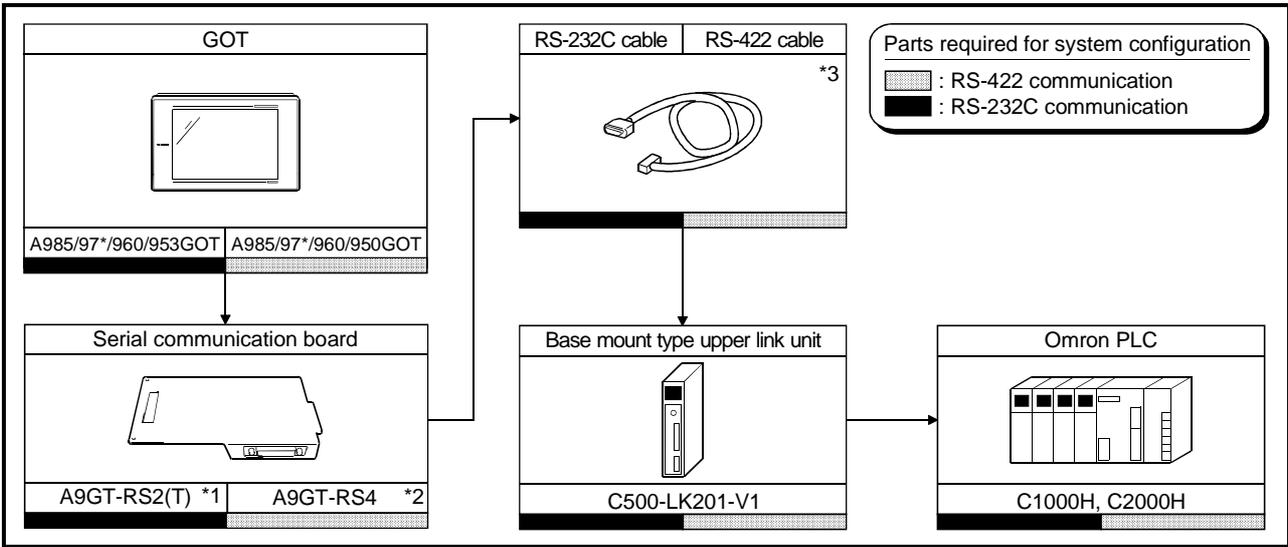
*2 This is not required when the A950GOT (with built-in serial communication interface) is used.

*3 Connection cable must be prepared by the user.

For details of preparation, refer to 10.3.

*4 CQM1-CPU11 cannot be connected because it does not have RS-232C interface.

10.1.3 System configuration of connection to C1000H and C2000H



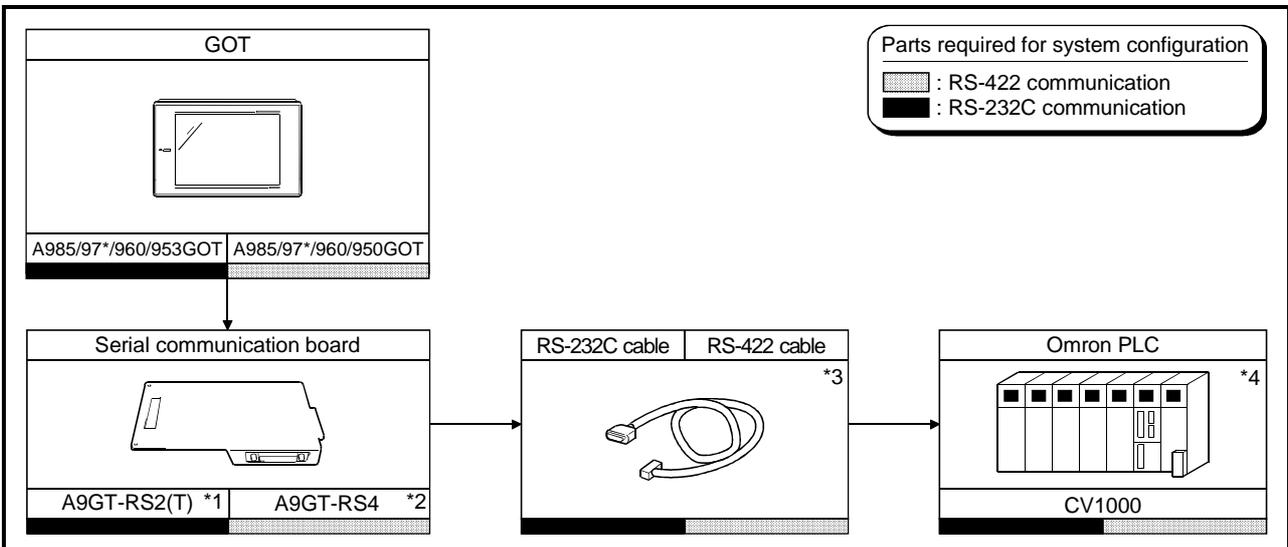
*1 This is not required when the A953GOT (with built-in serial communication interface) is used.

*2 This is not required when the A950GOT (with built-in serial communication interface) is used.

*3 Connection cable must be prepared by the user.

For details of preparation, refer to 10.3.

10.1.4 System configuration of connection to CV1000



*1 This is not required when the A953GOT (with built-in serial communication interface) is used.

*2 This is not required when the A950GOT (with built-in serial communication interface) is used.

*3 Connection cable must be prepared by the user.

For details of preparation, refer to 10.3.

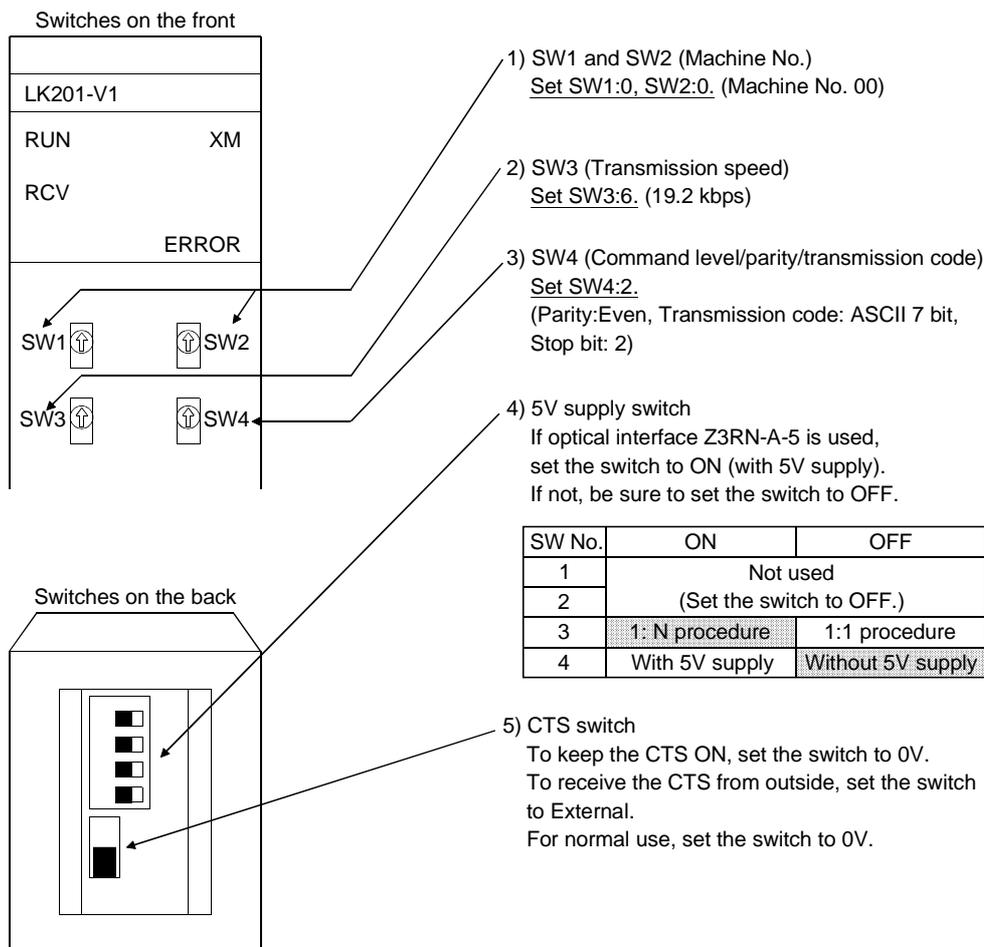
*4 Use CV1000 unit of version 1 or later.

10.2 Initial setting

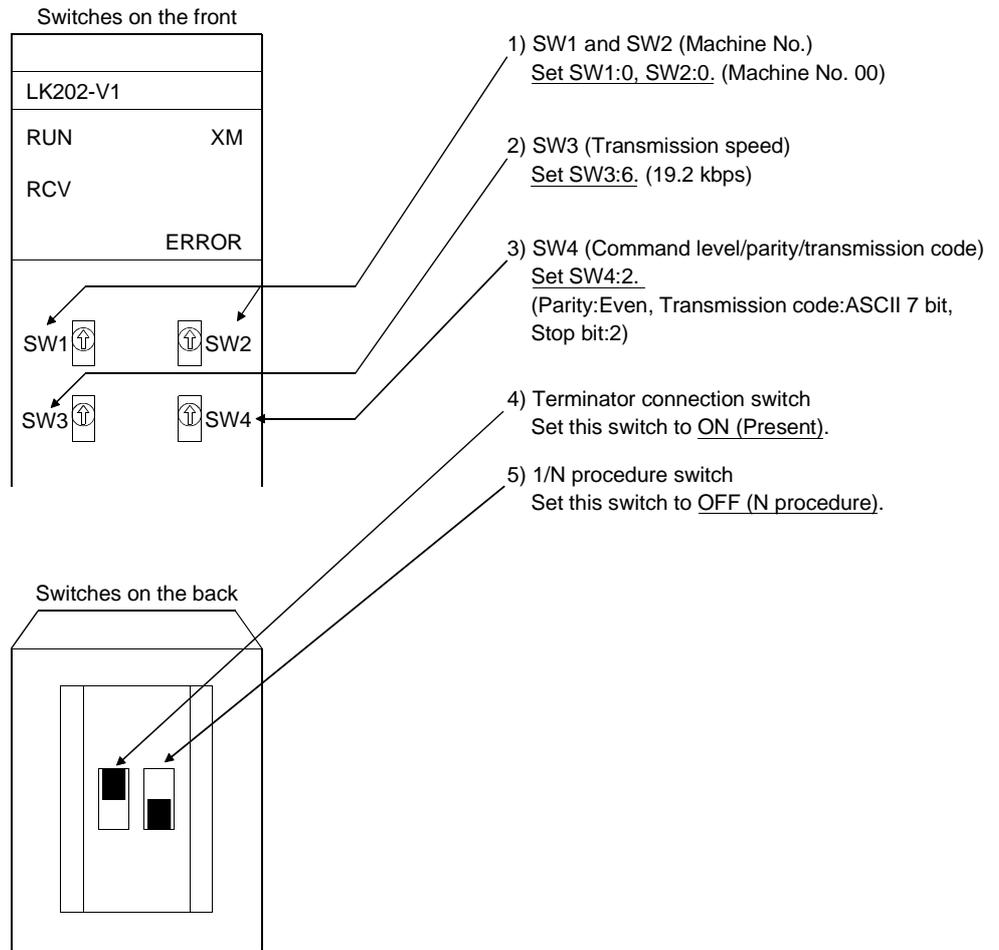
10.2.1 Switch setting of upper link unit

When using the upper link unit (C200H-LK201-V1, C200H-LK202-V1, C500H-LK201-V1), set the switches as follows.

(1) When using C200H-LK201-V1



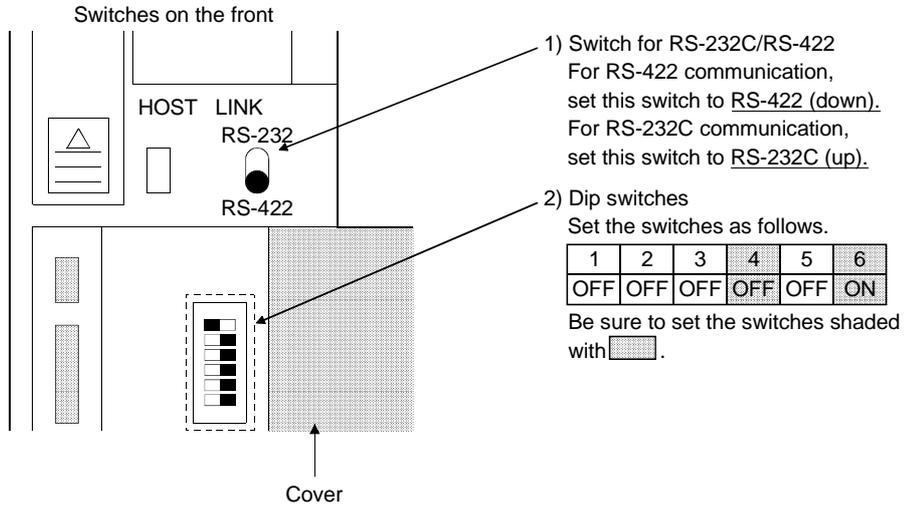
(2) When using C200H-LK202-V1



10.2.2 Setting CV1000

(1) Switches

For CPU (CV1000), set the switches as follows.



(2) Setting by peripheral tool

Use a peripheral tool to set the CPU (CV1000) as follows.

Item	Set value
Transmission speed	19200bps
Stop bit	2 stop bit
Parity	Even parity
Data length	7 bit
Machine No.	Machine No. 00

10.2.3 Initializing CQM1

Before using the RS232C port of CQM1, write values to the devices as follows and initialize the port by using a peripheral tool or the DM monitor.

For further details, refer to the instruction manual of CQM1.

Device name	Value	Device name	Value
DM6645	0001H	DM6646	0304H
DM6647	0000H	DM6648	0000H
DM6649	0000H		

10.2.4 Communication board initialization program

Before using the communication board, write values to the devices as follows and initialize port A of the communication board.

For application of devices and initialization programs, refer to the instruction manual of the communication board.

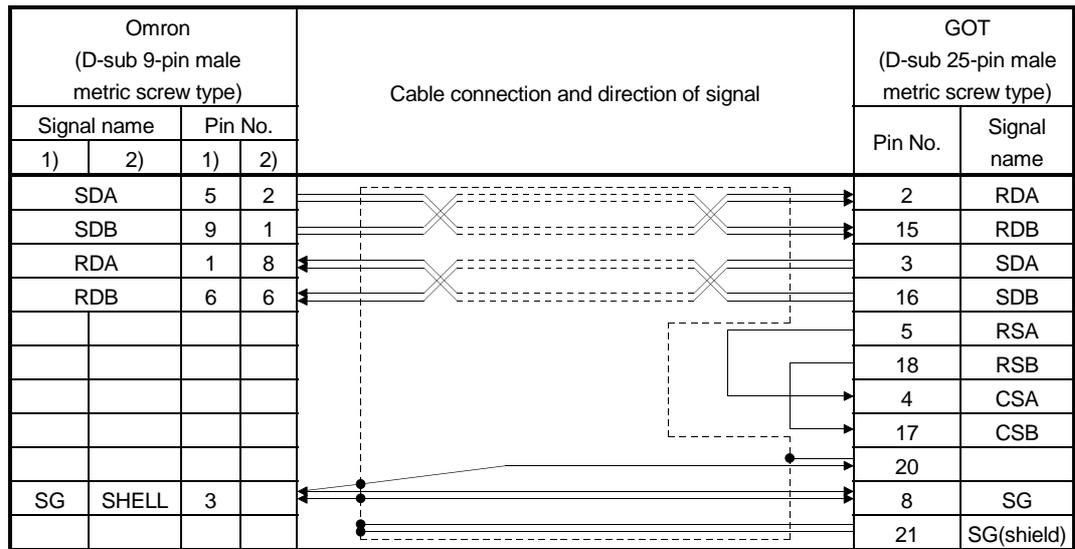
Device name	Value	Device name	Value
DM6550 to DM6554	Not required	DM6555	0001H
DM6556	0304H	DM6557	0000H
DM6558	0000H	DM6559	0000H

10.3 Connection cable

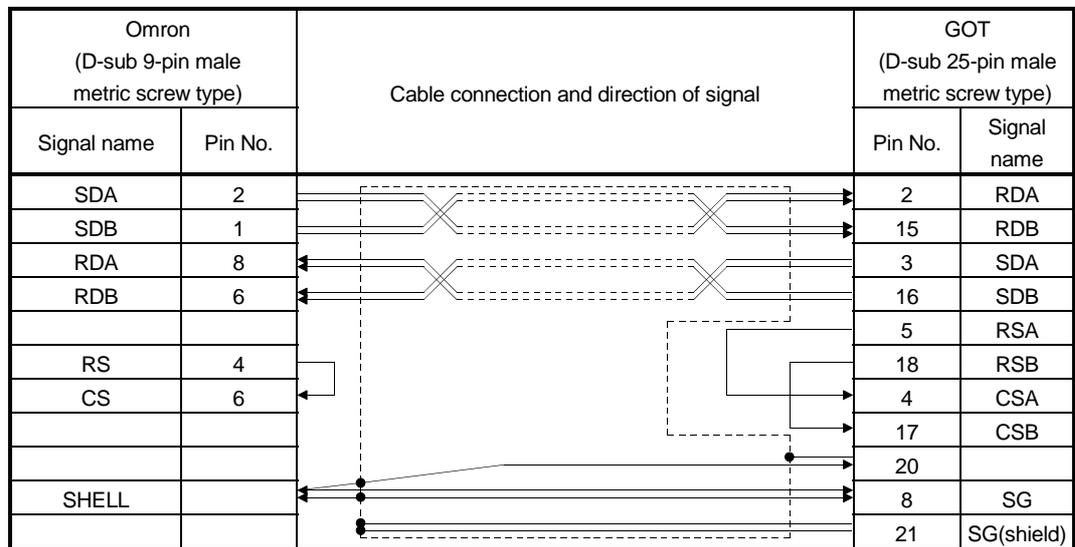
10.3.1 RS-422 cable

The connection diagram and connectors for the RS-422 cables between the upper link unit, the communication board, the CPU (CV1000) and the GOT are as follows.

- (1) Connection diagram
 - 1) Upper link unit
 - 2) Communication board



3) CPU(CV1000)



(2) Connector and connector cover

• Connector for GOT

Description	Model	Manufacturer
Connector with cover	17JE-23250-02(D8A6)	DDK

• Connector for Omron

Use connectors attached to the upper link unit, the communication board and the CPU (CV1000).

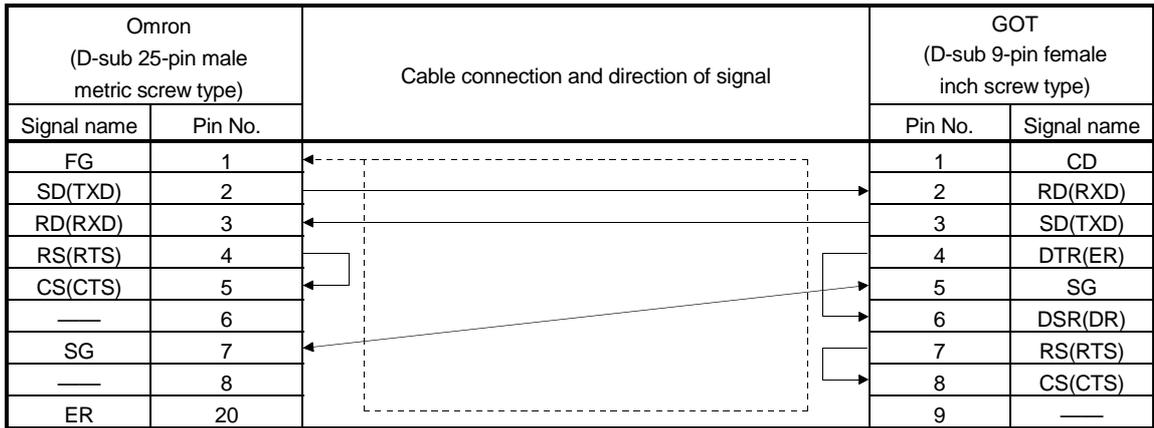
(3) Precautions for cable preparation

The cable must be 200m(655.74feet) or shorter.

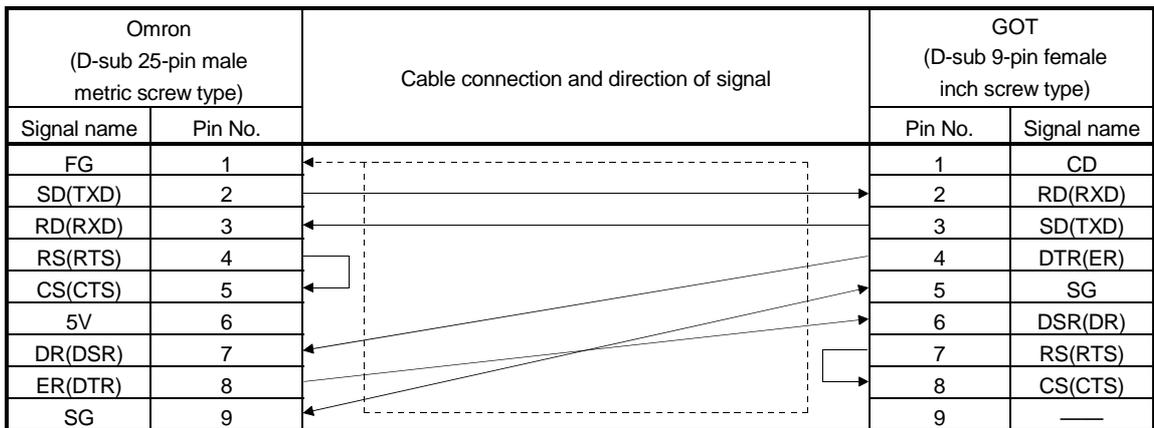
10.3.2 RS-232C cable

The connection diagram and connectors for the RS-232C cables between the upper link unit, the communication board, the CPU (CV1000, CQM1) and the GOT are as follows.

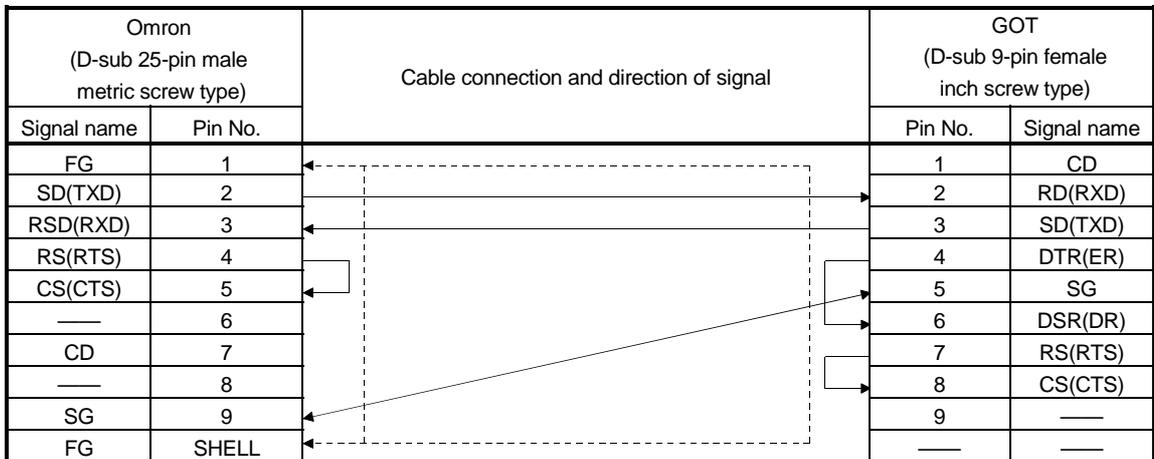
(1) Connection diagram
1) Upper link unit



2) Communication board



3) CPU (CV1000, CQM1)



(2) Connector and connector cover

- Connector for GOT

Use connector matching the following connector that is used for the GOT.

9-pin D-sub (male) inch screw type

Manufactured by DDK

17LE-23090-27 (D3CC)

- Use connectors attached to the upper link unit, the communication board and the CPU (CV1000, CQM1).

(3) Precautions for cable preparation

The cable must be 15m(49.18feet) or shorter.

10.3.3 Converter and connection cable used in CQM1

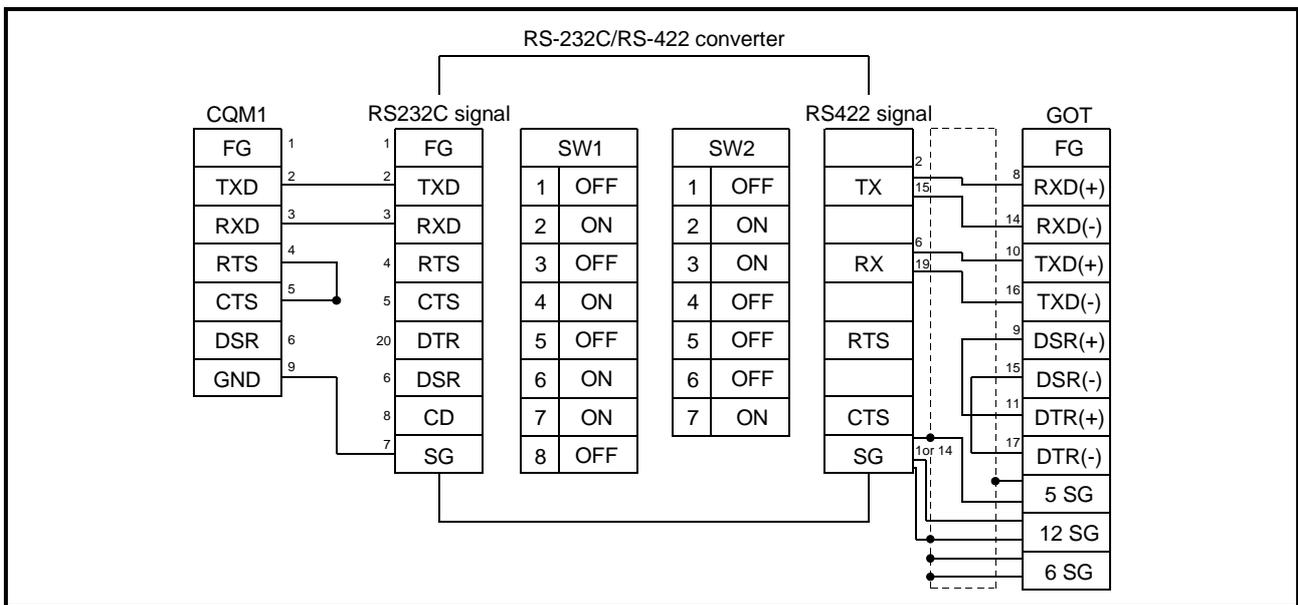
The converters (recommended parts) for connecting the CQM1 and the GOT, and the connection diagram and connectors are as follows.

(1) Available converter

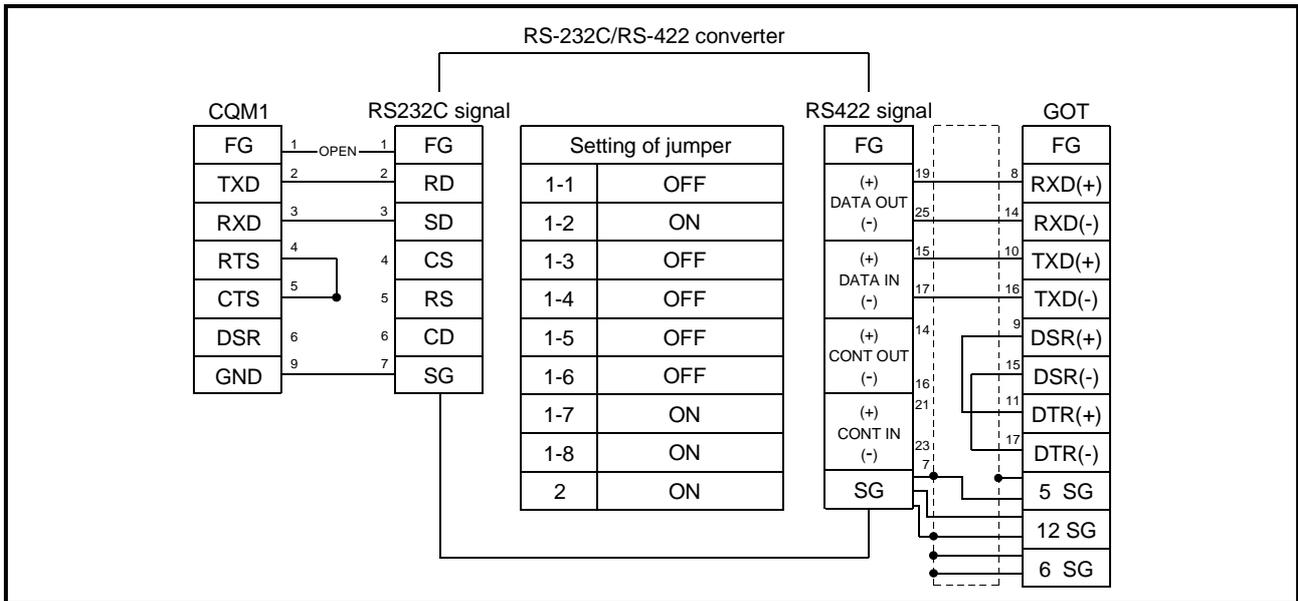
Model name	Manufacturer
EL-LINE-II	EL Engineering
KS-10P	System Sacom

(2) Connection diagram

1) When using EL-LINE-II



2) When using KS-10P



(3) Connector and connector cover

- Connector for GOT

Description	Model	Manufacturer
Connector with cover	17JE-23250-02(D8A6)	DDK

- Connector for CQM1

Use connector attached to the CQM1.

- When using EL-LINE-II

RS-232C : D-Sub 25-pin male screw type

RS-422 : D-Sub 25-pin female screw type

- When using KS-10P

RS-232C : D-Sub 9-pin male screw type

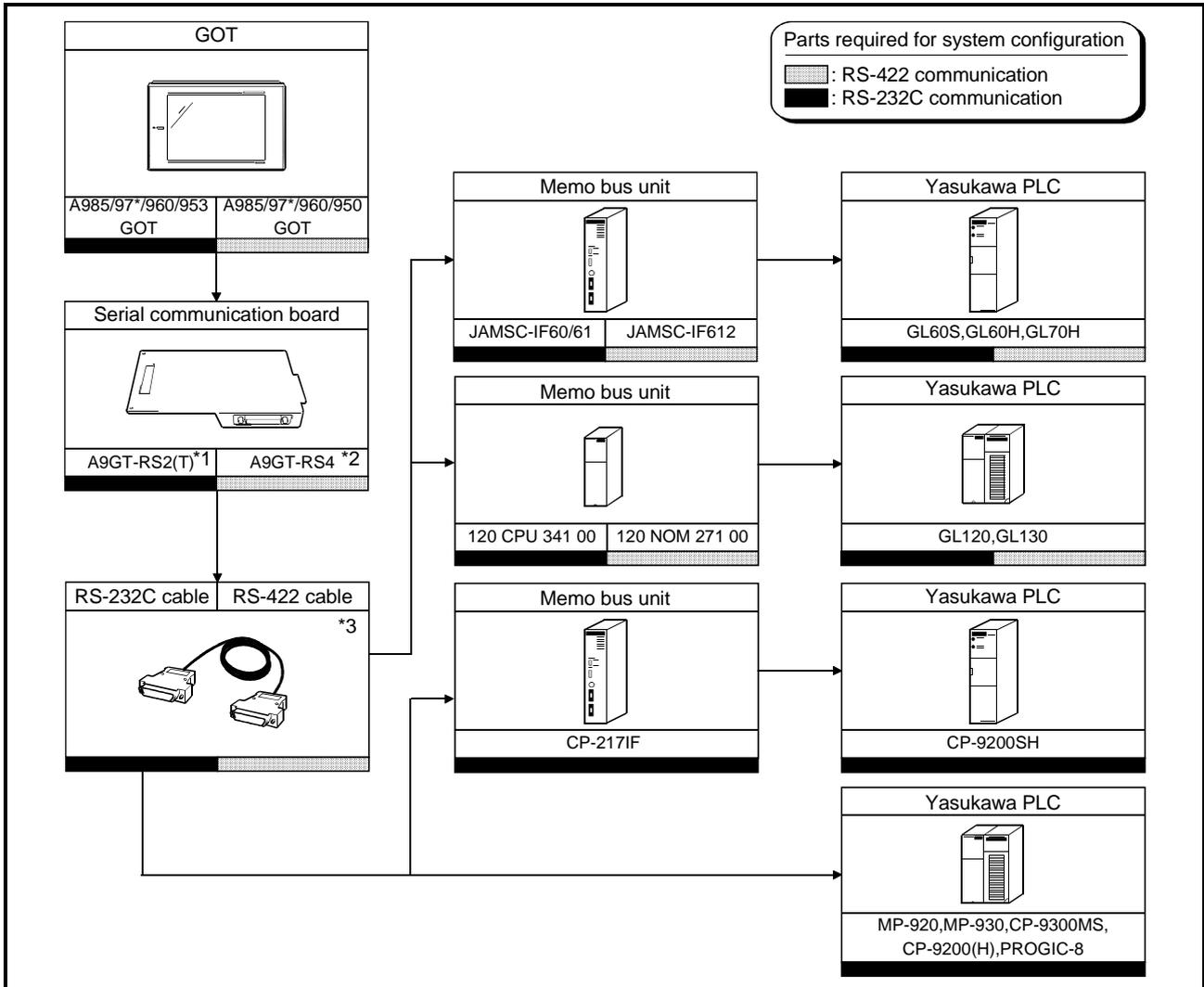
RS-422 : D-Sub 25-pin female screw type

(4) Precautions for cable preparation

- The cable length (including the converter) must be 200m(655.74feet) or shorter.

Chapter11 Yasukawa PLC connection

11.1 System configuration



*1 This is not required when the A953GOT (with built-in serial communication interface) is used.

*2 This is not required when the A950GOT (with built-in serial communication interface) is used.

*3 Connection cable must be prepared by the user.

For details of preparation, refer to 11.3.

11.2 Initial settings

(1) Yasukawa Electric PLC side settings

When connecting the GOT and Yasukawa Electric PLC, make the following communication and port settings with the peripheral tool.

For details of the setting method, refer to the instruction manual of the Yasukawa Electric PLC.

Item	Set value
Address	1
Protocol	MEMOBUS
Mode	RTU
Data length	8
Parity	EVEN
Stop	1
Communication speed (transmission speed)*	4800bps/9600bps/19200bps/38400bps

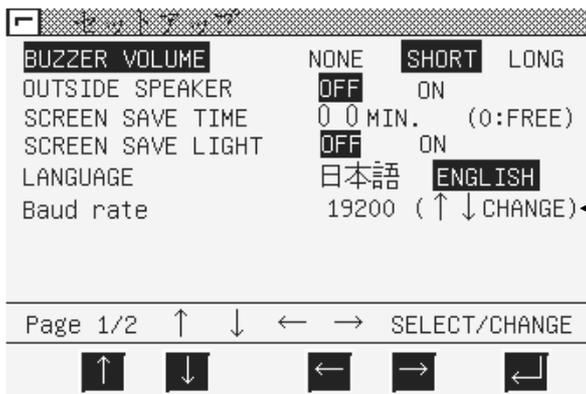
*The upper limit that may be set changes with the Yasukawa Electric PLC used.

(2) GOT side settings

When connecting the GOT and Yaskawa Electric PLC, you need to set the transmission speed to the GOT according to the setting of the Yaskawa Electric PLC used.

Set the transmission speed on Setup of the GOT's utility function.

For details of the utility function, refer to the GOT-A900 Series Operating Manual (SW4D5C-GOTR-PACKE Compatible Extended • Option Function Manual).



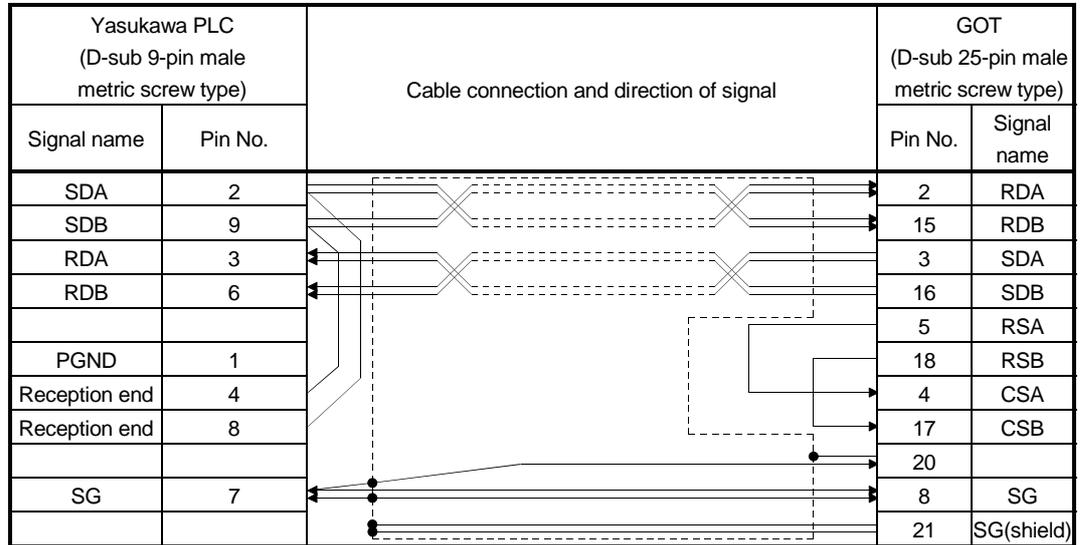
Baud rate
Choose the GOT side transmission speed.
(Factory-set to 19200bps)

POINT	<p>The utility function can be started by switching power on again after installing the system programs (system OS, communication driver, etc.) into the GOT.</p> <p>After the utility function has started, touch the [Setup] icon to display the setup screen, and make settings related to Yasukawa PLC connection.</p>
--------------	--

11.3 Connection cable

11.3.1 RS-422 cable

(1) Connection diagram



(2) Connector and connector cover

- Connector for GOT

Description	Model	Manufacturer
Connector with cover	17JE-23250-02(D8A6)	DDK

- Connector for Yasukawa PLC

Use a connector matching the memo bus unit.

(3) Precautions for cable preparation

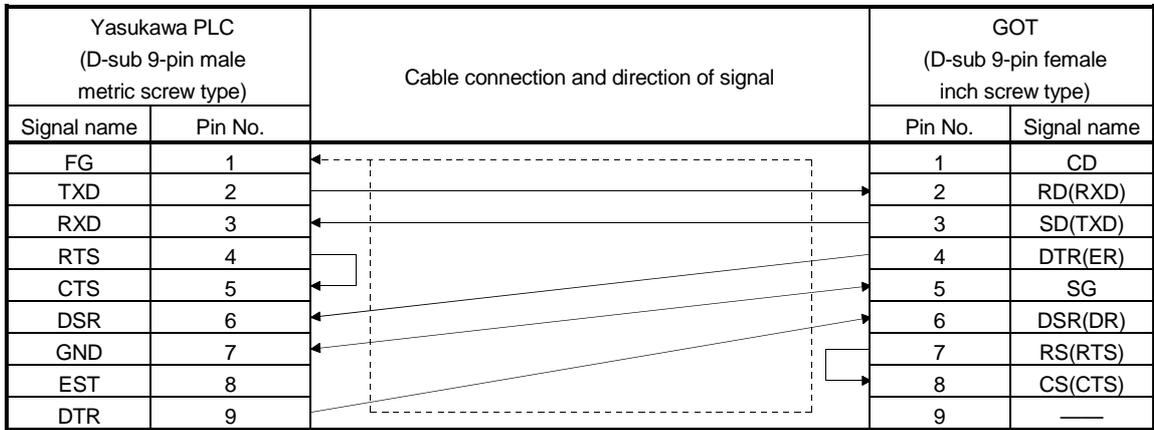
Maximum cable length depends on the specifications of the memo bus unit.

For further details, refer to the instruction manual of the memo bus unit.

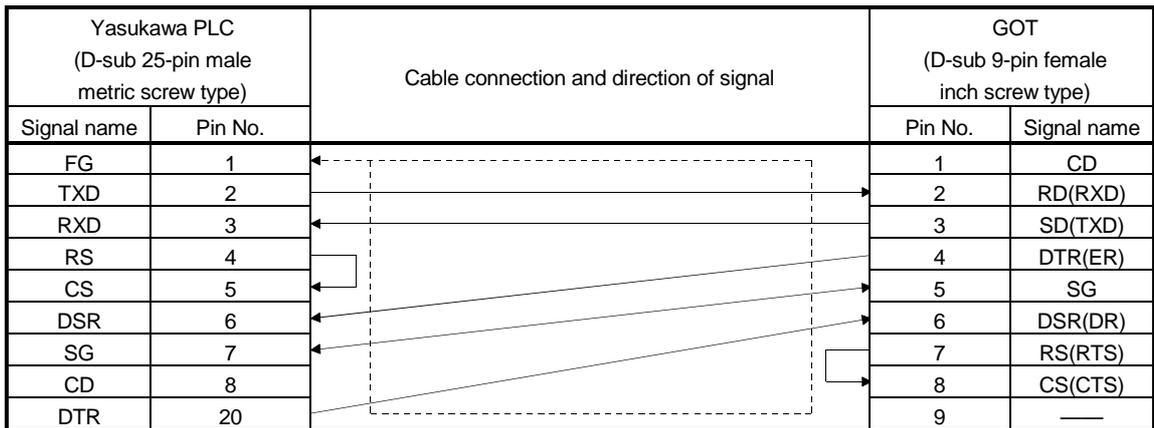
11.3.2 RS-232C cable

(1) Connection diagram

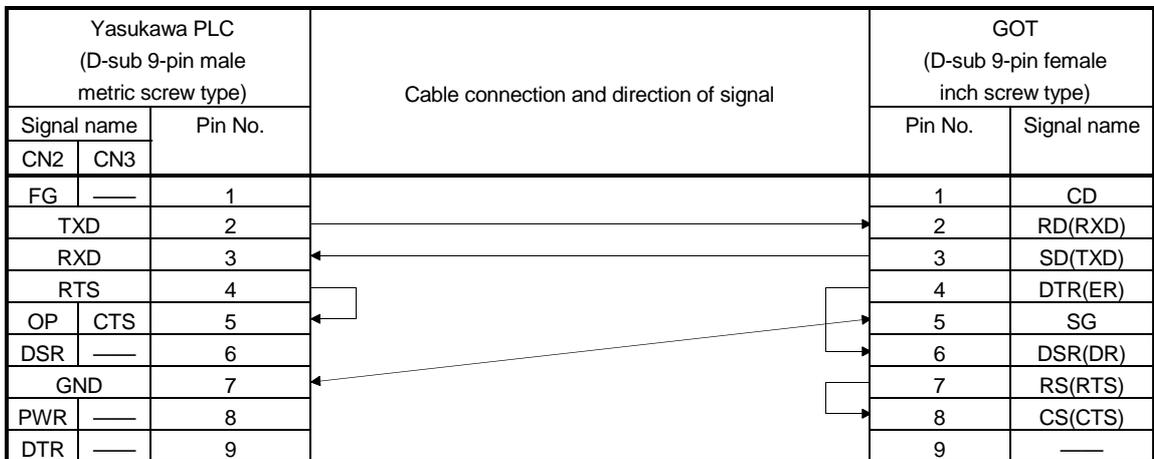
(a) When using GL60S, GL60H, GL70H, GL120, GL130, MP-920, MP-930, CP-9200(H) or PROGIC-8 (when using D-sub 9-pin port)



(b) When using CP-9200SH



(c) When using CP-9300MS



(d) When using PROGIC-8 (when using D-sub 15-pin port)

Yaskawa PLC side (D-sub 15-pin male metric screw type)		Cable connection and signal direction	GOT (D-sub 9-pin female inch screw type)	
Signal name	Pin No.		Pin No.	Signal name
FG	1		1	CD
TXD	2		2	RD(RXD)
RXD	3		3	SD(TXD)
RTS	4		4	DTR(ER)
CTS	5		5	SG
DSR	6		6	DSR(DR)
GND	7		7	RS(RTS)
EST	8		8	CS(CTS)
DTR	9		9	—

(2) Connector and connector cover

- Connector for GOT

Use connector matching the following connector that is used for the GOT.

9-pin D-sub (male) inch screw type

Manufactured by DDK

17LE-23090-27 (D3CC)

- Connector for Yasukawa PLC

Use connectors matching the Yasukawa PLC.

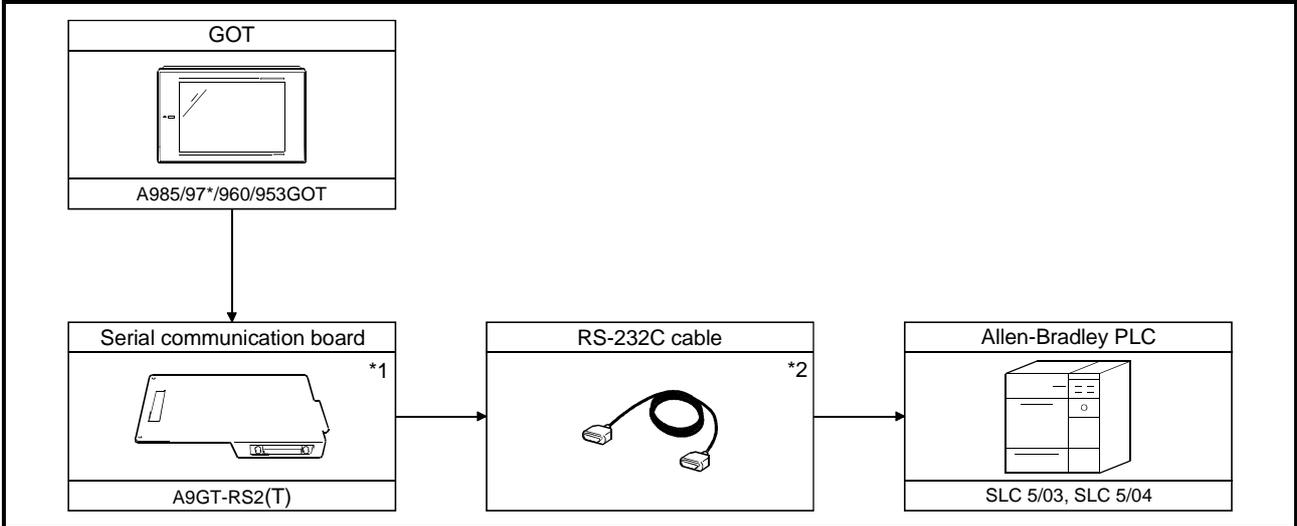
(3) Precautions for cable preparation

The maximum cable length depends on the specifications of the Yasukawa PLC.

For further details, refer to the instruction manuals of the Yasukawa PLC.

Chapter12 Allen-Bradley PLC connection

12.1 System configuration



*1 This is not required when the A953GOT (with built-in serial communication interface) is used.

*2 The connection cable must be prepared by the user.
For details of preparation, refer to 12.4.

12.2 Communication settings of Allen-Bradley PLC

For monitoring with connection to the GOT, make the communication settings and the port settings with the peripheral tool as follows.

For details, refer to the operation manual of the Allen-Bradley PLC.

Setting of Allen-Bradley PLC	
Band Rate	19200bps
	—
	—
Parity	EVEN
	—
	—
Communication Driver	DF1 HALF-DUPLEX SLAVE
Duplicate Packet Detection	DISABLE
Error Detection	BCC
Control Line	NO HANDSHAKING
Station Address	0

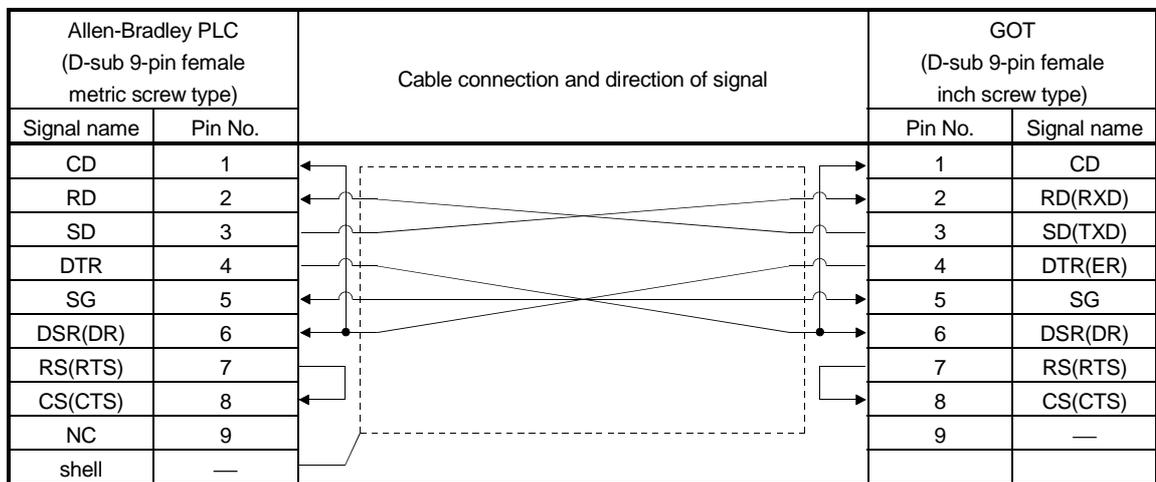
12.3 Transmission specification

Transmission specification for communication between the GOT and the Allen-Bradley PLC is as follows:

Item	Setting details
Transmission speed	19200bps
Data length	8 bit
Stop bit	1 bit
Parity bit	EVEN
Control method	None

12.4 Connection cable

(1) Connection diagram



(2) Connector and connector cover to be used

- GOT connector
The following connector is used for RS-232C interface of A9GT-RS2.
Use the connector at the other end matching this connector.

9-pin D sub (male) inch screw type
Made by DDK
17LE-23090-27 (D3CC)

- Connector for Allen-Bradley PLC
Use the connector that matches the Allen-Bradley PLC.

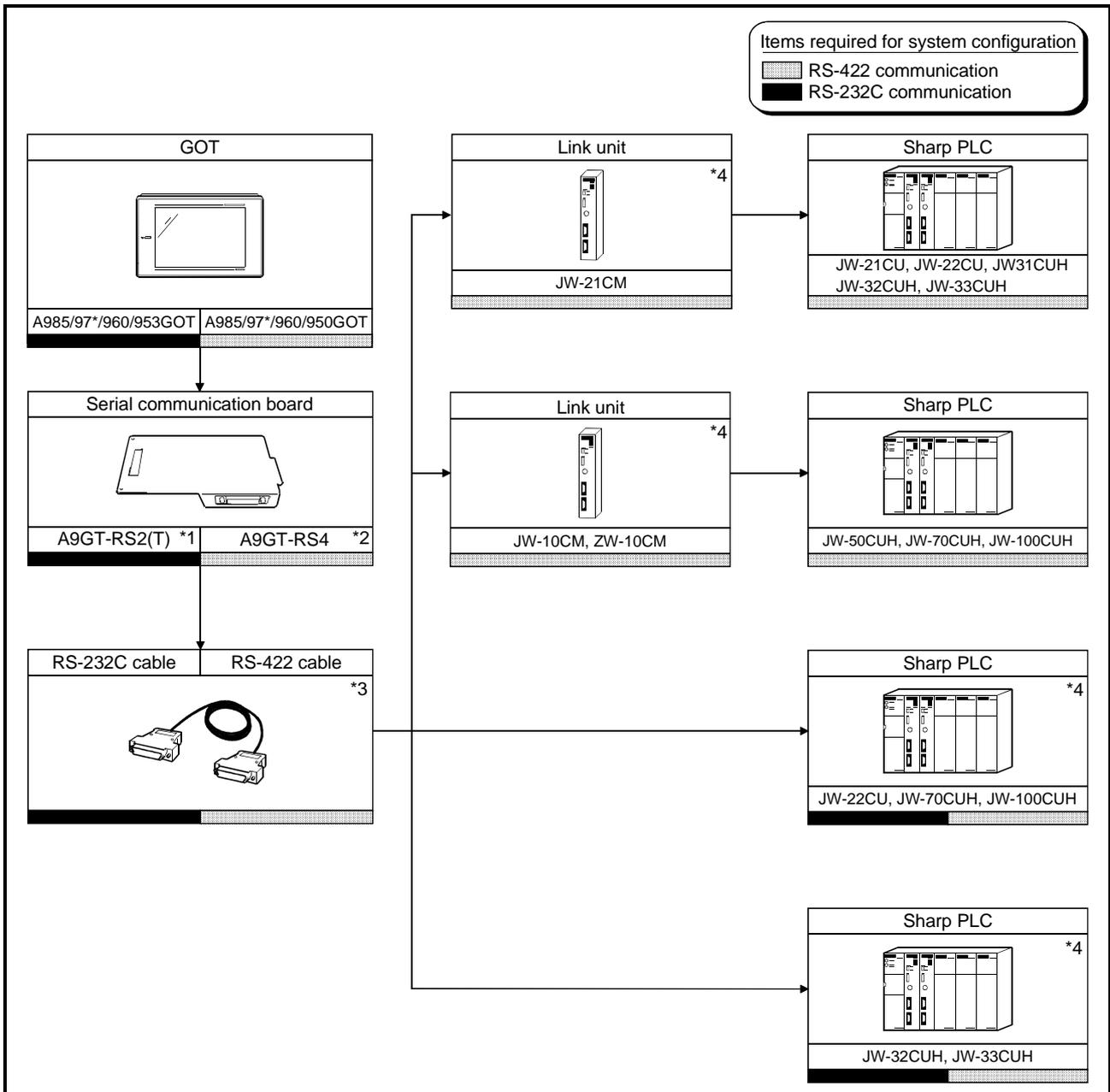
(3) Precautions for preparation of connector

The maximum cable length may vary depending on the specification of the Allen-Bradley PLC specification.

For details, refer to the Allen-Bradley PLC operation manual.

Chapter13 Sharp PLC connection

13.1 System configuration



*1 This is not required when the A953GOT (with built-in serial communication interface) is used.

*2 This is not required when the A950GOT (with built-in serial communication interface) is used.

*3 The connection cable must be prepared by the user.
For details of preparation, refer to 13.4.

*4 For communication to the GOT, it is necessary to make settings for communication.
For details of settings, refer to 13.2.

13.2 Initial setting

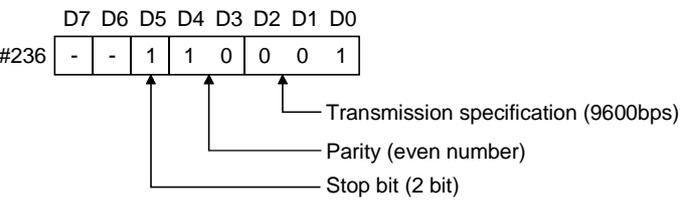
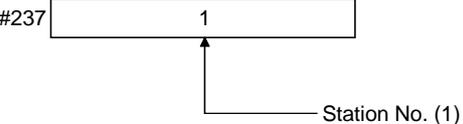
13.2.1 Connecting directly to the PLC CPU

To connect the GOT to the PLC CPU directly, it is necessary to make initial settings of the communication port.

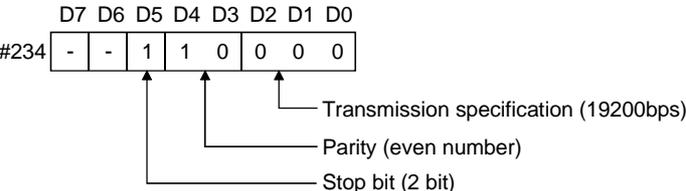
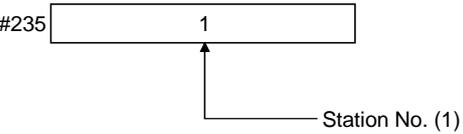
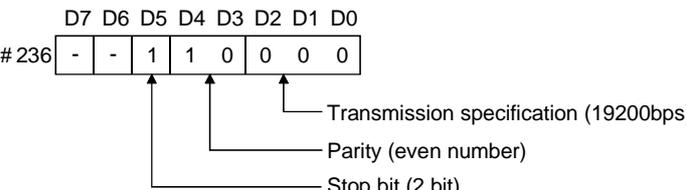
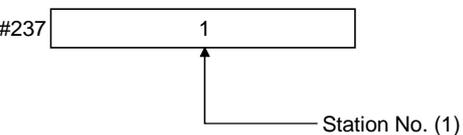
Set the system memory of the PLC CPU with the peripheral tool as follows.

For details of the setting method, refer to the operation manual of the Sharp PLC.

(1) When using JW-22CUH, JW-70CUH and JW-100CUH

Setting item	System memory address	Setting details
Setting of communication port	# 236	Set the transmission speed, the parity and the stop bit to the bit of D0 to D5 as follows : 
	# 237	Set the station number as follows : 

(2) When using JW-32CUH and JW-33CUH

Setting item	System memory address	Setting details
Setting of communication port 1	# 234	Set the transmission speed, the parity and the stop bit to the bit of D0 to D5 as follows : 
	# 235	Set the station number as follows : 
Setting of communication port 2	# 236	Set the transmission speed, the parity and the stop bit to the bit of D0 to D5 as follows : 
	# 237	Set the station number as follows : 

13.2.2 Connecting to the link unit

To connect the GOT to the link unit, it is necessary to make settings for initial communication.

Set the switches on the link unit as follows.

For details of the setting method, refer to the operation manual of the link unit.

Switch No.	Setting item	Set value
SW3	2	2 wire /4 wire
	4	Parity
SW4	Setting of transmission speed	0 (19200 bit/s)

13.3 Transmission specification

Transmission specification for communication between the GOT and the Sharp PLC is as follows :

(1) JW-22CU, JW-70CUH, JW-100CUH (when directly connected to the PLC CPU)

Item	Set value
Transmission speed	9600bps
Data length	7 bit
Stop bit	2 bit
Parity bit	EVEN
Control method	None

(2) JW-32CUH, JW-33CUH (when directly connected to the PLC CPU)

Item	Set value
Transmission speed	19200bps
Data length	7 bit
Stop bit	2 bit
Parity bit	EVEN
Control method	None

(3) JW-21CU, JW-22CU, JW-31CUH, JW-32CUH, JW-33CUH, JW-50CUH, JW-70CUH, JW-100CUH,
(when connected through the link unit)

Item	Set value
Transmission speed	19200bps
Data length	7 bit
Stop bit	2 bit
Parity bit	EVEN
Control method	None

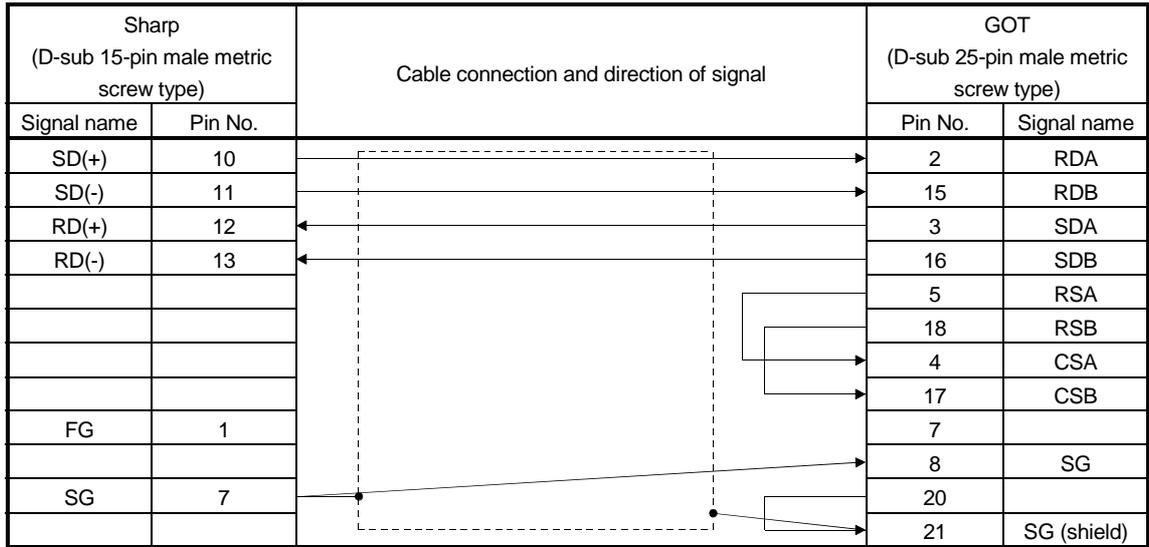
13.4 Connection cable

13.4.1 RS-422 cable

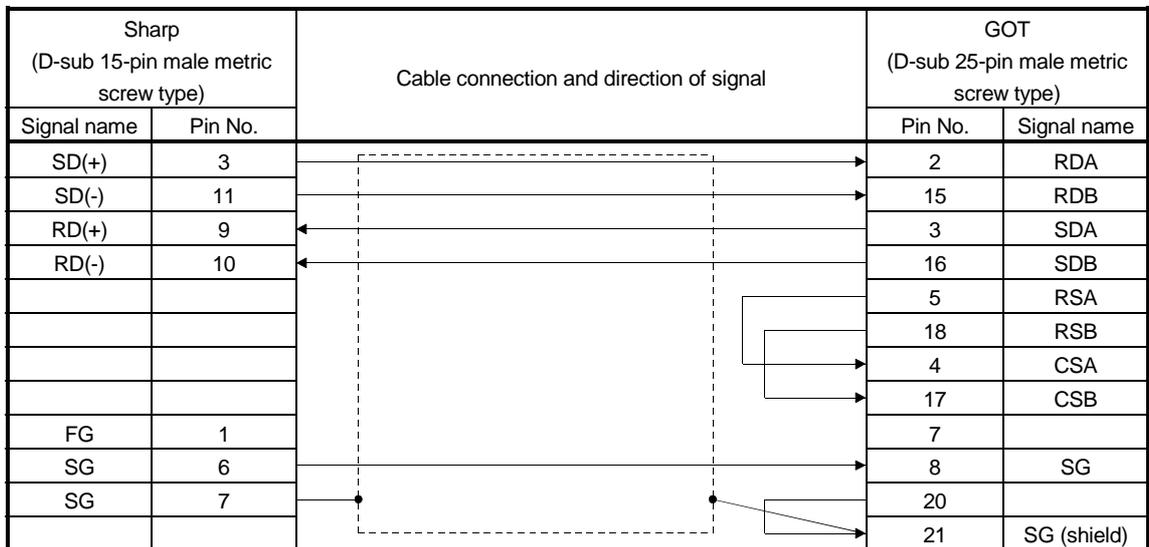
The RS-422 cable connection diagram and the connector for the PLC CPU and the link unit are as follows :

(1) Connection diagram

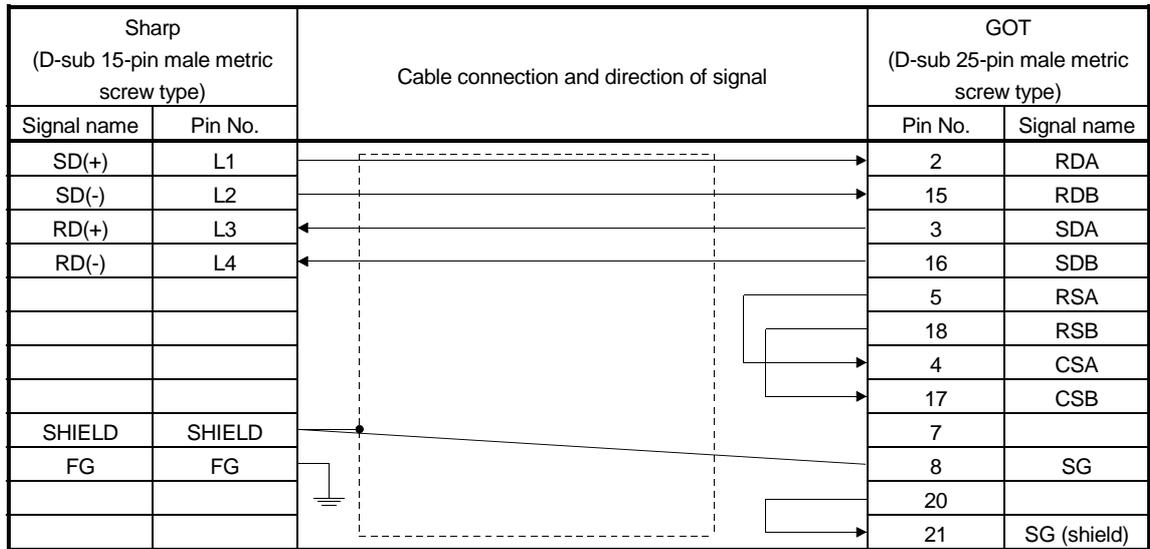
(a) PLC CPU (JW-22CU, JW-70CUH, JW-100CUH)



(b) PLC CPU (JW-32CUH, JW-33CUH)



(c) Link unit (JW-21CM, JW-10CM, ZW-10CM)



(2) Connector and connector cover to be used

- GOT connector

Name	Type	Manufacturer
Connector with cover	17JE-23250-02(D8A6)	DDK

- Connector at Sharp PLC

Use the connector matching the Sharp PLC.

(3) Precautions for preparation of connector

The maximum cable length may vary depending on the specification of the Sharp PLC specification.

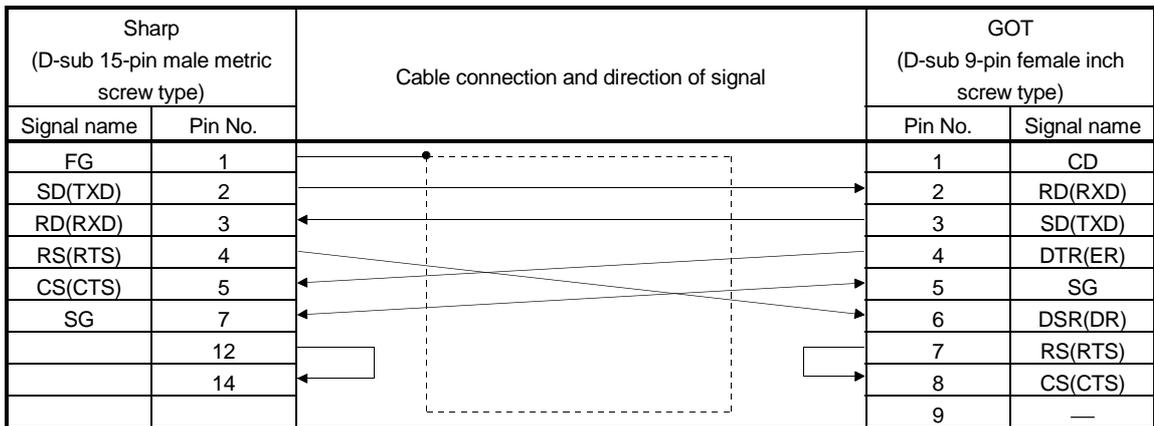
For details, refer to the Sharp PLC operation manual.

13.4.2 RS-232C cable

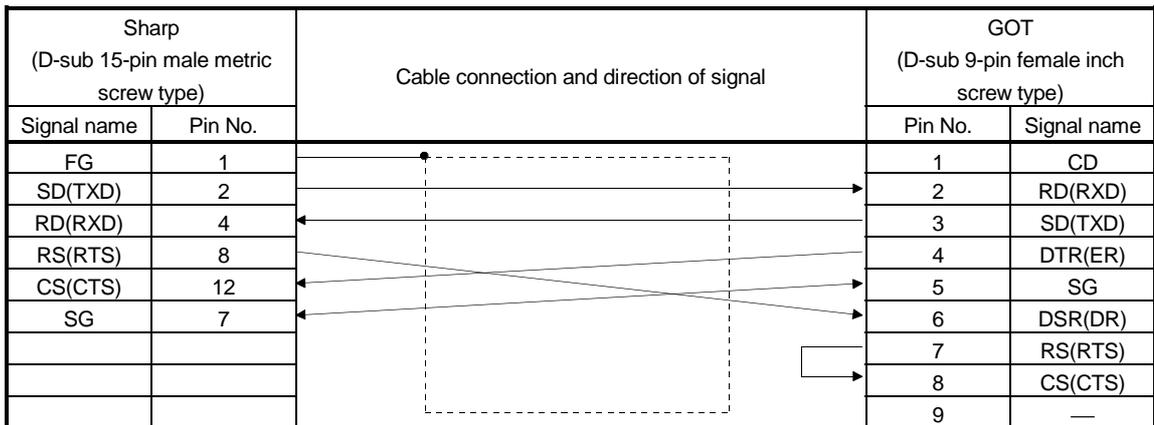
The RS-232C cable connection diagram and the connector for the PLC CPU and the GOT are as follows :

(1) Connection diagram

(a) PLC CPU (JW-22CU, JW-70CUH, JW-100CUH)



(b) PLC CPU (JW-32CUH, JW-33CUH)



(2) Connector and connector cover to be used

- GOT connector

The following GOT connector is used. Use the connector at the other end matching this connector.

9-pin D sub (male) inch screw type

Made by DDK

17LE-23090-27 (D3CC)

- Connector for Sharp PLC

Use the connector that matches the Sharp PLC.

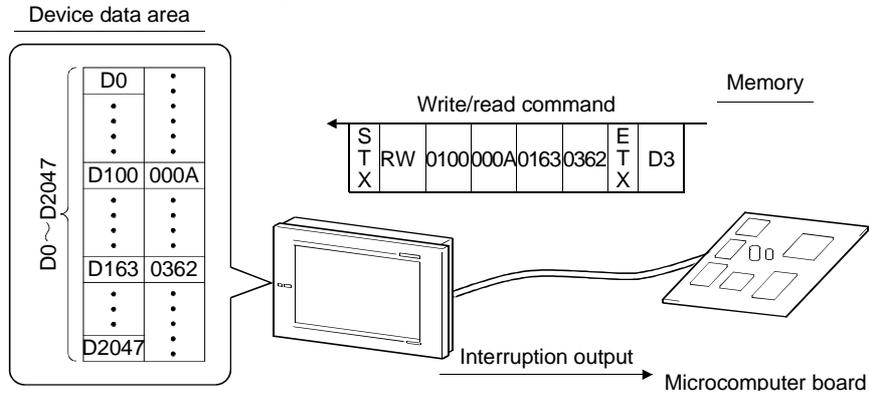
(3) Precautions for preparation of connector

The maximum cable length may vary depending on the specification of the Sharp PLC specification.

For details, refer to the Sharp PLC operation manual.

Chapter14 Microcomputer connection

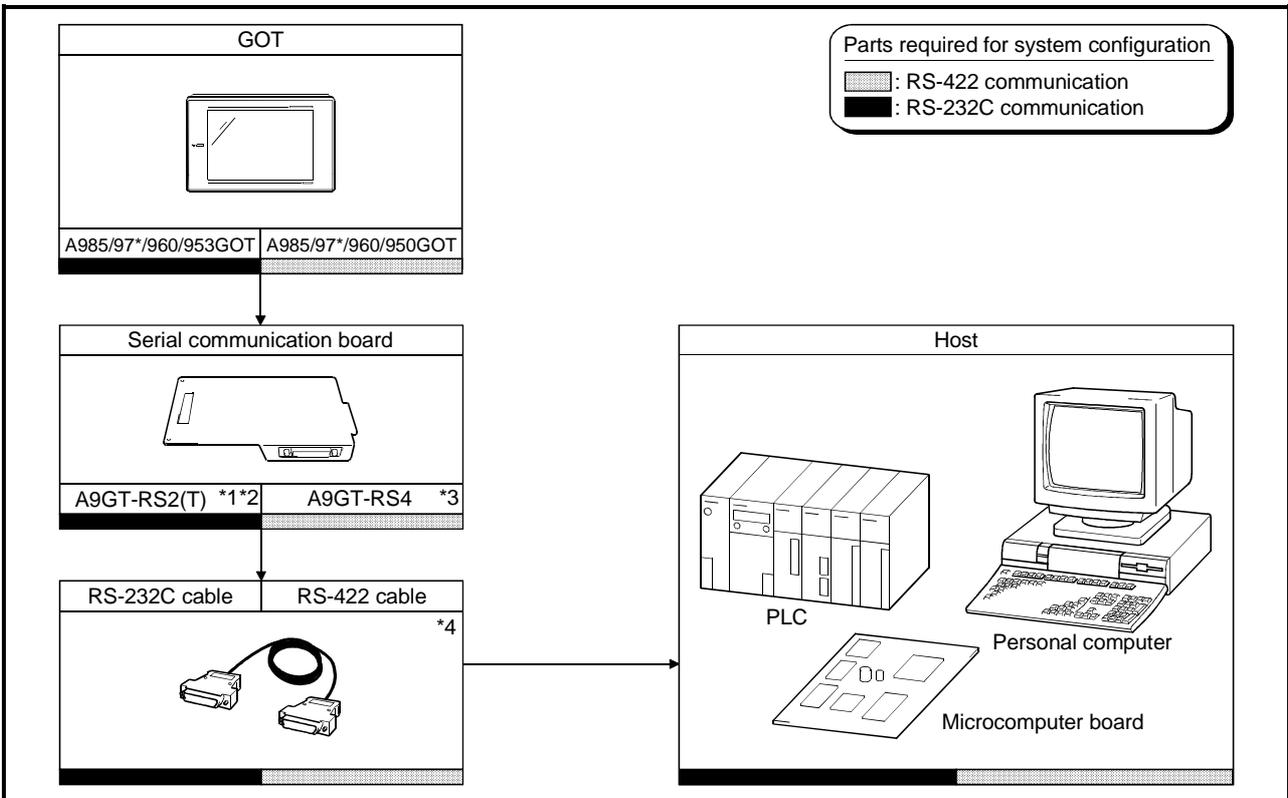
A virtual device of the GOT (D) can be monitored from the personal computer, microcomputer board and PLC (hereinafter referred to as "host") by sending/receiving data.



REMARK

Refer to the system configuration example (which uses the sample program contained in SW4D5C-GOTR-PACKE) given in Appendices.

14.1 System configuration



*1 This is not required when the A953GOT (with built-in serial communication interface) is used.
 *2 The use of A9GT-RS2T, which includes a clock element, enables the use of the time display function of the GOT.
 *3 This is not required when the A950GOT (with built-in serial communication interface) is used.
 *4 Connection cable must be prepared by the user.
 For details of preparation, refer to 14.2.

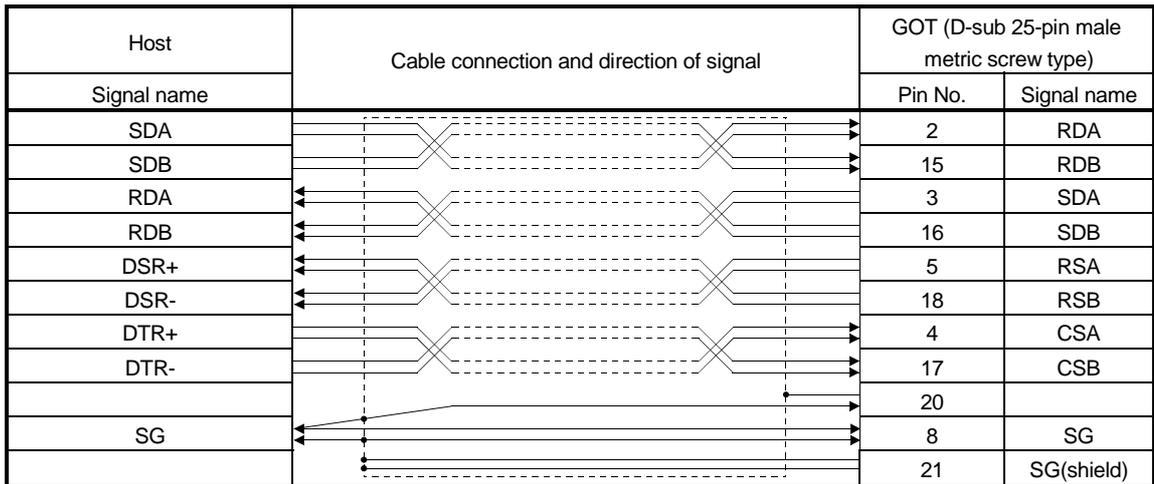
14.2 Connecting cable

14.2.1 With connection to DTR

The cable connection diagram and the connector with connection to DTR signals are described below.

(1) When using RS-422 communication

(a) Connection diagram



DSR signal ... If this signal is OFF, data is not transmitted from the GOT to the host.

Normally, send signals from the host so that the DSR is always ON.

DTR signal ... This signal is turned ON when the GOT is ready to receive data.

(b) Connector and connector cover

• Connector for GOT

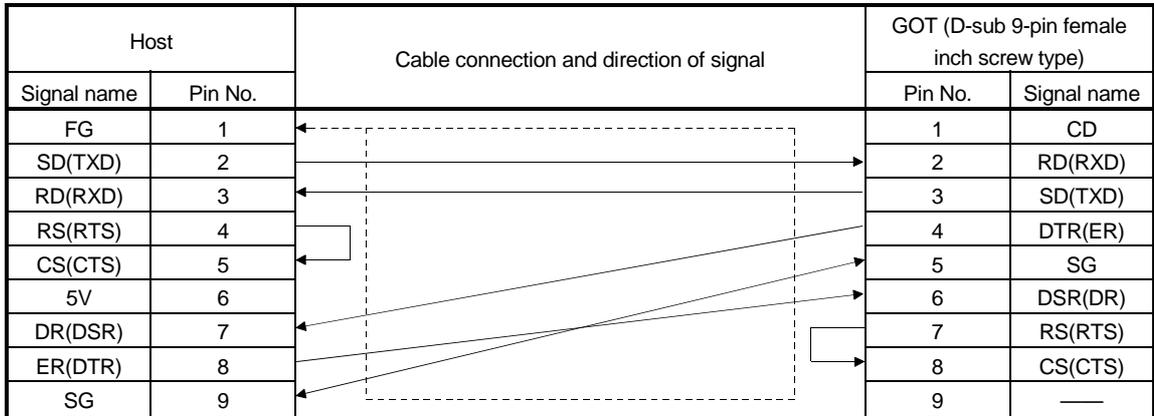
Description	Model	Manufacturer
Connector with cover	17JE-23250-02(D8A6)	DDK

• Connector for host

Use a connector matching the host.

(2) When using RS-232C communication

(a) Connection diagram



Note) The pin numbers for the host in the above diagram are for reference.
Use pin numbers according to the specification of the host.

(b) Connector and connector cover

• Connector for GOT

The following connector is used for the RS-232C interface of A9GT-RS2.
Use connector matching this connector.

9-pin D-sub (male) inch screw type
Manufactured by DDK
17LE-23090-27 (D3CC)

• Connector for host

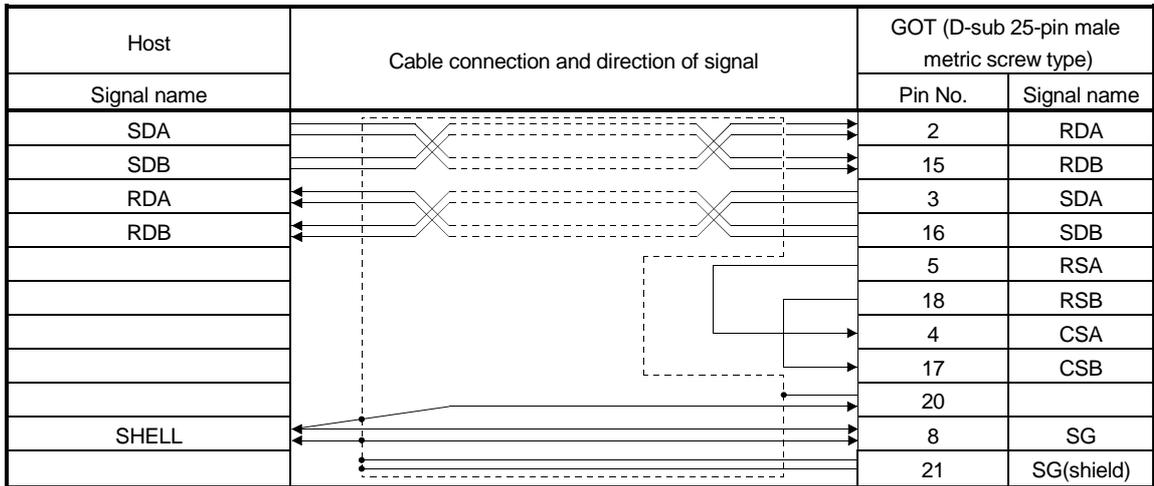
Use connectors matching the host.

14.2.2 Without connection to DTR

The cable connection diagram and the connector without connection to DTR signals are described below.

(1) When using RS-422 communication

(a) Connection diagram



(b) Connector and connector cover

• Connector for GOT

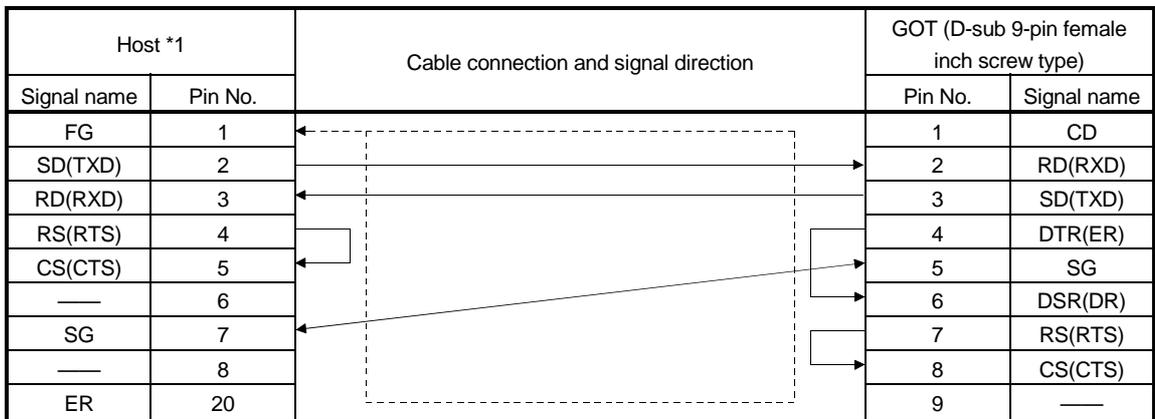
Description	Model	Manufacturer
Connector with cover	17JE-23250-02(D8A6)	DDK

• Connector for host

Use a connector matching the host.

(2) For RS-232C communication

(a) Connection diagram



*1 Pin numbers at the host side are only for reference.
 They are not defined.
 Use the appropriate number according to the host specification.

(b) Connector and connector cover

- Connector for GOT
 RS-232C interface connector of A9GT-RS2 uses the following type.
 Use the connector matching this connector.

 9 pin D-sub (male) inch screw type
 Manufactured by DDK
 17LE-23090-27 (D3CC)
- Connector for host
 Use a connector matching the host.

14.3 Transmission specification

Transmission specification for communication between the GOT and the host is as follows.

Item	Setting details
Data bit	7 bit
Parity bit	Yes (even number)
Stop bit	1 bit
Sum check	Yes
Transmission speed	4800/9600/19200bps (default 19200bps)

14.4 Device data area

The data area, virtual device of the GOT, is shown below.

Address (decimal) *1	Details																																	
D0 to D2	Not used																																	
D3 *2	Communication error status Error varies depending on the error status of the GOT communication driver. <table border="1" style="width: 100%; border-collapse: collapse;"> <thead> <tr> <th style="width: 50%;">Bit</th> <th style="width: 50%;">Not used</th> </tr> </thead> <tbody> <tr> <td>0 to 3</td> <td>Not used</td> </tr> <tr> <td>4</td> <td>SIO framing error</td> </tr> <tr> <td>5</td> <td>SIO parity error</td> </tr> <tr> <td>6</td> <td>SIO overrun error</td> </tr> <tr> <td>7</td> <td>Communication time error</td> </tr> <tr> <td>8</td> <td>Cable removal error</td> </tr> <tr> <td>9 to 15</td> <td>Not used</td> </tr> </tbody> </table>		Bit	Not used	0 to 3	Not used	4	SIO framing error	5	SIO parity error	6	SIO overrun error	7	Communication time error	8	Cable removal error	9 to 15	Not used																
Bit	Not used																																	
0 to 3	Not used																																	
4	SIO framing error																																	
5	SIO parity error																																	
6	SIO overrun error																																	
7	Communication time error																																	
8	Cable removal error																																	
9 to 15	Not used																																	
D4 *2	Clock data (year) <table border="1" style="width: 100%; border-collapse: collapse;"> <thead> <tr> <th colspan="2">Bit</th> </tr> </thead> <tbody> <tr> <td style="width: 50%;">15 to 8</td> <td style="width: 50%;">7 to 0</td> </tr> <tr> <td>Not used</td> <td>Store last 2 digit data of the year in BCD 2 digits.</td> </tr> </tbody> </table>	Bit		15 to 8	7 to 0	Not used	Store last 2 digit data of the year in BCD 2 digits.	Clock data (year, month, day, hour, minute) is stored in BCD 2 digits to each address (0 to 7 bit). (Example) 18:02:30, Thursday, June 10, 1999 <table border="1" style="width: 100%; border-collapse: collapse; margin-top: 10px;"> <thead> <tr> <th rowspan="2">Address</th> <th colspan="2">Bit</th> </tr> <tr> <th>15 to 8</th> <th>7 to 0</th> </tr> </thead> <tbody> <tr><td>D4</td><td>00</td><td>99</td></tr> <tr><td>D5</td><td>00</td><td>06</td></tr> <tr><td>D6</td><td>00</td><td>10</td></tr> <tr><td>D7</td><td>00</td><td>18</td></tr> <tr><td>D8</td><td>00</td><td>02</td></tr> <tr><td>D9</td><td>00</td><td>30</td></tr> <tr><td>D10</td><td>00</td><td>04</td></tr> </tbody> </table>	Address	Bit		15 to 8	7 to 0	D4	00	99	D5	00	06	D6	00	10	D7	00	18	D8	00	02	D9	00	30	D10	00	04
Bit																																		
15 to 8	7 to 0																																	
Not used	Store last 2 digit data of the year in BCD 2 digits.																																	
Address	Bit																																	
	15 to 8	7 to 0																																
D4	00	99																																
D5	00	06																																
D6	00	10																																
D7	00	18																																
D8	00	02																																
D9	00	30																																
D10	00	04																																
D5 *2	Clock data (month) <table border="1" style="width: 100%; border-collapse: collapse;"> <thead> <tr> <th colspan="2">Bit</th> </tr> </thead> <tbody> <tr> <td style="width: 50%;">15 to 8</td> <td style="width: 50%;">7 to 0</td> </tr> <tr> <td>Not used</td> <td>Store month data from 01 to 12 in BCD 2 digits.</td> </tr> </tbody> </table>	Bit		15 to 8	7 to 0	Not used	Store month data from 01 to 12 in BCD 2 digits.																											
Bit																																		
15 to 8	7 to 0																																	
Not used	Store month data from 01 to 12 in BCD 2 digits.																																	
D6 *2	Clock data (day) <table border="1" style="width: 100%; border-collapse: collapse;"> <thead> <tr> <th colspan="2">Bit</th> </tr> </thead> <tbody> <tr> <td style="width: 50%;">15 to 8</td> <td style="width: 50%;">7 to 0</td> </tr> <tr> <td>Not used</td> <td>Store day data from 01 to 31 in BCD 2 digits.</td> </tr> </tbody> </table>	Bit		15 to 8	7 to 0	Not used	Store day data from 01 to 31 in BCD 2 digits.																											
Bit																																		
15 to 8	7 to 0																																	
Not used	Store day data from 01 to 31 in BCD 2 digits.																																	
D7 *2	Clock data (hour) <table border="1" style="width: 100%; border-collapse: collapse;"> <thead> <tr> <th colspan="2">Bit</th> </tr> </thead> <tbody> <tr> <td style="width: 50%;">15 to 8</td> <td style="width: 50%;">7 to 0</td> </tr> <tr> <td>Not used</td> <td>Store hour data from 00 to 23 in BCD 2 digits.</td> </tr> </tbody> </table>	Bit		15 to 8	7 to 0	Not used	Store hour data from 00 to 23 in BCD 2 digits.																											
Bit																																		
15 to 8	7 to 0																																	
Not used	Store hour data from 00 to 23 in BCD 2 digits.																																	
D8 *2	Clock data (minute) <table border="1" style="width: 100%; border-collapse: collapse;"> <thead> <tr> <th colspan="2">Bit</th> </tr> </thead> <tbody> <tr> <td style="width: 50%;">15 to 8</td> <td style="width: 50%;">7 to 0</td> </tr> <tr> <td>Not used</td> <td>Store minute data from 00 to 59 in BCD 2 digits..</td> </tr> </tbody> </table>	Bit		15 to 8	7 to 0	Not used	Store minute data from 00 to 59 in BCD 2 digits..																											
Bit																																		
15 to 8	7 to 0																																	
Not used	Store minute data from 00 to 59 in BCD 2 digits..																																	
D9 *2*3	Clock data (second) <table border="1" style="width: 100%; border-collapse: collapse;"> <thead> <tr> <th colspan="2">Bit</th> </tr> </thead> <tbody> <tr> <td style="width: 50%;">15 to 8</td> <td style="width: 50%;">7 to 0</td> </tr> <tr> <td>Not used</td> <td>Store second data from 00 to 59 in BCD 2 digits..</td> </tr> </tbody> </table>	Bit		15 to 8	7 to 0	Not used	Store second data from 00 to 59 in BCD 2 digits..																											
Bit																																		
15 to 8	7 to 0																																	
Not used	Store second data from 00 to 59 in BCD 2 digits..																																	
D10 *2*3	Clock data (day of week) <table border="1" style="width: 100%; border-collapse: collapse;"> <thead> <tr> <th colspan="2">Bit</th> </tr> </thead> <tbody> <tr> <td style="width: 50%;">15 to 8</td> <td style="width: 50%;">7 to 0</td> </tr> <tr> <td>Not used</td> <td>Store day-of-week data from 00 to 06 in BCD 2 digits..</td> </tr> </tbody> </table> Day-of-week data 00: Sunday 03: Wednesday 06: Saturday 01: Monday 04: Thursday 02: Tuesday 05: Friday	Bit		15 to 8	7 to 0	Not used	Store day-of-week data from 00 to 06 in BCD 2 digits..																											
Bit																																		
15 to 8	7 to 0																																	
Not used	Store day-of-week data from 00 to 06 in BCD 2 digits..																																	

Address (decimal) *1	Details
D11 to D12	Not used
D13	Interrupt output Write data and lower level 8 bit details are output as interrupt code.
D14 to D19	Not used
D20 to D2031	User area
D2032 to D2034	Not used
D2035	1 second binary counter Counting increases every second after the power is turned on. The data is binary.
D2036 to D2047	Not used

*1 "D****" indicated in this chapter indicates a virtual device of the GOT and is not the data register of the PLC.

*2 It can be used only when the A9GT-RS2T with built-in clock element is connected.

*3 SW4D5C-GOTR-PACK version C or later is compatible with (second) and (day of week) of the clock data.

14.5 Communication commands

This section describes commands for communication.

14.5.1 Command list

Commands used for data transmission between the GOT and the host are shown below.

Command	Command name	Details
RD	Batch read command	Designated amount of data is continuously read from the designated device.
WD	Batch write command	Designated amount of data is continuously written into the designated device.
RR	Random read	Data is read from multiple different device addresses.
RW	Random write	Data is written into multiple different device addresses.

14.5.2 Data communication type

2 types of data communication are available in using commands.

Each data communication type is explained below.

Data communication type is switched with the utility function of the GOT.

Refer to GOT-A900 series Operating Manual (SW4D5C-GOTR-PACKE compatible Extended • Option Functions Manual) for details of the utility function.

Protocol for selection		Type 1	Type 2					
Data communication type (host→GOT)		<div style="border: 1px solid black; padding: 5px; display: inline-block;"> <table border="1" style="border-collapse: collapse;"> <tr> <td style="text-align: center;">STX (02H)</td> <td style="text-align: center;">Command</td> <td style="text-align: center;">Data (64 points max.)</td> <td style="text-align: center;">ETX (03H)</td> <td style="text-align: center;">Sum check</td> </tr> </table> </div> <p style="text-align: center;">Sum check range</p>	STX (02H)	Command	Data (64 points max.)	ETX (03H)	Sum check	
STX (02H)	Command	Data (64 points max.)	ETX (03H)	Sum check				
Response data type in normal operation (GOT→host)	Read command in (RD, RR) transmission	<div style="border: 1px solid black; padding: 5px; display: inline-block;"> <table border="1" style="border-collapse: collapse;"> <tr> <td style="text-align: center;">STX (02H)</td> <td style="text-align: center;">Data (64 points max.)</td> <td style="text-align: center;">ETX (03H)</td> <td style="text-align: center;">Sum check</td> </tr> </table> </div> <p style="text-align: center;">Sum check range</p>	STX (02H)	Data (64 points max.)	ETX (03H)	Sum check		
	STX (02H)	Data (64 points max.)	ETX (03H)	Sum check				
Write command in (WD, RW) transmission	<div style="border: 1px solid black; padding: 5px; display: inline-block;"> ACK (06H) </div>							
Response data type in error (GOT→host)		<div style="border: 1px solid black; padding: 5px; display: inline-block;"> NAK (15H) </div>	<div style="border: 1px solid black; padding: 5px; display: inline-block;"> <table border="1" style="border-collapse: collapse;"> <tr> <td style="text-align: center;">NAK (15H)</td> <td style="text-align: center;">*1 Error code</td> </tr> </table> </div>	NAK (15H)	*1 Error code			
NAK (15H)	*1 Error code							
Interrupt output type (GOT→host)		<div style="border: 1px solid black; padding: 5px; display: inline-block;"> Interrupt output data </div>	<div style="border: 1px solid black; padding: 5px; display: inline-block;"> <table border="1" style="border-collapse: collapse;"> <tr> <td style="text-align: center;">STX (02H)</td> <td style="text-align: center;">Interrupt output data</td> <td style="text-align: center;">ETX (03H)</td> <td style="text-align: center;">Sum check</td> </tr> </table> <p style="text-align: center;">Sum check range</p> </div>	STX (02H)	Interrupt output data	ETX (03H)	Sum check	
STX (02H)	Interrupt output data	ETX (03H)	Sum check					

*1 When type 2 is used, the error code is stored for interrupt output.

Each error code is shown below in detail.

Error code	Error details	Action
06H	Sum check error An error has occurred at the sum check after receipt of communication packet.	Check the communication line and the transmission packet.
10H	Command error Request command which is not supported was used.	Check the request command data which was transmitted.
11H	Data length error The data volume exceeded the upper limit of the reception buffer.	Check if the total number of bytes in the transmission data packet is within 518 bytes.

Error code	Error details	Action
7BH	Point excess error The allowance of read/write device was exceeded.	Check the range of the designated device
7AH	Address error Top address of read/write device is not within the range.	Check the top address of the designated device.
12H	Communication data error When the communication data is received, this error occurs if EXT is not found before the upper limit of the reception buffer is exceeded.	Check the communication data.

14.5.3 Precautions for use

The sum check code is the last 1 byte (8bit) value of the result (sum) from addition of binary data in the range of the sum check.

(Example) Reading RD command with D100 to D101

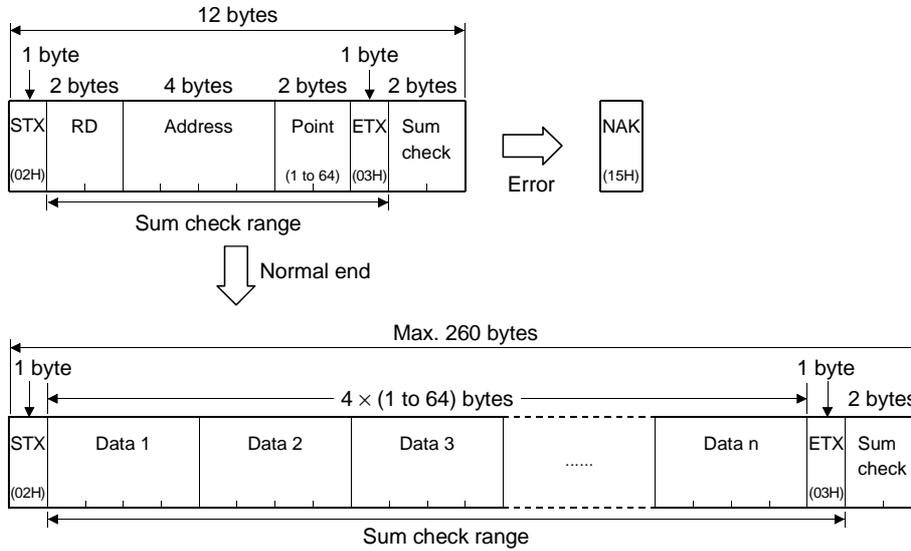
STX	R	D	Address				Point		ETX	Sum check	
			0	1	0	0	0	2		B	C
02H	52H	44H	30H	31H	30H	30H	30H	32H	03H	42H	43H

Sum check range

Formula: $52H+44H+30H+31H+30H+30H+30H+32H+03H=1\underline{B}C\underline{H}$

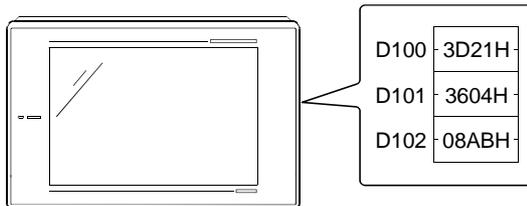
14.5.4 Batch read command (RD)

Batch read command details are shown below.



Example of use

When D100 to D102 are read from the GOT virtual device



STX	R	D	Address				Point	ETX	Sum check
(02H)			0	1	0	0	0	3	B D
			H	MH	ML	L	H	L	(03H) H L

Transmission from host to GOT

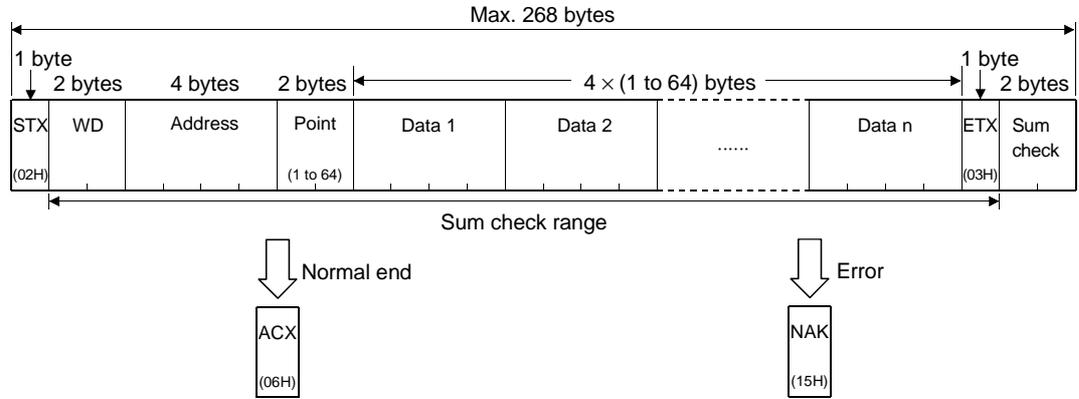


STX	D100				D101				D102				ETX	Sum check
	3	D	2	1	3	6	0	4	0	8	A	B		9 5
(02H)	H	MH	ML	L	H	MH	ML	L	H	MH	ML	L	(03H)	H L

Transmission from GOT to host

14.5.5 Batch write command (WD)

Batch write command details are shown below.

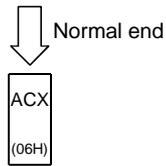


Example of use

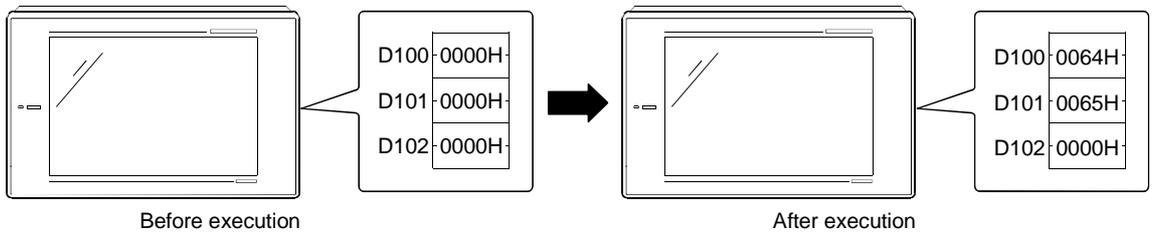
When 64H and 65H are written in D100 to D101 of the GOT virtual device

STX	W	D	Address				Point				D100				D101				ETX	Sum check		
(02H)			H	MH	ML	L	H	L	H	ML	L	H	MH	ML	L	H	ML	L	(03H)	H	L	
			0	1	0	0	0	2	0	0	6	4	0	0	6	5			5	6		

Transmission from host to GOT

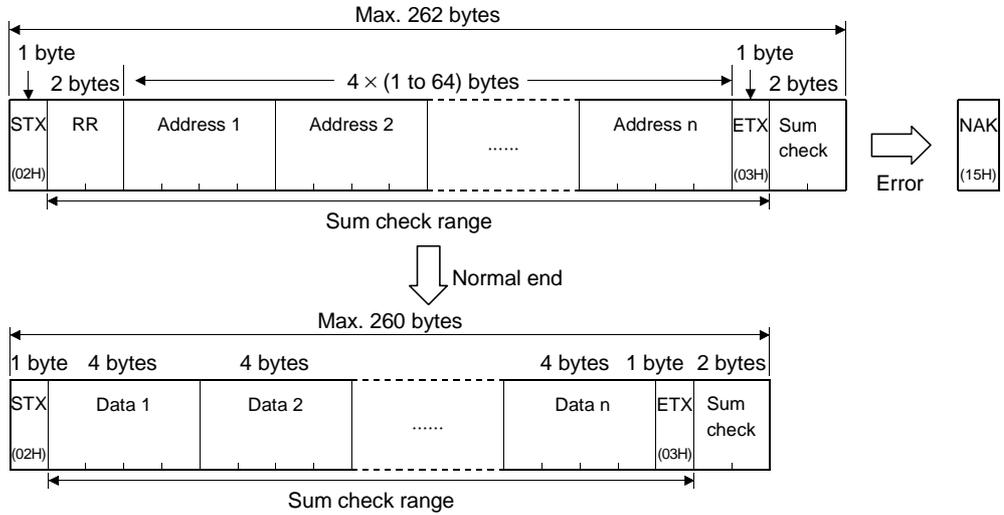


Transmission from GOT to host



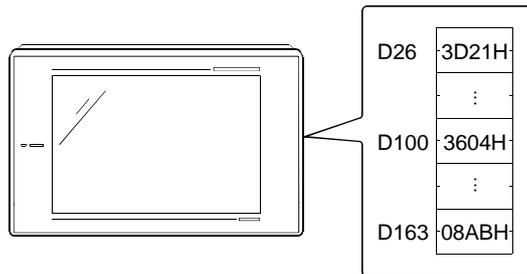
14.5.6 Random read command (RR)

Random read command details are shown below.



Example of use

When D100, D26 and D163 are read from the GOT virtual device



STX	R	R	D100				D26				D163				ETX	Sum check
(02H)			0	1	0	0	0	0	2	6	0	1	6	3	(03H)	F A
			H	MH	ML	L	H	MH	ML	L	H	MH	ML	L	H	L

Transmission from host to GOT

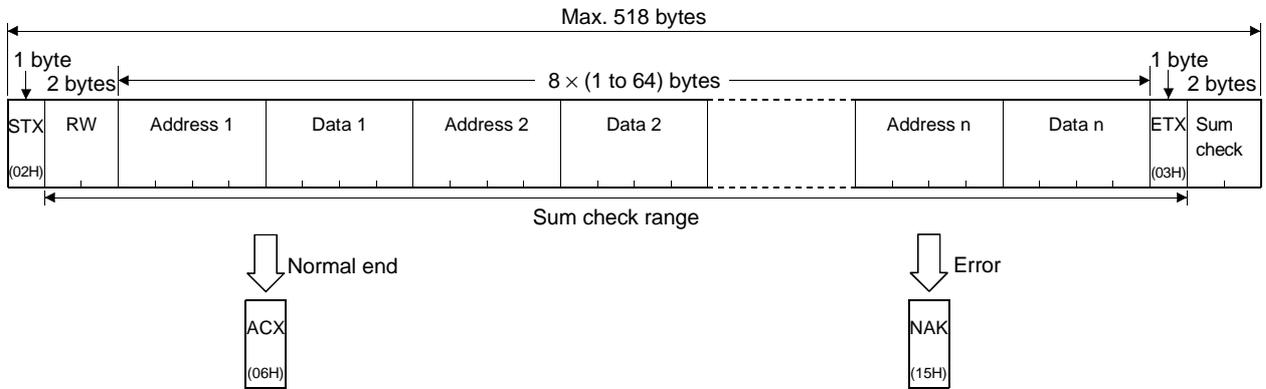
Normal end

STX	Details of D100				Details of D26				Details of D163				ETX	Sum check
(02H)	3	6	0	4	3	D	2	1	0	8	A	B	(03H)	9 9
	H	L	H	L	H	L	H	L	H	L	H	L	H	L

Transmission from GOT to host

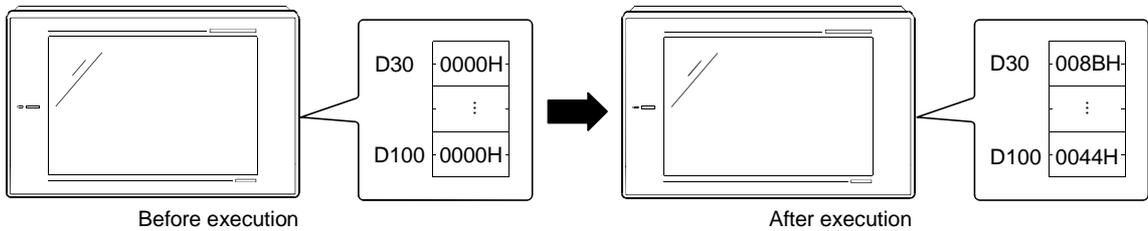
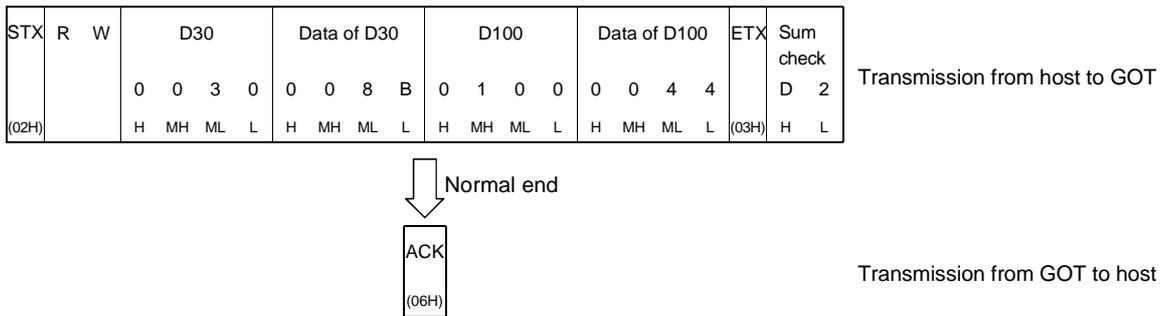
14.5.7 Random write command (RW)

Random write command details are shown below.



Example of use

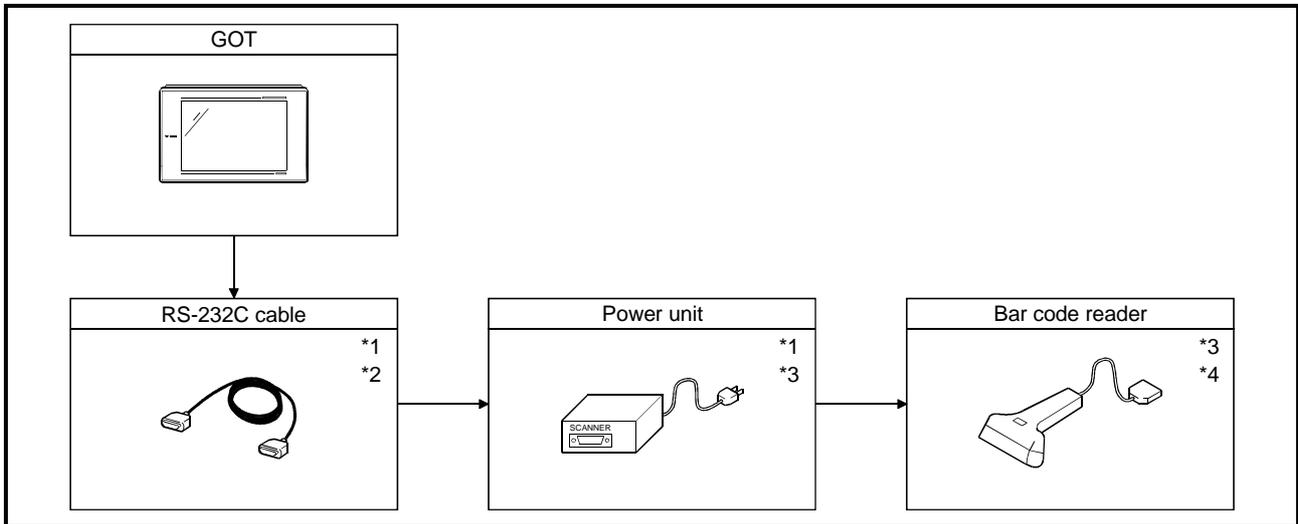
When 8BH is written into D30 and 44H is written into D100 of the GOT virtual device



Chapter15 Option devices connection

15.1 Bar code reader

15.1.1 System configuration



*1 Not needed depending on the bar code reader used.

*2 The user must prepare the RS-232C cable.

For details of preparation, refer to 15.1.3.

*3 The bar code reader requires power (DC5V) from the AC-DC adapter and the corresponding power unit.

*4 Refer to Section 15.1.4 for the bar code reader connectable with the GOT.

*5 The bar code reader is usable independently of the connection form of the GOT.

15.1.2 Communication setting of bar code reader

For connection to the GOT, set the following communication parameters and the port at the side of the bar code reader.

Refer to the bar code reader operation manual for details.

Setting items	Communication specification					
	Token bar code reader	Optoelectronics bar code reader	Keyence bar code reader	Imex bar code reader	OLYMPUS - symbol bar code reader	OMRON bar code reader
Interface	RS-232C					RS-232C
Transmission method		Asynchronous type		Dumb-terminal procedure CR ^{*1}		
Start bit		1				
Stop bit	1	1	1	1	1 ^{*1}	1 ^{*1}
Data bit length (word length)	8	8	8 ^{*1}	8	8 ^{*1}	8 ^{*1}
Parity bit	Even number	Yes, even number ^{*1}	Yes, even number	Yes, even number ^{*1}	EVEN	Even number
Parity check					No	
Hardware handshake					No	
Software handshake					No	
Communication control method		BUSY/READY (RS/CS)	RTS/CTS ^{*1}	BUSY/READY (RS/CS)		
Baud rate	9600			9600 ^{*1}	9600	
Prefix (header)	No					No ^{*1}
Suffix (terminator)	CR				CR ^{*1}	

*1 It is necessary to change the initial setting (default) of the bar code reader.

15.1.3 Connection cable

Cable connection diagram and connectors between the GOT and the power unit are shown below.

(Maximum cable length: Obtain the length from the manufacturer of the bar code reader.)

(1) Token's bar code reader

1) Connection diagram

Token's power unit		Cable connection and signal direction	GOT	
Signal name	Pin No.		Pin No.	Signal name
FG	1		—	—
SD(TXD)	2		2	RXD
RD(RXD)	3		3	TXD
RS(RTS)	4		4	DTR
CS(CTS)	5		5	SG
—	6		6	DSR
SG	7		7	RTS
—	—		8	CTS
DC+5V	16		—	—

2) Connectors to be used

- Connector at the GOT
Use a screw (inch screw) type connector at the GOT.
- Connector at the Token's bar code reader
Use the connector applicable to the Token's power unit.

(2) Keyence's bar code reader (BL-500 Series)

1) Connection diagram

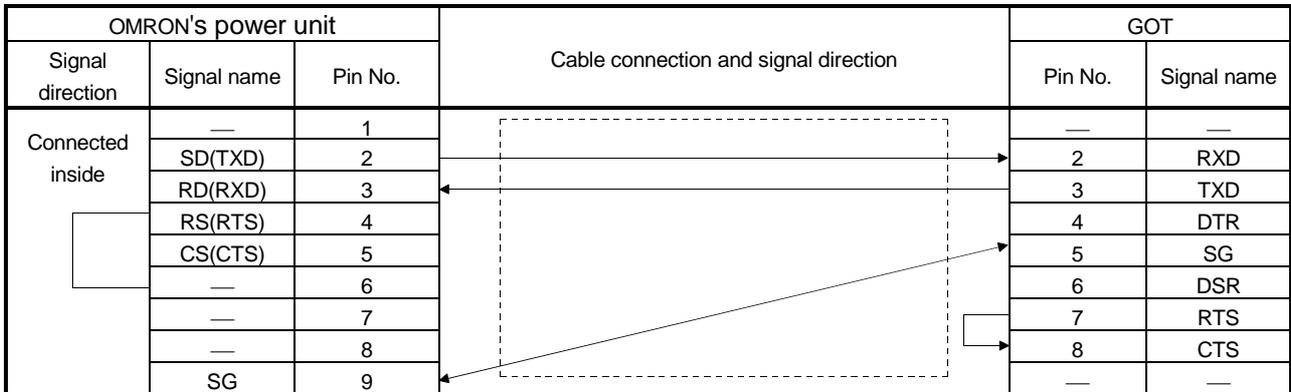
Keyence's power unit			Cable connection and signal direction	GOT	
Signal direction	Signal name	Pin No.		Pin No.	Signal name
Connected inside	SG	1		—	—
	RD(RXD)	2		2	RXD
	SD(TXD)	3		3	TXD
	ER(DTR)	4		4	DTR
	SG	5		5	SG
	DR(DSR)	6		6	DSR
	RS(RTS)	7		7	RTS
	CS(CTS)	8		8	CTS
	—	—		—	—

2) Connectors to be used

- Connector at the GOT
Use a screw (inch screw) type connector at the GOT.
- Connector at the Keyence's bar code reader
Use the connector applicable to the Keyence's power unit.

(3) OMRON's bar code reader (V520-R221F)

1) Connection diagram



2) Connectors to be used

- Connector at the GOT
Use a screw (inch screw) type connector at the GOT.
- Connector at the OMRON's bar code reader
Use the connector applicable to the Keyence's power unit.

15.1.4 Recommended parts for customers and ordering method

(1) Model

Manufacturer	Model	Remark
Token	TCD-6100RMG	Bar code reader
	TPU-6100RMG	Power unit
Optoelectronics	OPT-5125-RS232C(H)	Bar code reader
Keyence	BL-80R	Bar code reader
	BL-100R	
	BL-500 series	
	BL-U2	Power unit
Imex	BR-530RS	Bar code reader
	BB-60-1	Power unit
OLYMPUS - symbol	LSH3502	Bar code reader
	C31-31201-01J2	Connection cable
OMRON	V520-R221F	Bar code reader
	V509-W016	Connection cable
	S82S-0305	Power unit

(2) Order and inquiry

Orders and inquiries for the bar code reader and the power unit should be made to your shop.

15.1.5 GOT setting method

When using a bar code reader on the GOT, it is necessary to make the following setting in the drawing software.

(1) Setting storage device

Set the device (write device, device point) to store the data from the bar code reader with the bar code setting.

Refer to the help function of the drawing software for setting details.

(2) Setting system information

System information is the function to check the GOT status with the PLC CPU.

Refer to the help function of the drawing software for setting details.

POINTS
<p>If the bar code setting is made under the following conditions, the data from the bar code reader is not written.</p> <ul style="list-style-type: none"> • System information is not set. • System signal 1 • b5 (bar code input invalid) is ON. • System signal 1 • b6 (bar code input read complete) remains ON. • System signal 2 • b6 (bar code input) is ON.

15.1.6 Bar code types that can be read with GOT

The bar code specification (data transmission format) supported by the GOT is the following item only:

Data	CR
------	----

Header	End code
No	CR(0DH)

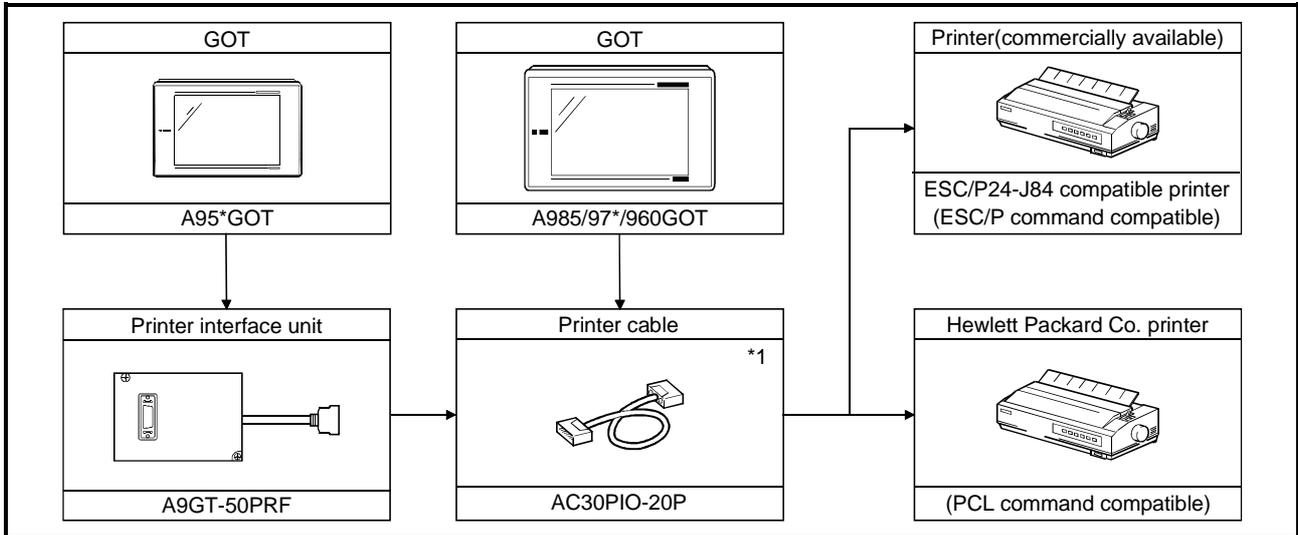
Types of bar codes checked for operation by Mitsubishi are as follows : (○ : operation checked)

Bar code types	Token's bar code reader	Optoelectronics's bar code reader	Keyence's bar code reader	Imex's bar code reader	OLYMPUS-symbol's bar code reader	OMRON's bar code reader
WPC (JAN/EAN/UPC)	○	○	○	○	○	○
CODE-39	○ ^{*1}	○	○	○	○	○
CODE-93	○			○	○	○
CODE-128	○		○	○	○	○
NW-7	○	○		○	○	○
2of5 (Industrial)	○	○	○	○	○	○
ITF				○	○	○

*1 Full ASCII is not supported.

15.2 Printer

15.2.1 System configuration



*1 A printer cable can be prepared by the user.
Refer to 15.2.2 for details of preparation.

15.2.2 Connection cable

Connection diagram and connectors of the printer cable between the GOT and the printer are shown below.

(1) Connection diagram

Printer side		Cable connection and signal direction	GOT side	
Signal name	Pin No.		Pin No.	Signal name
CHASIS GND	17		1	CHASIS GND
ACKNLG	10		2	ACKNLG
DATA6	7		3	DATA6
DATA5	6		4	DATA5
DATA4	5		5	DATA4
NC	36		6	NC
INIT	31		7	INIT
DATA1	2		8	DATA1
STROBE	1		9	STROBE
BUSY	11		10	BUSY
DATA8	9		11	DATA8
DATA7	8		12	DATA7
PE	12		13	PE
SLCT	13		14	SLCT
GND	22		15	GND
DATA3	4		16	DATA3
DATA2	3		17	DATA2
GND	24		18	GND
ERROR	32		19	ERROR
GND	19		20	GND

(2) Connector to be used

- GOT connector

Name	Model	Manufacturer
Connector cover	10320-3210-000	Sumitomo 3M Ltd.
Connector	10120-6000EL	

- Printer connector

Use the connector applicable to the printer to be used.

(3) Precautions for cable preparation

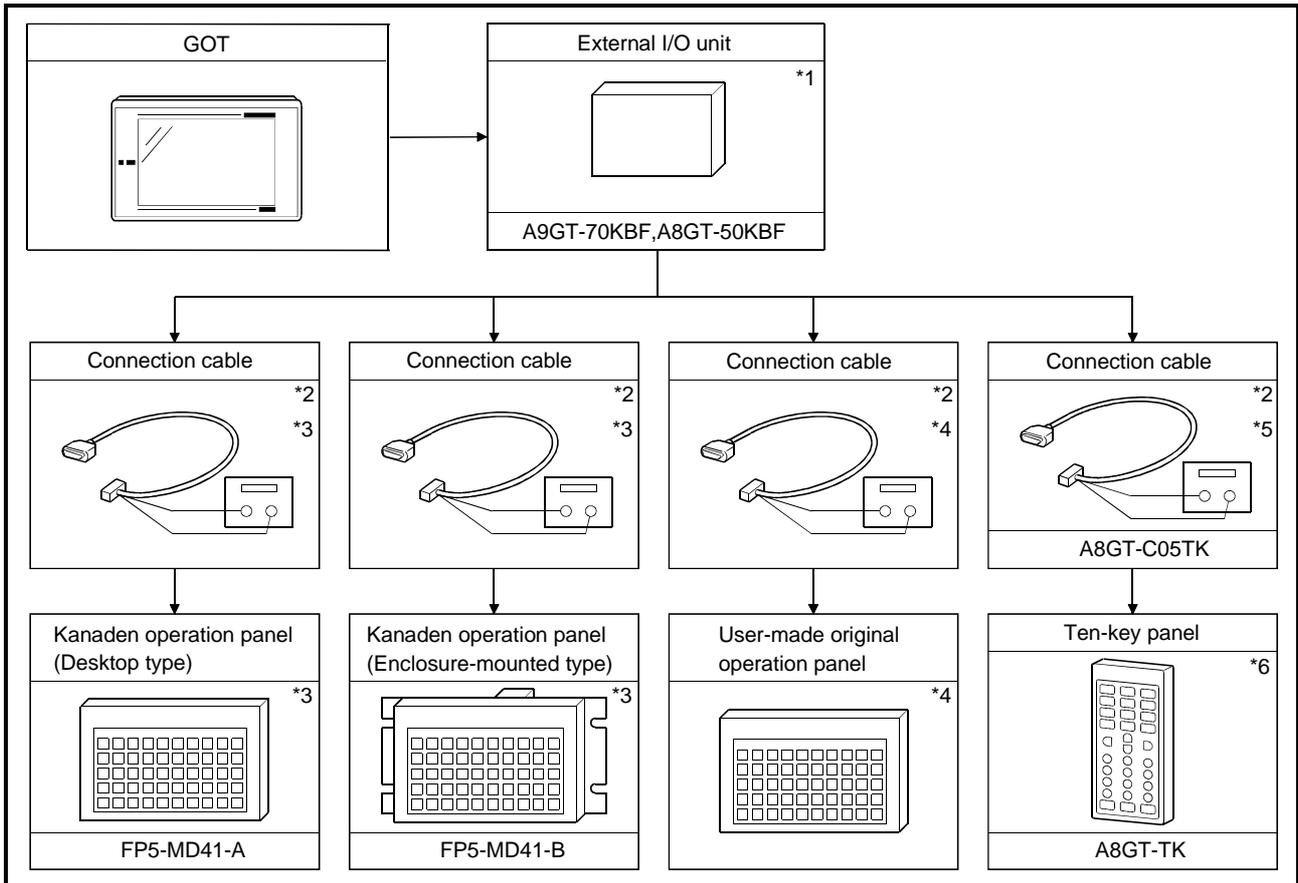
Prepare the cable of a length within 3 m (9.84 feet) or the within the specification range of the printer to be used.

15.3 External I/O equipment

15.3.1 System configuration

The system configuration differs between when the external I/O unit is used for inputs only and when it is used for inputs and outputs.

(1) Inputs only



*1 Select the external I/O unit for the GOT to be used as follows:

When the A985/97*/960GOT is used : A9GT-70KBF

When the A95*GOT is used : A8GT-50KBF

*2 The connection cable must be supplied with 12/24VDC power for the external I/O unit.

Also, the cable used should be within 20m long.

*3 Purchase the Kanaden operation panel and connection cable from Kanaden Corp.

For details of contact, refer to Section 15.3.4.

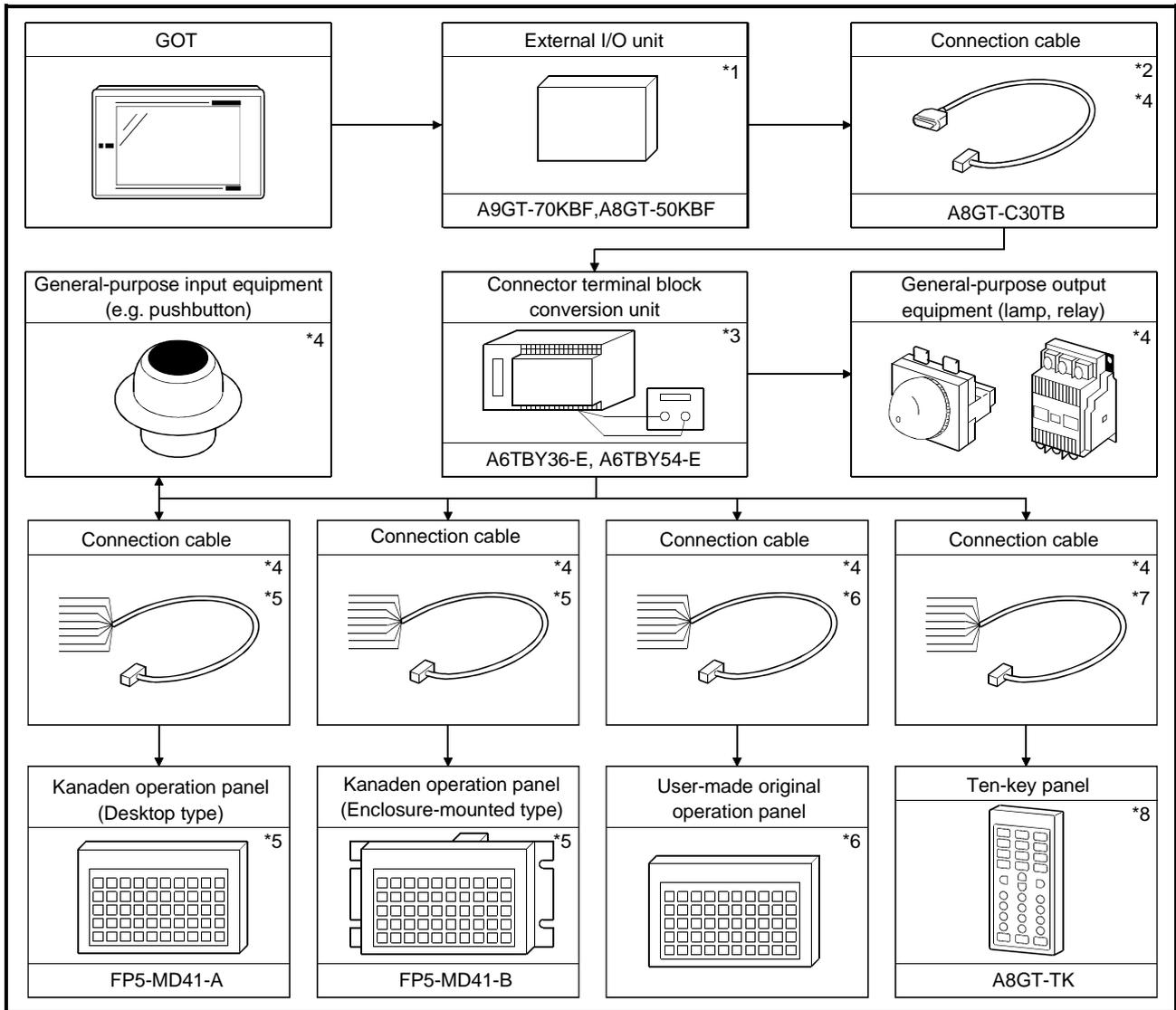
*4 Fabricate the connection cable and user-made original operation panel by referring to Section 15.3.2.

*5 The connection cable may also be fabricated by the user.

For full information on fabrication, refer to the A8GT-TK Type Ten-key Panel User's Manual.

*6 For details of the ten-key panel specifications, refer to the A8GT-TK Type Ten-key Panel User's Manual.

(2) Inputs/outputs



*1 Select the external I/O unit for the GOT to be used as follows:

When the A985/97*/960GOT is used : A9GT-70KBF

When the A95*GOT is used : A8GT-50KBF

*2 The connection cable may also be fabricated by the user.

For full information on fabrication, refer to Section 15.3.2.

*3 The connector terminal block conversion unit must be supplied with 12/24VDC power for the external I/O unit.

*4 The cable used should be within 10m long.

*5 Purchase the Kanaden operation panel and connection cable from Kanaden Corp. For details of contact, refer to Section 15.3.4.

*6 Fabricate the connection cable and user-made original operation panel by referring to the wiring diagram in Section 15.3.3.

*7 The connection cable may also be fabricated by the user.

For full information on fabrication, refer to the A8GT-TK Type Ten-key Panel User's Manual.

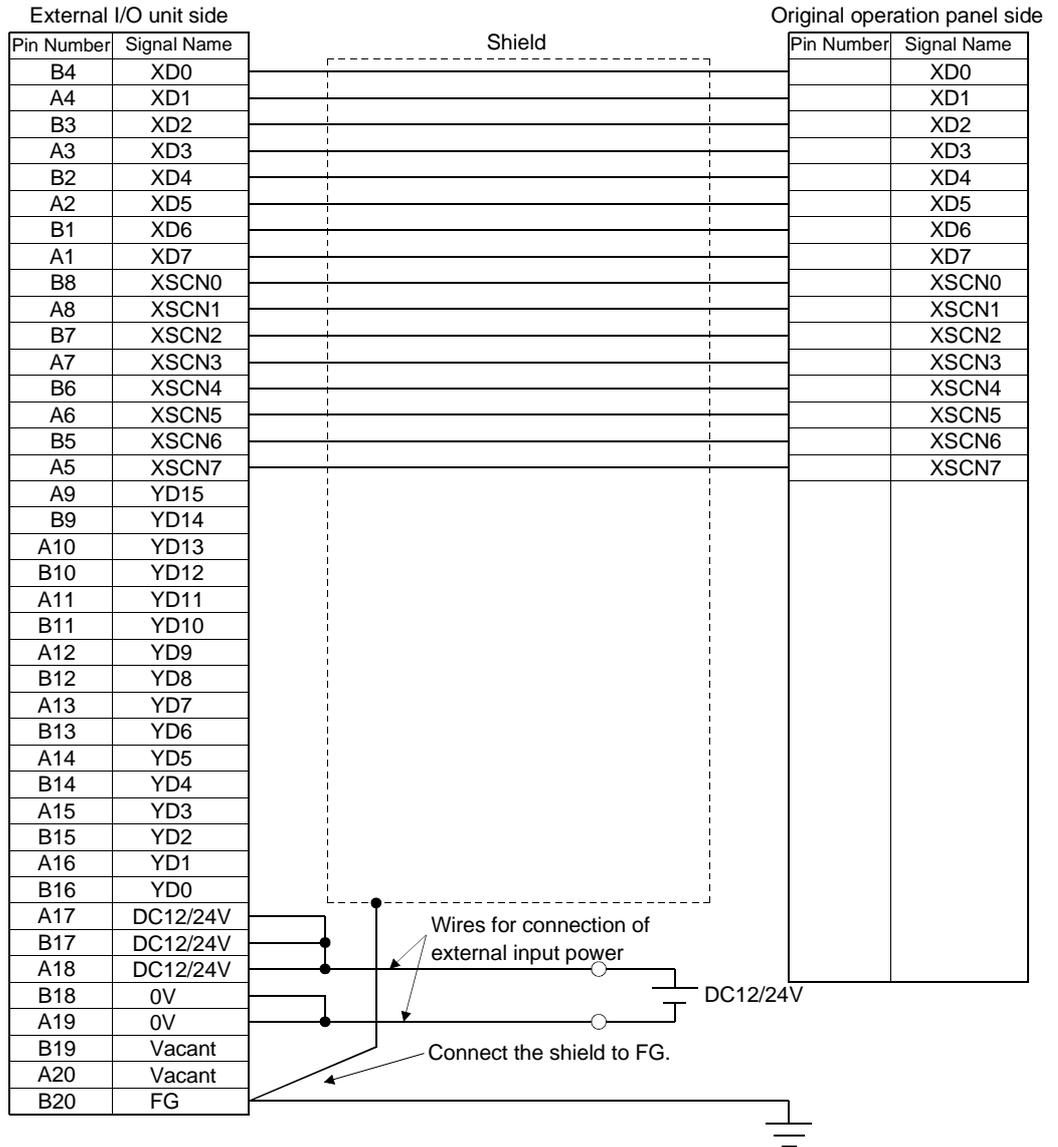
*8 For details of the ten-key panel specifications, refer to the A8GT-TK Type Ten-key Panel User's Manual.

15.3.2 Connection cables

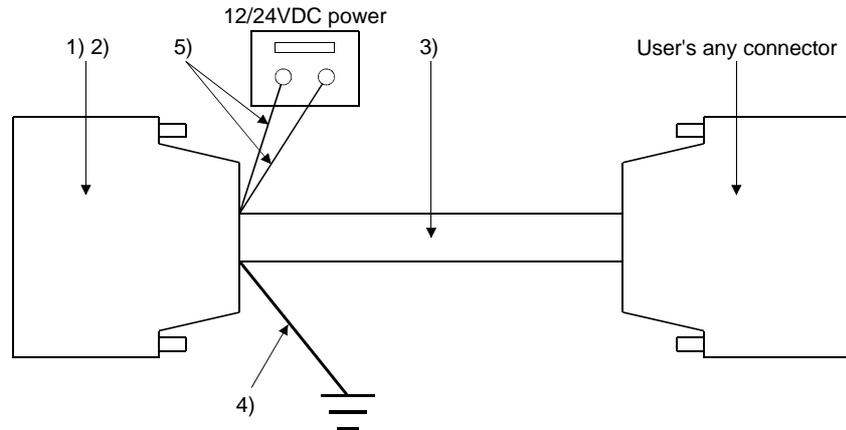
(1) Connection cable for use between external I/O unit and user-made original operation panel

Fabricate the connection cable for use between the external I/O unit and user-made original operation panel on the user side by referring to the following.

(a) Connection diagram



(b) Connector and connector cover used



Number	Name	Type	Maker
1) 2)	Connector (with cover)	A6CON1	Mitsubishi Electric
1)	Connector	FCN-361JO40-AU	Fujitsu
2)	Connector cover	FCN-360CO40-B	
3)	Pair shielded cable	UL 2464 AWG26 or equivalent	-----
4)	FG wire	UL 1015 AWG14 or equivalent	
5)	Wires for connection of external input power	UL 1007 AWG24 or equivalent	

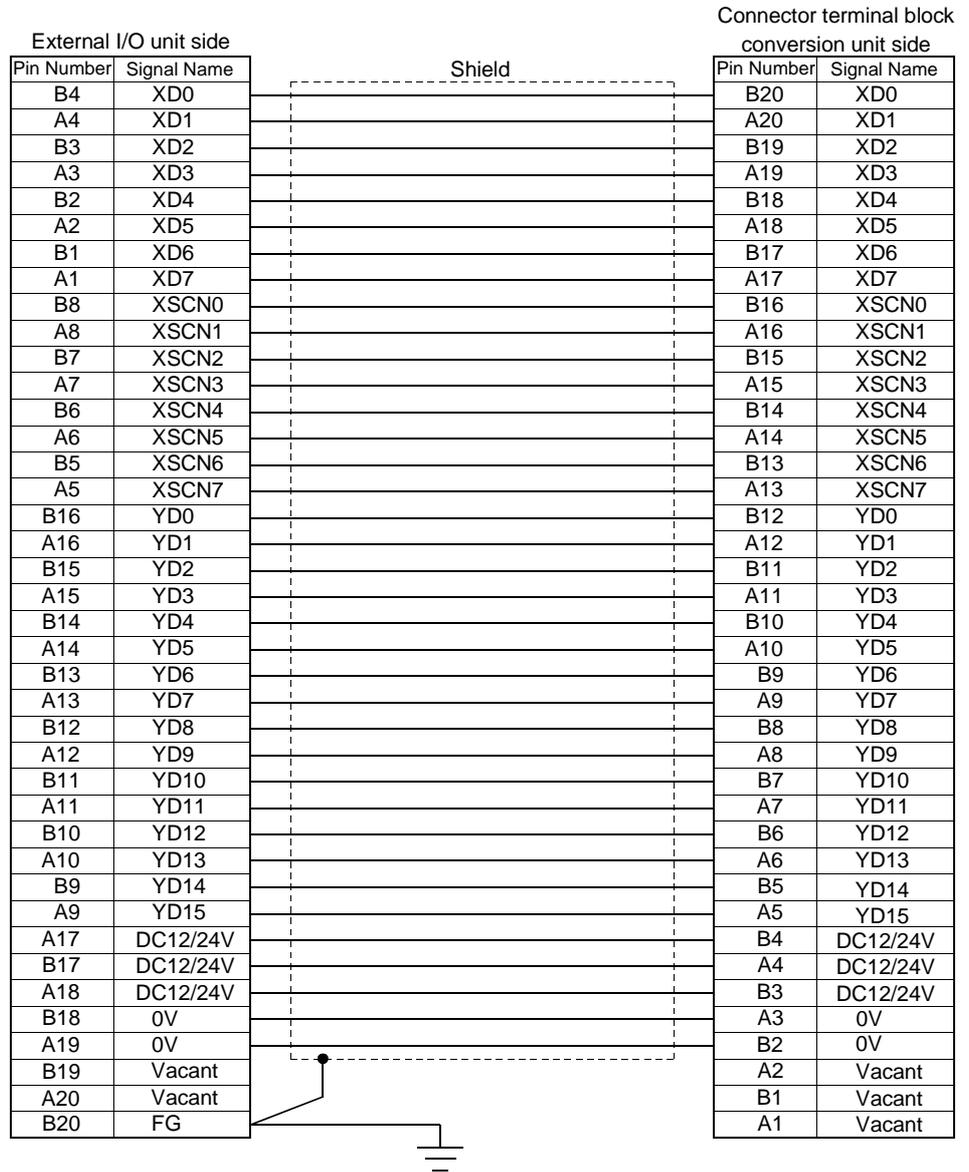
(c) Precaution for cable fabrication

The cable fabricated should be within 20m long.

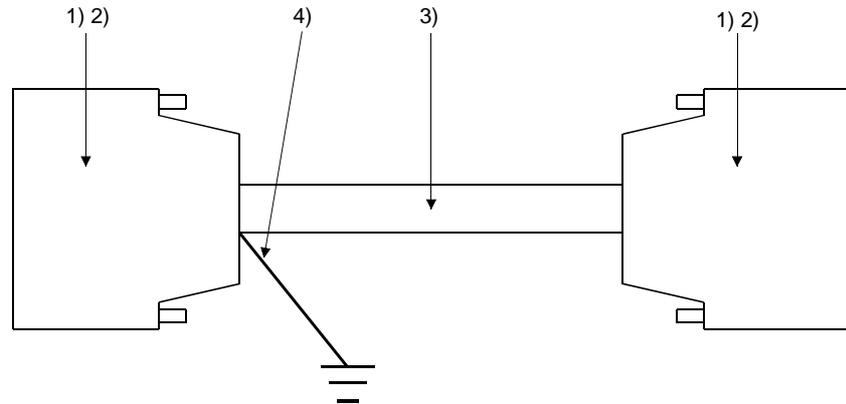
(2) Connection cable for use between external I/O unit and connector terminal block conversion unit

Instead of using the dedicated cable (A8GT-C30TB), the user can fabricate the connection cable for use between the external I/O unit and connector terminal block conversion unit. When fabricating the connection cable, refer to the following.

(a) Connection diagram



(b) Connectors and connector covers used



Number	Name	Type	Maker
1) 2)	Connector (with cover)	A6CON1	Mitsubishi Electric
1)	Connector	FCN-361JO40-AU	Fujitsu
2)	Connector cover	FCN-360CO40-B	
3)	Pair shielded cable	UL 2464 AWG26 or equivalent	———
4)	FG wire	UL 1015 AWG14 or equivalent	

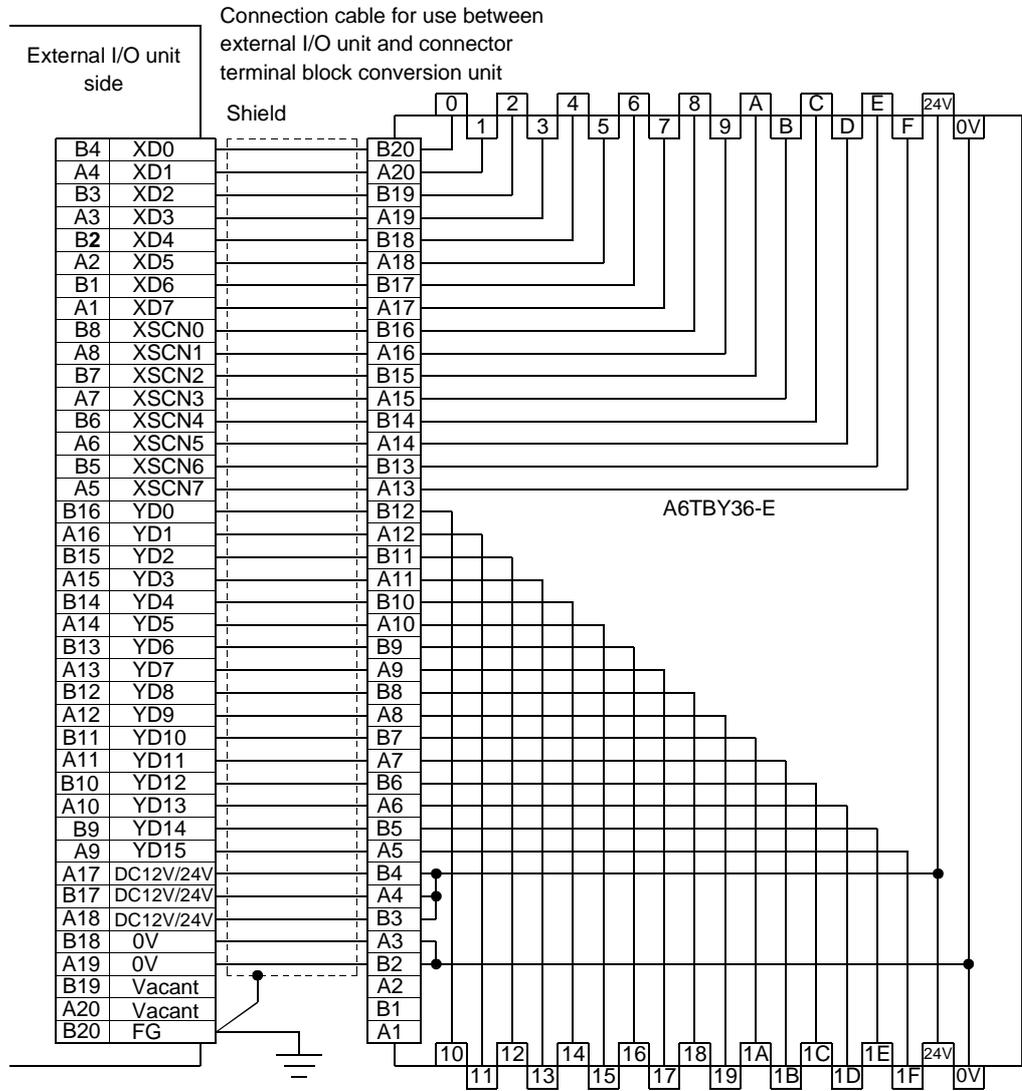
(c) Precaution for cable fabrication

The cable fabricated should be within 10m long.

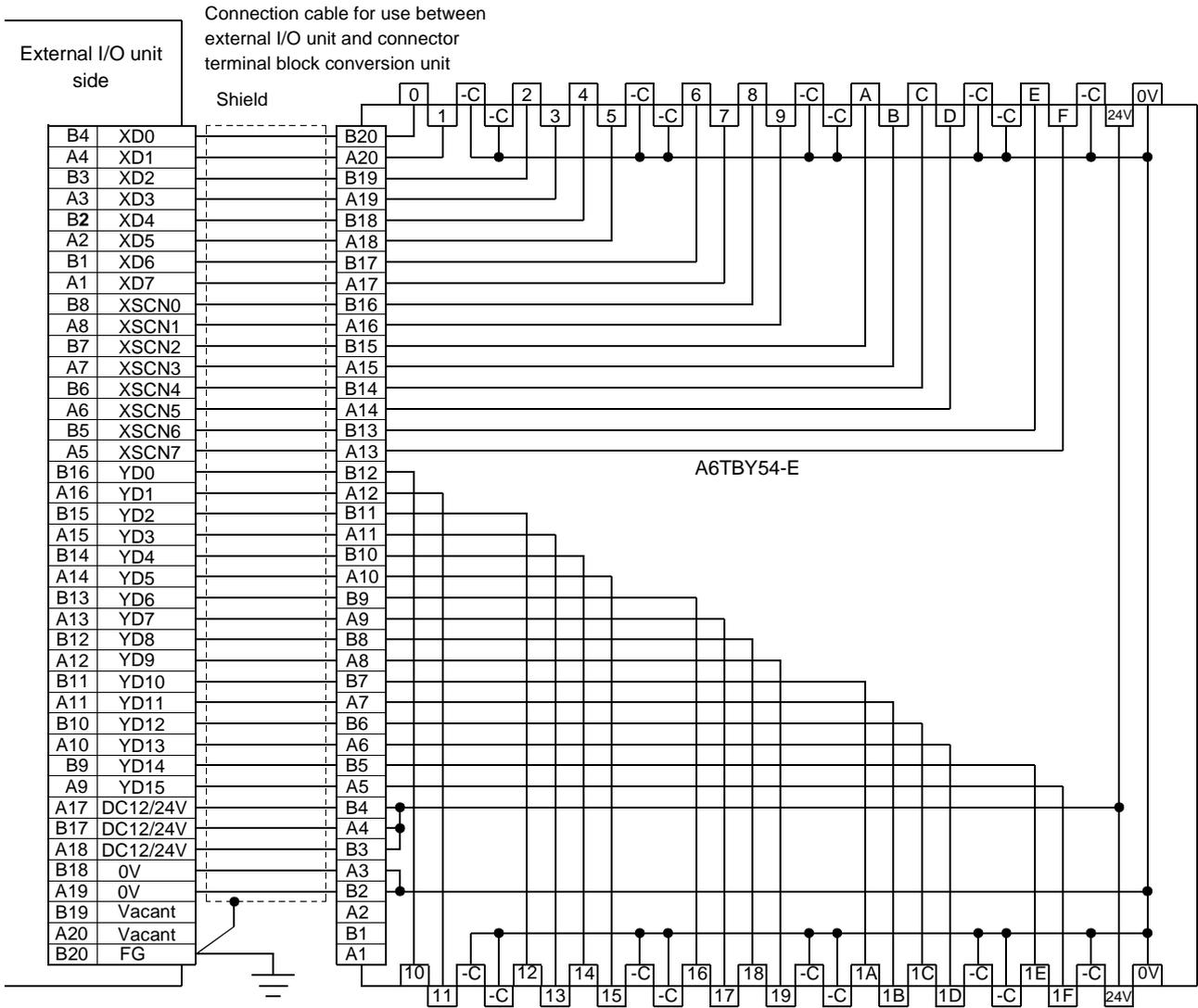
15.3.3 Wiring diagrams

(1) Wiring diagram for use between external I/O unit and connector terminal block conversion unit

(a) For use of A6TBY36-E type connector terminal block conversion unit

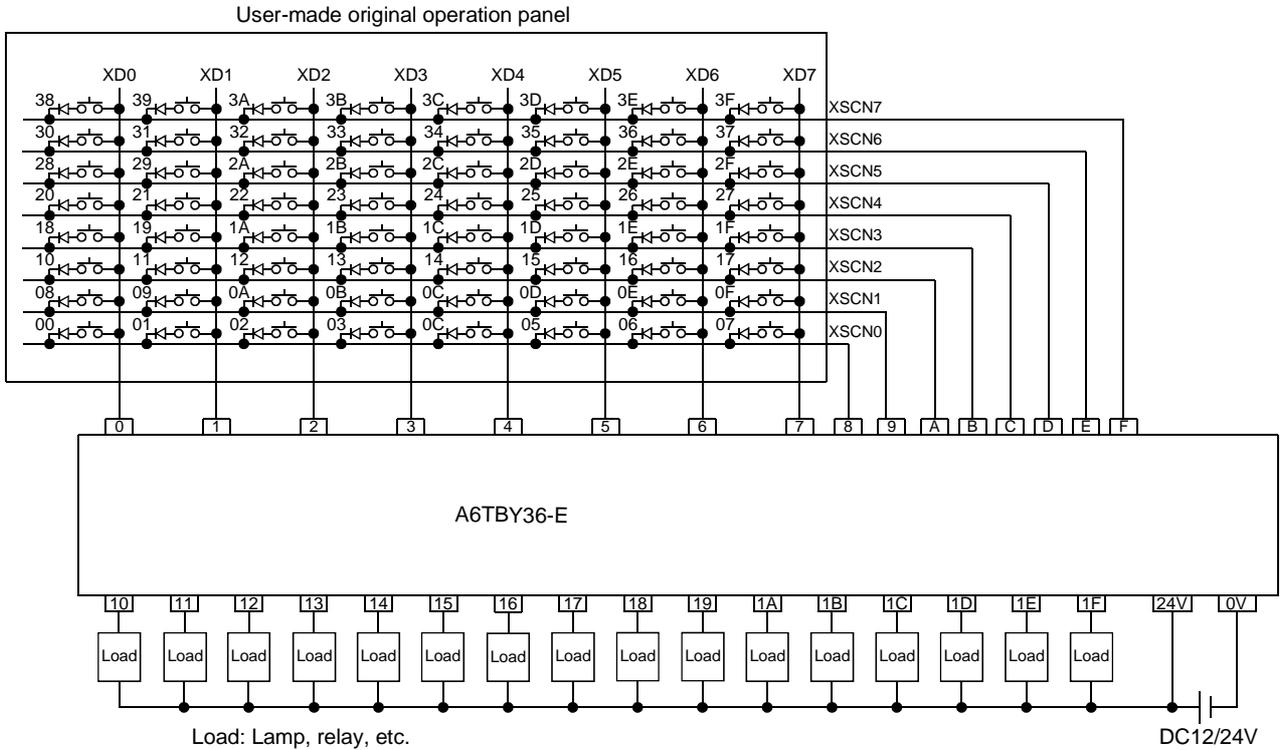


(b) For use of A6TBY54-E type connector terminal block conversion unit

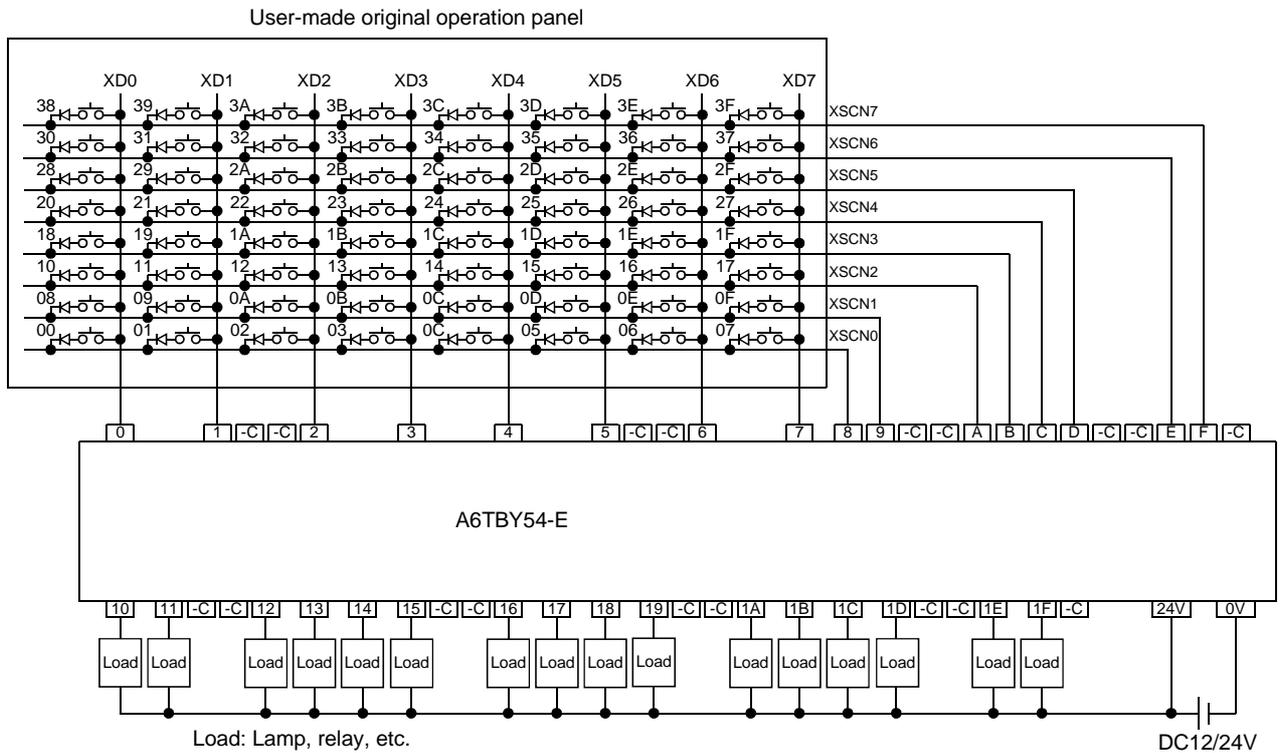


(2) Wiring diagram for use between connector terminal block conversion unit and user-made original operation panel

(a) For use of A6TBY36-E type connector terminal block conversion unit



(b) For use of A6TBY54-E type connector terminal block conversion unit



15.3.4 Recommended user-prepared articles and how to prepare them

(1) Type

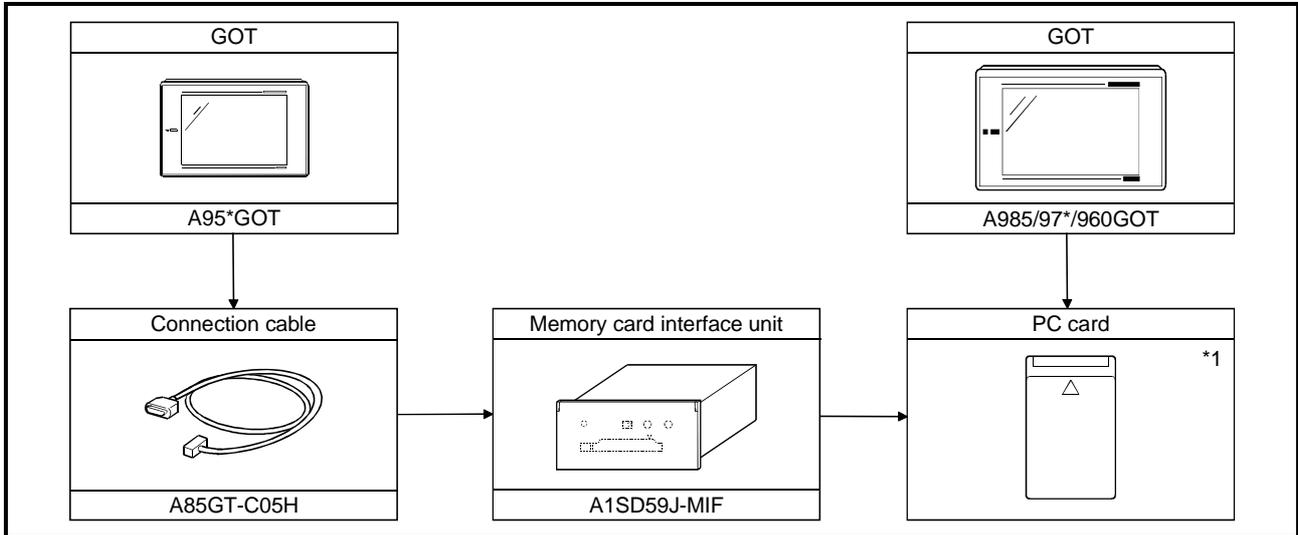
Maker	Type	Remarks
Kanaden Corp.	FP5-MD41-A	Operation panel (desktop type)
	FP5-MD41-B	Operation panel (enclosure-mounted type)

(2) Order and inquiry

Orders and inquiries for the operation panel should be made to your shop.

15.4 PC card

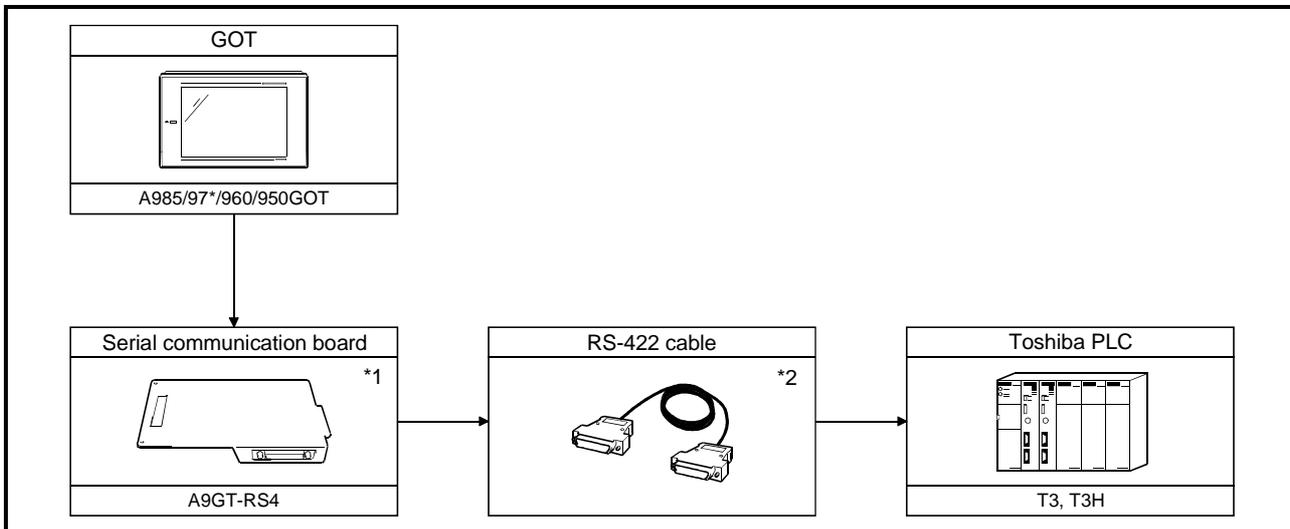
15.4.1 System configuration



*1 For details of available PC cards, refer to the SW4D5C-GOTR-PACKE(V) type operating manual.

Chapter 16 Toshiba PLC connection

16.1 System configuration



*1 Not needed when the A950GOT (with built-in serial communication interface) is used.

*2 The connection cable is to be prepared by the user.
For details of how to fabricate it, refer to Section 16.3.

16.2 Initial settings

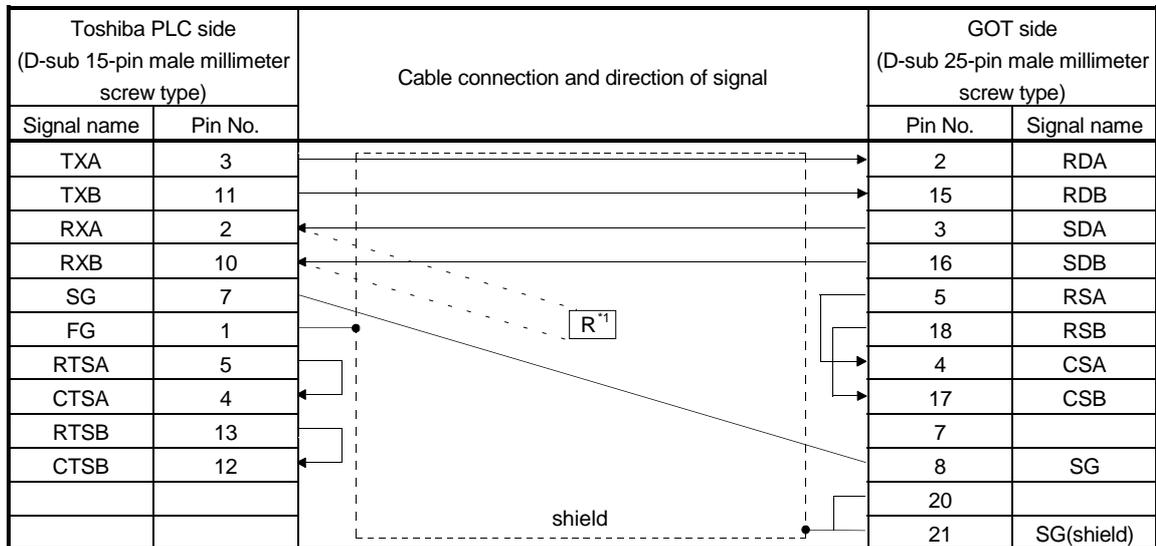
For monitoring by connection to the GOT, the following transmission parameters must be set to the Toshiba PLC using the peripheral software.

For details of how to make this setting, refer to the instruction manual of the Toshiba PLC.

Setting item	Setting
Station No.	1
Baudrate	19200bps
Parity	Even
Data length	7bit
Stop bit	2bit

16.3 Connection cable

(1) Connection diagram



*1 A 1/2W-120Ω resistor must be connected between RXA and RXB on the Toshiba PLC side.

(2) Connector and connector cover to be used

- Connector for GOT

Description	Model	Manufacturer
Connector with cover	17JE-23250-02(D8A6)	DDK

- Connector for host

Use a connector matching the host.

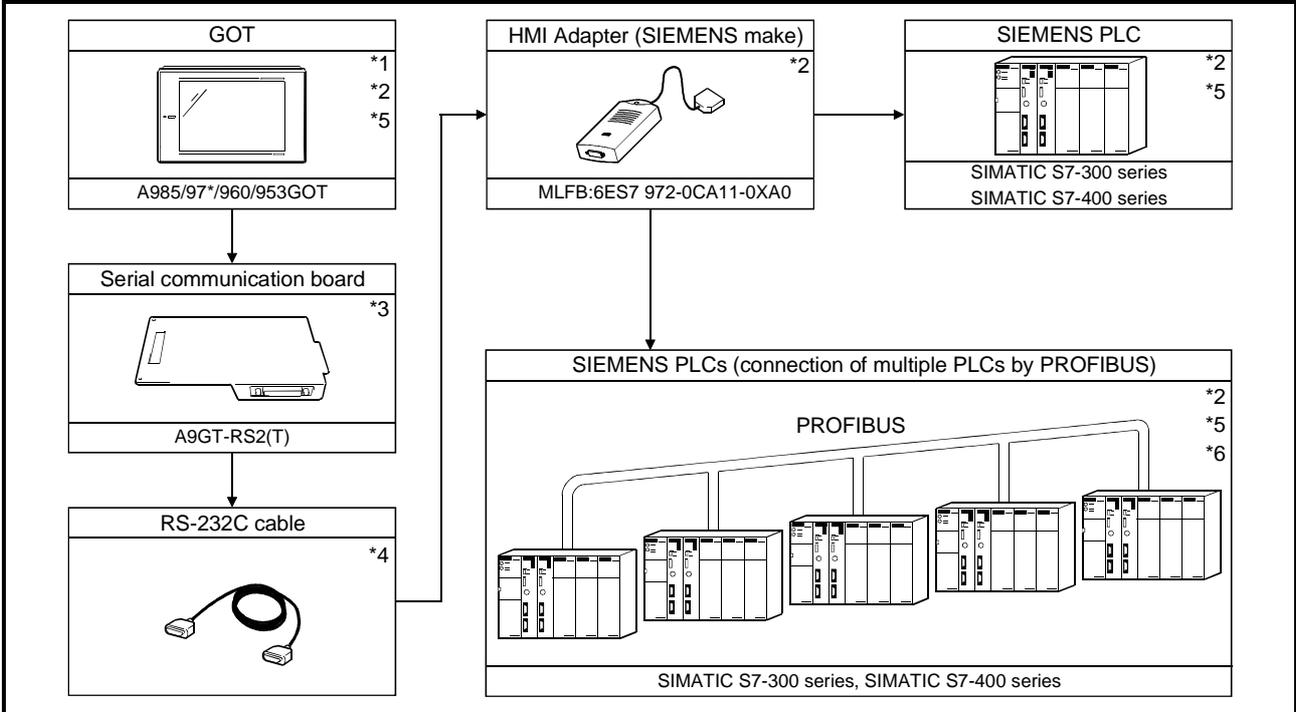
Description	Model	Manufacturer
Connector	DAC-15P-F0	Japan Aviation Electronics Industry, Ltd.
	DA-15-P-N	
Cover	DA-110963-2	
	GH-15LK	

(3) Precautions for preparation of connector

The cable to be fabricated should be within 1000m long.

Chapter 17 SIEMENS PLC connection

17.1 System configuration



- *1 Note that though the GOT can monitor the PLC CPU side error information with the alarm list (system alarm) function, it cannot monitor the error information when connected with the SIEMENS PLC(s).
For details of the alarm list (system alarm) function, refer to the help function of SW4D5C-GOTR-PACKE.
- *2 On the GOT, the PLC CPU to which the HMI adapter is connected must be set to "host".
Refer to Section 17.2 for details of the setting method.
- *3 Not needed for use of the A953GOT (with built-in serial communication interface).
- *4 Fabricate the RS-232C cable on the user side.
Refer to Section 17.3 for details of how to fabricate it.
- *5 To make a system start (switch on power), power on the GOT after powering on all PLC CPUs. If the PLC CPUs are powered on later, the GOT must be restarted.
- *6 If the other station PLC CPU (PLC CPU to which the HMI adapter is not connected) is powered off during system operation, the GOT stops monitoring.
If the PLC CPU is powered on again, the GOT does not resume monitoring.
To resume monitoring of the GOT, you need to restart the GOT.

17.2 Initial settings

When connecting the GOT and SIEMENS PLC, you need to make the following settings on Setup of the GOT's utility function.

- **Baud rate**
Set the transmission speed between GOT and SIEMENS PLC.
(Factory-set to 19200bps)
- **ADAPTER ADDRESS**
Specify the MPI address on PROFIBUS assigned to the HMI adapter connected to the GOT. (Factory-set to 1)
- **HOST (FF) ADDRESS**
Specify the MPI address on PROFIBUS assigned to the PLC CPU to which the HMI adapter is connected.
The specified PLC CPU is the "host" when monitor device setting is made on the drawing software.
For details of monitor device setting, refer to the help function of SW4D5C-GOTR-PACKE. (Factory-set to 2)

For details of the utility function, refer to the GOT-A900 Series Operating Manual (SW4D5C-GOTR-PACKE Compatible Extended • Option Function Manual).

BUZZER VOLUME	NONE	SHORT	LONG
OUTSIDE SPEAKER	OFF	ON	
SCREEN SAVE TIME	0 0 MIN.	(0:FREE)	
SCREEN SAVE LIGHT	OFF	ON	
LANGUAGE	日本語	ENGLISH	
Baud rate	19200	(↑ ↓ CHANGE)	
ADAPTER ADDRESS	0 1	(1~31)	
HOST(FF) ADDRESS	0 2	(1~31)	

Baud rate
Set the transmission speed between GOT and SIEMENS PLC.
(Factory-set to 19200bps)

ADAPTER ADDRESS
Specify the MPI address on PROFIBUS assigned to the HMI adapter connected to the GOT. (Factory-set to 1)

HOST(FF) ADDRESS
Specify the MPI address of the PLC CPU to which the HMI adapter is connected. (Factory-set to 2)

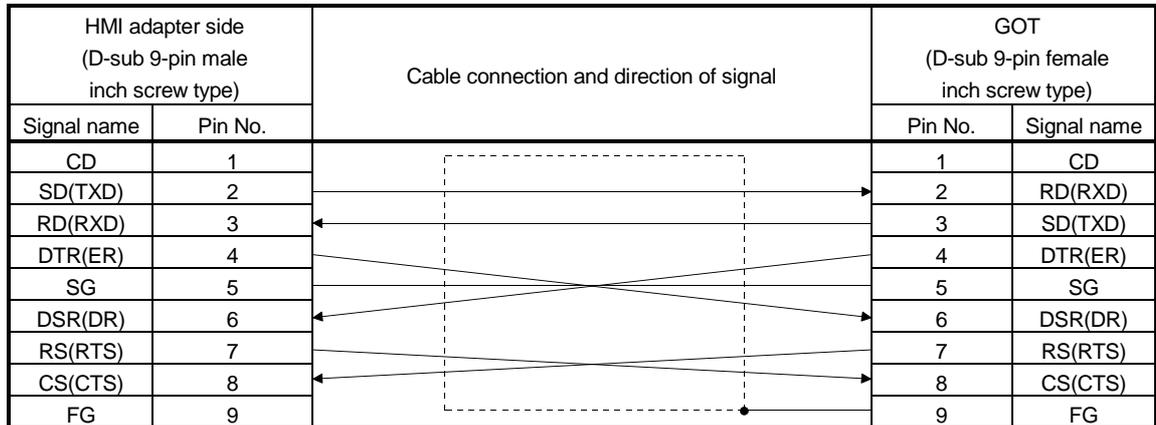
POINT

The utility function can be started by switching power on again after installing the system programs (system OS, communication driver, etc.) into the GOT. After the utility function has started, touch the [Setup] icon to display the setup screen, and make settings related to Yaskawa PLC connection.

17.3 Connection cable

The following connection diagram and connectors are used to connect the HMI adapter and GOT.

(1) Connection diagram



(2) Connector and connector cover

- Connector for GOT
Use connector matching the following connector that is used for the GOT.
9-pin D-sub (male) inch screw type
Manufactured by DDK
17LE-23090-27 (D3CC)
- Connector for HMI adapter side
Use the connector compatible with the HMI adapter.

(3) Precaution for cable fabrication

The maximum cable length changes with the specifications of the SIEMENS PLC used.
For details, refer to the instruction manual of the SIEMENS PLC.

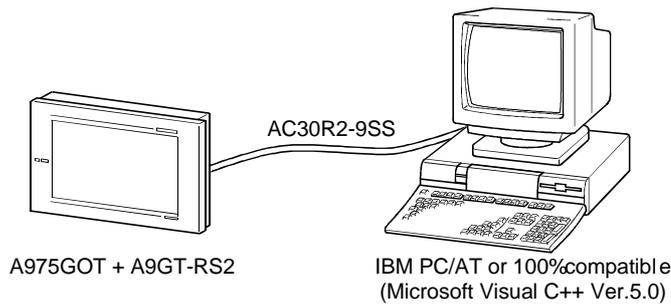
Appendices

Appendix 1 System configuration example for microcomputer connection

The following system configuration example is given for microcomputer connection.
Refer to this section when configuring a microcomputer connection system.

Appendix 1.1 System configuration

The system shown below was used in this system configuration example.



Appendix 1.2 GOT side communication setting and monitor screen setting details

(1) Communication setting

The communication setting of the GOT unit is indicated below.
Use the utility function (setup) to make communication setting for microcomputer connection.

Setting item	Setting
Microcomputer connection transmission speed	19200bps
Microcomputer connection protocol	Format 1

(2) Monitor screen setting details

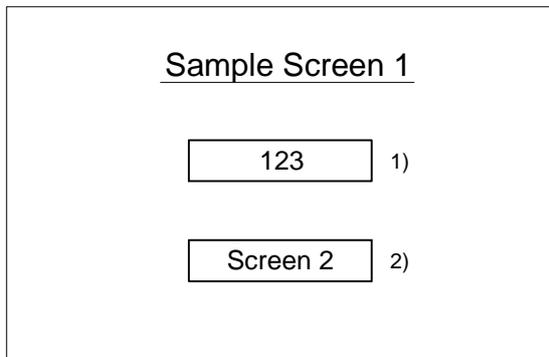
The monitor screen setting details are indicated below.

(a) Common setting

Screen switching device (base screen): D20

(b) Monitor screen images

Base screen 1



- 1) Numerical display function
Numerical display setting for monitoring the device value of D21.
The device value is incremented only while "Sample Screen 1" is being displayed.
- 2) Touch key 1
Key used to switch the screen to "Sample Screen 2".
Touching this key switches the base screen to "Sample Screen 2".

Base screen 2



- 3) Lamp indication function
Indicates the device status of D22.b0 with the lamp.
- 4) Touch key 2
Alternate key which changes the status of D22.b0.
- 5) Touch key 3
Key used to switch the screen to "Sample Screen 1".
Touching this key switches the base screen to "Sample Screen 1".

(c) Numerical display function

Number	Basic	Form		
	Device	Format	Size	Digits
1)	D21, unsigned BIN, 16 bit	Unsigned 16 bit	Any	4

(d) Touch key function

Number	Basic	Case	Action				
			Action	Switched to	Device	Data format	Operation type
2)	Any	Any	Base	Fixed value 2	—	—	—
			Word	—	D13	Signed BIN	Fixed value 01
4)	Any	Any	Bit	—	D22.b0	—	Bit ALT
5)	Any	Any	Base	Fixed value 1	—	—	—
			Word	—	D13	Signed BIN	Fixed value 255

(e) Lamp indication function

Number	Basic		Case (bit)	
	Device	Shape	At ON	At OFF
3)	D22.B0, bit	Basic figure	Any	Any

Appendix 1.3 Host side sample program

The host side sample program (C language) is contained in SW4D5C-GOTR-PACKE. It can be used by optionally selecting the sample program for microcomputer connection when installing the software package.

For the way of performing operation during installation (how to perform operation for optional selection), refer to the SW4D5C-GOTR-PACKE (V) Operating Manual.

Appendix 1.4 System operation overview

System operations will be explained in relation to the host side processing, GOT side display/processing and data communication packets.

Processing item	Host side processing details		Packet used for data communication	GOT side display/processing details
Initial processing	Port open processing is performed.		—	—
	"1" is written to screen switching device (D20).		Screen 1 switching batch write packet *1	Base screen 1 is displayed.
	Reply from GOT is received.		—	—
	Judgment is made as to whether reply from GOT is in error or not.		—	—
	Initial value is written to device (D21).		Numerical display batch write packet *2	"0" is shown in numerical display of base screen 1.
Reply/interrupt receipt from GOT	When reply to write to device (D21) is received from GOT.	Device (D21) current value acquisition request is given.	Numerical display batch read packet *3	Numerical display of base screen 1 is incremented. (As long as base screen 1 is displayed, host side repeats processing given on left.)
	When reply to read of device (D21) is received from GOT.	Next device value (D21) is created.	—	
		Sumcheck calculation of send packet is made.	—	
	When interrupt of switching request from base screen 1 to base screen 2 is received.	Device (D21) update request is given.	Numerical display batch write packet *2	
		Base screen status is set to base screen 2.	Interrupt receipt packet *6	Touch touch key 1 to switch to base screen 2. Host is notified by interrupt.
	When interrupt of switching request from base screen 2 to base screen 1 is received.	Base screen status is set to base screen 1.	Interrupt receipt packet *6	Touch touch key 3 to switch to base screen 1. Host is notified by interrupt.
Termination processing (Only when error reply is received)	Port close processing is performed.		—	—

*1 Send packet structure of screen 1 switching batch write packet is indicated.

Item	STX	WD	Address				points	Data				ETX	Sumcheck	
Stored value	0x02	0x57	0x44	0x30	0x30	0x32	0x30	0x30	0x30	0x30	0x31	0x03	0x38	0x32
Contents	—	"W" "D"		D20				1 point	1				—	"8" "2"

*2 Send packet structure of numerical display batch write packet is indicated.

Item	STX	WD	Address				points	Data				ETX	Sumcheck	
Stored value	0x02	0x57	0x44	0x30	0x30	0x32	0x30	0x30	0x30	0x31	—	—	—	—
Contents	—	"W" "D"		D21				1 point	—				—	—

*3 Send packet structure of numerical display batch read packet is indicated.

Item	STX	WD	Address				points	ETX	Sumcheck	
Stored value	0x02	0x52	0x44	0x30	0x30	0x32	0x30	0x30	0x32	
Contents	—	"R" "D"		D21				1 point	—	"B" "D"

*4 Receive packet structure of batch write reply packet is indicated.

Item	STX
Stored value	0x02
Contents	—

STX	STX
0x02	0x02
—	—

*5 Receive packet structure of batch read reply packet is indicated.

Item	STX	Data				STX	Sumcheck
Stored value	0x02	—	—	—	—	0x03	—
Contents	—	—				—	—

Item	STX
Stored value	0x15
Contents	—

*6 Receive packet structure of interrupt receive packet is indicated.

Item	Data
Stored value	—
Contents	Interrupt data

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WARRANTY

Please confirm the following product warranty details before starting use.

1. Gratis Warranty Term and Gratis Warranty Range

If any faults or defects (hereinafter "failure") found to be the responsibility of Mitsubishi occurs during use of the product within the gratis warranty term, the product shall be repaired at no cost via the dealer or Mitsubishi Service Company. Note that if repairs are required at a site overseas, on a detached island or remote place, expenses to dispatch an engineer shall be charged for.

[Gratis Warranty Term]

The gratis warranty term of the product shall be for one year after the date of purchase or delivery to a designated place.

Note that after manufacture and shipment from Mitsubishi, the maximum distribution period shall be six (6) months, and the longest gratis warranty term after manufacturing shall be eighteen (18) months. The gratis warranty term of repair parts shall not exceed the gratis warranty term before repairs.

[Gratis Warranty Range]

- (1) The range shall be limited to normal use within the usage state, usage methods and usage environment, etc., which follow the conditions and precautions, etc., given in the instruction manual, user's manual and caution labels on the product.
- (2) Even within the gratis warranty term, repairs shall be charged for in the following cases.
 1. failure occurring from inappropriate storage or handling, carelessness or negligence by the user. Failure caused by the user's hardware or software design.
 2. Failure caused by unapproved modifications, etc., to the product by the user.
 3. When the Mitsubishi product is assembled into a user's device, failure that could have been avoided if functions or structures, judged as necessary in the legal safety measures the user's device is subject to or as necessary by industry standards, had been provided.
 4. Failure that could have been avoided if consumable parts (battery, backlight, fuse, etc.) designated in the instruction manual had been correctly serviced or replaced.
 5. Failure caused by external irresistible forces such as fires or abnormal voltages, and failure caused by force majeure such as earthquakes, lightning, wind and water damage.
 6. Failure caused by reasons unpredictable by scientific technology standards at time of shipment from Mitsubishi.
 7. Any other failure found to not be the responsibility of Mitsubishi or the user.

2. Onerous repair term after discontinuation of production

- (1) Mitsubishi shall accept onerous product repairs for seven (7) years after production of the product is discontinued. Discontinuation of production shall be notified with Mitsubishi Technical Bulletins, etc.
- (2) Product supply (including repair parts) is not possible after production is discontinued.

3. Overseas service

Overseas, repairs shall be accepted by Mitsubishi's local overseas FA Center. Note that the repair conditions at each FA Center may differ.

4. Exclusion of chance loss and secondary loss from warranty liability

Regardless of the gratis warranty term, Mitsubishi shall not be liable for compensation to damages caused by any cause found not to be the responsibility of Mitsubishi, chance losses, lost profits incurred to the user by failures in Mitsubishi products, damages and secondary damages caused from special reasons regardless of Mitsubishi's expectations, compensation for accidents, and compensation for damages to products other than Mitsubishi products and other duties.

5. Changes in product specifications

The specifications given in the catalogs, manuals or technical documents are subject to change without prior notice.

6. Product application

- (1) In using the Mitsubishi MELSEC programmable logic controller, the usage conditions shall be that the application will not lead to a major accident even if any problem or fault should occur in the programmable logic controller device, and that backup and fail-safe functions are systematically provided outside of the device for any problem or fault.
- (2) The Mitsubishi general-purpose programmable logic controller has been designed and manufactured for applications in general industries, etc. Thus, applications in which the public could be affected such as in nuclear power plants and other power plants operated by respective power companies, and applications in which a special quality assurance system is required, such as for each Japan Railways company or the Department of Defense shall be excluded from the programmable logic controller applications.

Note that even with these applications, if the user approves that the application is to be limited and a special quality is not required, application shall be possible.

When considering use in aircraft, medical applications, railways, incineration and fuel devices, manned transport devices, equipment for recreation and amusement, and safety devices, in which human life or assets could be greatly affected and for which a particularly high reliability is required in terms of safety and control system, please consult with Mitsubishi and discuss the required specifications.

GOT-A900 Series User's Manual

(SW4D5C-GOTR-PACKE compatible Connection System Manual)

MODEL	SW4-GOTR-U(CON)-E
MODEL CODE	13JR11
SH(NA)-080070-B(0005)MEE	

 **MITSUBISHI ELECTRIC CORPORATION**

HEAD OFFICE : MITSUBISHI DENKI BLDG MARUNOUCHI TOKYO 100-8310 TELEX : J24532 CABLE MELCO TOKYO
NAGOYA WORKS : 1-14, YADA-MINAMI 5, HIGASHI-KU, NAGOYA, JAPAN

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